

MSSM without flavor violation
Superpotential, Rotations and Interactions for eigenstates 'EWSB'
including Renormalization Group Equations

SARAH 4.6.0

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References: [arXiv: 1309.7223](#) , [Comput.Phys.Commun.184:1792-1809,2011 \(1207.0906\)](#) , [Comput.Phys.Commun.182:833,2011 \(1002.0840\)](#) , [Comput.Phys.Commun.181:1077-1086,2010 \(0909.2863\)](#) , [arXiv: 0806.0538](#)

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1 Superfields

1.1 Vector Superfields

SF	Spin $\frac{1}{2}$	Spin 1	$SU(N)$	Coupling	Name
\hat{B}	$\lambda_{\hat{B}}$	B	$U(1)$	g_1	hypercharge
\hat{W}	$\lambda_{\hat{W}}$	W	$SU(2)$	g_2	left
\hat{g}	$\lambda_{\hat{g}}$	g	$SU(3)$	g_3	color

1.2 Chiral Superfields

SF	Spin 0	Spin $\frac{1}{2}$	Generations	$(U(1) \otimes SU(2) \otimes SU(3))$
\hat{q}	\tilde{q}	q	3	$(\frac{1}{6}, \mathbf{2}, \mathbf{3})$
\hat{l}	\tilde{l}	l	3	$(-\frac{1}{2}, \mathbf{2}, \mathbf{1})$
\hat{H}_d	H_d	\tilde{H}_d	1	$(-\frac{1}{2}, \mathbf{2}, \mathbf{1})$
\hat{H}_u	H_u	\tilde{H}_u	1	$(\frac{1}{2}, \mathbf{2}, \mathbf{1})$
\hat{d}	\tilde{d}_R^*	d_R^*	3	$(\frac{1}{3}, \mathbf{1}, \bar{\mathbf{3}})$
\hat{u}	\tilde{u}_R^*	u_R^*	3	$(-\frac{2}{3}, \mathbf{1}, \bar{\mathbf{3}})$
\hat{e}	\tilde{e}_R^*	e_R^*	3	$(1, \mathbf{1}, \mathbf{1})$

2 Superpotential and Lagrangian

2.1 Superpotential

$$W = \mu \hat{H}_u \hat{H}_d - Y_d \hat{d} \hat{q} \hat{H}_d - Y_e \hat{e} \hat{l} \hat{H}_d + Y_u \hat{u} \hat{q} \hat{H}_u \quad (1)$$

2.2 Softbreaking terms

$$\begin{aligned}
-L_{SB,W} = & -H_d^0 H_u^0 B_\mu + H_d^- H_u^+ B_\mu + H_d^0 \tilde{d}_{R,i\alpha}^* \delta_{\alpha\beta} \delta_{ij} \tilde{d}_{L,j\beta} T_{d,ij} - H_d^- \tilde{d}_{R,i\alpha}^* \delta_{\alpha\beta} \delta_{ij} \tilde{u}_{L,j\beta} T_{d,ij} \\
& + H_d^0 \tilde{e}_{R,i}^* \delta_{ij} \tilde{e}_{L,j} T_{e,ij} - H_d^- \tilde{e}_{R,i}^* \delta_{ij} \tilde{\nu}_j T_{e,ij} - H_u^+ \tilde{u}_{R,i\alpha}^* \delta_{\alpha\beta} \delta_{ij} \tilde{d}_{L,j\beta} T_{u,ij} \\
& + H_u^0 \tilde{u}_{R,i\alpha}^* \delta_{\alpha\beta} \delta_{ij} \tilde{u}_{L,j\beta} T_{u,ij} + \text{h.c.} \quad (2)
\end{aligned}$$

$$\begin{aligned}
-L_{SB,\phi} = & + m_{H_d}^2 |H_d^0|^2 + m_{H_d}^2 |H_d^-|^2 + m_{H_u}^2 |H_u^0|^2 + m_{H_u}^2 |H_u^+|^2 + \tilde{d}_{L,i\alpha}^* \delta_{\alpha\beta} \delta_{ij} m_{q,ij}^2 \tilde{d}_{L,j\beta} \\
& + \tilde{d}_{R,i\alpha}^* \delta_{\alpha\beta} \delta_{ij} m_{d,ij}^2 \tilde{d}_{R,j\beta} + \tilde{e}_{L,i}^* \delta_{ij} m_{l,ij}^2 \tilde{e}_{L,j} + \tilde{e}_{R,i}^* \delta_{ij} m_{e,ij}^2 \tilde{e}_{R,j} + \tilde{u}_{L,i\alpha}^* \delta_{\alpha\beta} \delta_{ij} m_{q,ij}^2 \tilde{u}_{L,j\beta} \\
& + \tilde{u}_{R,i\alpha}^* \delta_{\alpha\beta} \delta_{ij} m_{u,ij}^2 \tilde{u}_{R,j\beta} + \tilde{\nu}_i^* \delta_{ij} m_{l,ij}^2 \tilde{\nu}_j \quad (3)
\end{aligned}$$

$$-L_{SB,\lambda} = \frac{1}{2} \left(\lambda_B^2 M_1 \delta_{ij} + M_2 \delta_{ij} \lambda_{\hat{W},i} \lambda_{\hat{W},j} + M_3 \delta_{ij} \lambda_{\hat{g},\alpha} \lambda_{\hat{g},\beta} + \text{h.c.} \right) \quad (4)$$

2.3 Gauge fixing terms

2.3.1 Gauge fixing terms for eigenstates 'GaugeES'

$$L_{GF} = -\frac{1}{2}|\partial_\mu B|^2\xi_B^{-1} - \frac{1}{2}|\partial_\mu g|^2\xi_g^{-1} - \frac{1}{2}|\partial_\mu W|^2\xi_W^{-1} \quad (5)$$

2.3.2 Gauge fixing terms for eigenstates 'EWSB'

$$L_{GF} = -\frac{1}{2}|\partial_\mu g|^2\xi_g^{-1} - \frac{1}{2}|\partial_\mu \gamma|^2\xi_\gamma^{-1} - \frac{i}{2}g_2\left(H_d^- v_d - v_u H_u^{+,*}\right)\xi_{W^-} + \partial_\mu W^-|^2\xi_{W^-}^{-1} \\ - \frac{1}{2}\left|\frac{1}{2}\left(2\partial_\mu Z + \left(\sigma_d v_d - \sigma_u v_u\right)\xi_Z\left(g_1 \sin \Theta_W + g_2 \cos \Theta_W\right)\right)\right|^2\xi_Z^{-1} \quad (6)$$

2.4 Fields integrated out

None

3 Renormalization Group Equations

3.1 Anomalous Dimensions

$$\gamma_{\hat{q}}^{(1)} = -\frac{1}{30}\left(45g_2^2 + 80g_3^2 + g_1^2\right)\mathbf{1} + Y_d^\dagger Y_d + Y_u^\dagger Y_u \quad (7)$$

$$\gamma_{\hat{q}}^{(2)} = +\left(8g_2^2g_3^2 + \frac{15}{4}g_2^4 + \frac{1}{90}g_1^2\left(16g_3^2 + 9g_2^2\right) + \frac{199}{900}g_1^4 - \frac{8}{9}g_3^4\right)\mathbf{1} + \frac{4}{5}g_1^2Y_u^\dagger Y_u - 2Y_d^\dagger Y_d Y_d^\dagger Y_d \\ - 2Y_u^\dagger Y_u Y_u^\dagger Y_u + Y_d^\dagger Y_d\left(-3\text{Tr}\left(Y_d Y_d^\dagger\right) + \frac{2}{5}g_1^2 - \text{Tr}\left(Y_e Y_e^\dagger\right)\right) - 3Y_u^\dagger Y_u \text{Tr}\left(Y_u Y_u^\dagger\right) \quad (8)$$

$$\gamma_{\hat{i}}^{(1)} = -\frac{3}{10}\left(5g_2^2 + g_1^2\right)\mathbf{1} + Y_e^\dagger Y_e \quad (9)$$

$$\gamma_{\hat{i}}^{(2)} = -2Y_e^\dagger Y_e Y_e^\dagger Y_e + \frac{3}{100}\left(125g_2^4 + 30g_1^2g_2^2 + 69g_1^4\right)\mathbf{1} + Y_e^\dagger Y_e\left(-3\text{Tr}\left(Y_d Y_d^\dagger\right) + \frac{6}{5}g_1^2 - \text{Tr}\left(Y_e Y_e^\dagger\right)\right) \quad (10)$$

$$\gamma_{\hat{H}_d}^{(1)} = 3\text{Tr}\left(Y_d Y_d^\dagger\right) - \frac{3}{10}\left(5g_2^2 + g_1^2\right) + \text{Tr}\left(Y_e Y_e^\dagger\right) \quad (11)$$

$$\gamma_{\hat{H}_d}^{(2)} = +\frac{207}{100}g_1^4 + \frac{9}{10}g_1^2g_2^2 + \frac{15}{4}g_2^4 - \frac{2}{5}\left(-40g_3^2 + g_1^2\right)\text{Tr}\left(Y_d Y_d^\dagger\right) + \frac{6}{5}g_1^2\text{Tr}\left(Y_e Y_e^\dagger\right) - 9\text{Tr}\left(Y_d Y_d^\dagger Y_d Y_d^\dagger\right) \\ - 3\text{Tr}\left(Y_d Y_u^\dagger Y_u Y_d^\dagger\right) - 3\text{Tr}\left(Y_e Y_e^\dagger Y_e Y_e^\dagger\right) \quad (12)$$

$$\gamma_{\hat{H}_u}^{(1)} = -\frac{3}{10}\left(-10\text{Tr}\left(Y_u Y_u^\dagger\right) + 5g_2^2 + g_1^2\right) \quad (13)$$

$$\gamma_{\hat{H}_u}^{(2)} = -3\text{Tr}\left(Y_d Y_u^\dagger Y_u Y_d^\dagger\right) - 9\text{Tr}\left(Y_u Y_u^\dagger Y_u Y_u^\dagger\right) + \frac{15}{4}g_2^4 + \frac{207}{100}g_1^4 + \frac{4}{5}\left(20g_3^2 + g_1^2\right)\text{Tr}\left(Y_u Y_u^\dagger\right) + \frac{9}{10}g_1^2g_2^2 \quad (14)$$

$$\gamma_{\hat{d}}^{(1)} = 2Y_d^* Y_d^T - \frac{2}{15}\left(20g_3^2 + g_1^2\right)\mathbf{1} \quad (15)$$

$$\gamma_{\hat{d}}^{(2)} = +\frac{2}{225}\left(-100g_3^4 + 101g_1^4 + 80g_1^2g_3^2\right)\mathbf{1} - 2\left(Y_d^* Y_d^T Y_d^* Y_d^T + Y_d^* Y_u^T Y_u^* Y_d^T\right)$$

$$+ Y_d^* Y_d^T \left(-2\text{Tr}(Y_e Y_e^\dagger) + 6g_2^2 - 6\text{Tr}(Y_d Y_d^\dagger) + \frac{2}{5}g_1^2 \right) \quad (16)$$

$$\gamma_{\hat{u}}^{(1)} = 2Y_u^* Y_u^T - \frac{8}{15} \left(5g_3^2 + g_1^2 \right) \mathbf{1} \quad (17)$$

$$\begin{aligned} \gamma_{\hat{u}}^{(2)} = & + \frac{8}{225} \left(107g_1^4 - 25g_3^4 + 80g_1^2 g_3^2 \right) \mathbf{1} - 2 \left(Y_u^* Y_d^T Y_d^* Y_u^T + Y_u^* Y_u^T Y_u^* Y_u^T \right) \\ & + Y_u^* Y_u^T \left(6g_2^2 - 6\text{Tr}(Y_u Y_u^\dagger) - \frac{2}{5}g_1^2 \right) \end{aligned} \quad (18)$$

$$\gamma_{\hat{e}}^{(1)} = 2Y_e^* Y_e^T - \frac{6}{5}g_1^2 \mathbf{1} \quad (19)$$

$$\gamma_{\hat{e}}^{(2)} = -2Y_e^* Y_e^T Y_e^* Y_e^T + \frac{234}{25}g_1^4 \mathbf{1} + Y_e^* Y_e^T \left(-2\text{Tr}(Y_e Y_e^\dagger) + 6g_2^2 - 6\text{Tr}(Y_d Y_d^\dagger) - \frac{6}{5}g_1^2 \right) \quad (20)$$

3.2 Gauge Couplings

$$\beta_{g_1}^{(1)} = \frac{33}{5}g_1^3 \quad (21)$$

$$\beta_{g_1}^{(2)} = \frac{1}{25}g_1^3 \left(-130\text{Tr}(Y_u Y_u^\dagger) + 135g_2^2 + 199g_1^2 + 440g_3^2 - 70\text{Tr}(Y_d Y_d^\dagger) - 90\text{Tr}(Y_e Y_e^\dagger) \right) \quad (22)$$

$$\beta_{g_2}^{(1)} = g_2^3 \quad (23)$$

$$\beta_{g_2}^{(2)} = \frac{1}{5}g_2^3 \left(-10\text{Tr}(Y_e Y_e^\dagger) + 120g_3^2 + 125g_2^2 - 30\text{Tr}(Y_d Y_d^\dagger) - 30\text{Tr}(Y_u Y_u^\dagger) + 9g_1^2 \right) \quad (24)$$

$$\beta_{g_3}^{(1)} = -3g_3^3 \quad (25)$$

$$\beta_{g_3}^{(2)} = \frac{1}{5}g_3^3 \left(11g_1^2 - 20\text{Tr}(Y_d Y_d^\dagger) - 20\text{Tr}(Y_u Y_u^\dagger) + 45g_2^2 + 70g_3^2 \right) \quad (26)$$

3.3 Gaugino Mass Parameters

$$\beta_{M_1}^{(1)} = \frac{66}{5}g_1^2 M_1 \quad (27)$$

$$\begin{aligned} \beta_{M_1}^{(2)} = & \frac{2}{25}g_1^2 \left(398g_1^2 M_1 + 135g_2^2 M_1 + 440g_3^2 M_1 + 440g_3^2 M_3 + 135g_2^2 M_2 - 70M_1 \text{Tr}(Y_d Y_d^\dagger) - 90M_1 \text{Tr}(Y_e Y_e^\dagger) \right. \\ & \left. - 130M_1 \text{Tr}(Y_u Y_u^\dagger) + 70\text{Tr}(Y_d^\dagger T_d) + 90\text{Tr}(Y_e^\dagger T_e) + 130\text{Tr}(Y_u^\dagger T_u) \right) \end{aligned} \quad (28)$$

$$\beta_{M_2}^{(1)} = 2g_2^2 M_2 \quad (29)$$

$$\begin{aligned} \beta_{M_2}^{(2)} = & \frac{2}{5}g_2^2 \left(9g_1^2 M_1 + 120g_3^2 M_3 + 9g_1^2 M_2 + 250g_2^2 M_2 + 120g_3^2 M_2 - 30M_2 \text{Tr}(Y_d Y_d^\dagger) - 10M_2 \text{Tr}(Y_e Y_e^\dagger) \right. \\ & \left. - 30M_2 \text{Tr}(Y_u Y_u^\dagger) + 30\text{Tr}(Y_d^\dagger T_d) + 10\text{Tr}(Y_e^\dagger T_e) + 30\text{Tr}(Y_u^\dagger T_u) \right) \end{aligned} \quad (30)$$

$$\beta_{M_3}^{(1)} = -6g_3^2 M_3 \quad (31)$$

$$\beta_{M_3}^{(2)} = \frac{2}{5}g_3^2 \left(11g_1^2 M_1 + 11g_1^2 M_3 + 45g_2^2 M_3 + 140g_3^2 M_3 + 45g_2^2 M_2 - 20M_3 \text{Tr}(Y_d Y_d^\dagger) - 20M_3 \text{Tr}(Y_u Y_u^\dagger) \right)$$

$$+ 20\text{Tr}(Y_d^\dagger T_d) + 20\text{Tr}(Y_u^\dagger T_u)) \quad (32)$$

3.4 Trilinear Superpotential Parameters

$$\beta_{Y_d}^{(1)} = 3Y_d Y_d^\dagger Y_d + Y_d \left(-3g_2^2 + 3\text{Tr}(Y_d Y_d^\dagger) - \frac{16}{3}g_3^2 - \frac{7}{15}g_1^2 + \text{Tr}(Y_e Y_e^\dagger) \right) + Y_d Y_u^\dagger Y_u \quad (33)$$

$$\begin{aligned} \beta_{Y_d}^{(2)} = & + \frac{4}{5}g_1^2 Y_d Y_u^\dagger Y_u - 4Y_d Y_d^\dagger Y_d Y_d^\dagger Y_d - 2Y_d Y_u^\dagger Y_u Y_d^\dagger Y_d - 2Y_d Y_u^\dagger Y_u Y_u^\dagger Y_u \\ & + Y_d Y_d^\dagger Y_d \left(-3\text{Tr}(Y_e Y_e^\dagger) + 6g_2^2 - 9\text{Tr}(Y_d Y_d^\dagger) + \frac{4}{5}g_1^2 \right) - 3Y_d Y_u^\dagger Y_u \text{Tr}(Y_u Y_u^\dagger) \\ & + Y_d \left(\frac{287}{90}g_1^4 + g_1^2 g_2^2 + \frac{15}{2}g_2^4 + \frac{8}{9}g_1^2 g_3^2 + 8g_2^2 g_3^2 - \frac{16}{9}g_3^4 - \frac{2}{5}(-40g_3^2 + g_1^2) \text{Tr}(Y_d Y_d^\dagger) \right. \\ & \left. + \frac{6}{5}g_1^2 \text{Tr}(Y_e Y_e^\dagger) - 9\text{Tr}(Y_d Y_d^\dagger Y_d Y_d^\dagger) - 3\text{Tr}(Y_d Y_u^\dagger Y_u Y_d^\dagger) - 3\text{Tr}(Y_e Y_e^\dagger Y_e Y_e^\dagger) \right) \end{aligned} \quad (34)$$

$$\beta_{Y_e}^{(1)} = 3Y_e Y_e^\dagger Y_e + Y_e \left(-3g_2^2 + 3\text{Tr}(Y_d Y_d^\dagger) - \frac{9}{5}g_1^2 + \text{Tr}(Y_e Y_e^\dagger) \right) \quad (35)$$

$$\begin{aligned} \beta_{Y_e}^{(2)} = & -4Y_e Y_e^\dagger Y_e Y_e^\dagger Y_e + Y_e Y_e^\dagger Y_e \left(-3\text{Tr}(Y_e Y_e^\dagger) + 6g_2^2 - 9\text{Tr}(Y_d Y_d^\dagger) \right) \\ & + \frac{1}{10}Y_e \left(-4(-40g_3^2 + g_1^2) \text{Tr}(Y_d Y_d^\dagger) \right. \\ & \left. + 3(45g_1^4 + 6g_1^2 g_2^2 + 25g_2^4 + 4g_1^2 \text{Tr}(Y_e Y_e^\dagger) - 30\text{Tr}(Y_d Y_d^\dagger Y_d Y_d^\dagger) - 10\text{Tr}(Y_d Y_u^\dagger Y_u Y_d^\dagger) \right. \\ & \left. - 10\text{Tr}(Y_e Y_e^\dagger Y_e Y_e^\dagger) \right) \end{aligned} \quad (36)$$

$$\beta_{Y_u}^{(1)} = 3Y_u Y_u^\dagger Y_u - \frac{1}{15}Y_u \left(13g_1^2 + 45g_2^2 - 45\text{Tr}(Y_u Y_u^\dagger) + 80g_3^2 \right) + Y_u Y_d^\dagger Y_d \quad (37)$$

$$\begin{aligned} \beta_{Y_u}^{(2)} = & + \frac{2}{5}g_1^2 Y_u Y_u^\dagger Y_u + 6g_2^2 Y_u Y_u^\dagger Y_u - 2Y_u Y_d^\dagger Y_d Y_d^\dagger Y_d - 2Y_u Y_d^\dagger Y_d Y_u^\dagger Y_u \\ & - 4Y_u Y_u^\dagger Y_u Y_u^\dagger Y_u + Y_u Y_d^\dagger Y_d \left(-3\text{Tr}(Y_d Y_d^\dagger) + \frac{2}{5}g_1^2 - \text{Tr}(Y_e Y_e^\dagger) \right) - 9Y_u Y_u^\dagger Y_u \text{Tr}(Y_u Y_u^\dagger) \\ & + Y_u \left(\frac{2743}{450}g_1^4 + g_1^2 g_2^2 + \frac{15}{2}g_2^4 + \frac{136}{45}g_1^2 g_3^2 + 8g_2^2 g_3^2 - \frac{16}{9}g_3^4 + \frac{4}{5}(20g_3^2 + g_1^2) \text{Tr}(Y_u Y_u^\dagger) \right. \\ & \left. - 3\text{Tr}(Y_d Y_u^\dagger Y_u Y_d^\dagger) - 9\text{Tr}(Y_u Y_u^\dagger Y_u Y_u^\dagger) \right) \end{aligned} \quad (38)$$

3.5 Bilinear Superpotential Parameters

$$\beta_\mu^{(1)} = 3\mu \text{Tr}(Y_d Y_d^\dagger) - \frac{3}{5}\mu \left(5g_2^2 - 5\text{Tr}(Y_u Y_u^\dagger) + g_1^2 \right) + \mu \text{Tr}(Y_e Y_e^\dagger) \quad (39)$$

$$\begin{aligned} \beta_\mu^{(2)} = & \frac{1}{50}\mu \left(207g_1^4 + 90g_1^2 g_2^2 + 375g_2^4 - 20(-40g_3^2 + g_1^2) \text{Tr}(Y_d Y_d^\dagger) + 60g_1^2 \text{Tr}(Y_e Y_e^\dagger) + 40g_1^2 \text{Tr}(Y_u Y_u^\dagger) \right. \\ & \left. + 800g_3^2 \text{Tr}(Y_u Y_u^\dagger) - 450\text{Tr}(Y_d Y_d^\dagger Y_d Y_d^\dagger) - 300\text{Tr}(Y_d Y_u^\dagger Y_u Y_d^\dagger) - 150\text{Tr}(Y_e Y_e^\dagger Y_e Y_e^\dagger) \right) \end{aligned}$$

$$-450\text{Tr}\left(Y_u Y_u^\dagger Y_u Y_u^\dagger\right) \quad (40)$$

3.6 Trilinear Soft-Breaking Parameters

$$\begin{aligned} \beta_{T_d}^{(1)} = & +4Y_d Y_d^\dagger T_d + 2Y_d Y_u^\dagger T_u + 5T_d Y_d^\dagger Y_d + T_d Y_u^\dagger Y_u - \frac{7}{15}g_1^2 T_d - 3g_2^2 T_d - \frac{16}{3}g_3^2 T_d \\ & + 3T_d \text{Tr}\left(Y_d Y_d^\dagger\right) + T_d \text{Tr}\left(Y_e Y_e^\dagger\right) + Y_d \left(2\text{Tr}\left(Y_e^\dagger T_e\right) + 6g_2^2 M_2 + 6\text{Tr}\left(Y_d^\dagger T_d\right) + \frac{14}{15}g_1^2 M_1 + \frac{32}{3}g_3^2 M_3\right) \end{aligned} \quad (41)$$

$$\begin{aligned} \beta_{T_d}^{(2)} = & +\frac{6}{5}g_1^2 Y_d Y_d^\dagger T_d + 6g_2^2 Y_d Y_d^\dagger T_d - \frac{8}{5}g_1^2 M_1 Y_d Y_u^\dagger Y_u + \frac{8}{5}g_1^2 Y_d Y_u^\dagger T_u \\ & + \frac{6}{5}g_1^2 T_d Y_d^\dagger Y_d + 12g_2^2 T_d Y_d^\dagger Y_d + \frac{4}{5}g_1^2 T_d Y_u^\dagger Y_u - 6Y_d Y_d^\dagger Y_d Y_d^\dagger T_d \\ & - 8Y_d Y_d^\dagger T_d Y_d^\dagger Y_d - 2Y_d Y_u^\dagger Y_u Y_d^\dagger T_d - 4Y_d Y_u^\dagger Y_u Y_u^\dagger T_u - 4Y_d Y_u^\dagger T_u Y_d^\dagger Y_d \\ & - 4Y_d Y_u^\dagger T_u Y_u^\dagger Y_u - 6T_d Y_d^\dagger Y_d Y_d^\dagger Y_d - 4T_d Y_u^\dagger Y_u Y_d^\dagger Y_d - 2T_d Y_u^\dagger Y_u Y_u^\dagger Y_u \\ & + \frac{287}{90}g_1^4 T_d + g_1^2 g_2^2 T_d + \frac{15}{2}g_2^4 T_d + \frac{8}{9}g_1^2 g_3^2 T_d + 8g_2^2 g_3^2 T_d - \frac{16}{9}g_3^4 T_d \\ & - 12Y_d Y_d^\dagger T_d \text{Tr}\left(Y_d Y_d^\dagger\right) - 15T_d Y_d^\dagger Y_d \text{Tr}\left(Y_d Y_d^\dagger\right) - \frac{2}{5}g_1^2 T_d \text{Tr}\left(Y_d Y_d^\dagger\right) \\ & + 16g_3^2 T_d \text{Tr}\left(Y_d Y_d^\dagger\right) - 4Y_d Y_d^\dagger T_d \text{Tr}\left(Y_e Y_e^\dagger\right) - 5T_d Y_d^\dagger Y_d \text{Tr}\left(Y_e Y_e^\dagger\right) \\ & + \frac{6}{5}g_1^2 T_d \text{Tr}\left(Y_e Y_e^\dagger\right) - 6Y_d Y_u^\dagger T_u \text{Tr}\left(Y_u Y_u^\dagger\right) - 3T_d Y_u^\dagger Y_u \text{Tr}\left(Y_u Y_u^\dagger\right) \\ & - \frac{2}{5}Y_d Y_d^\dagger Y_d \left(15\text{Tr}\left(Y_e^\dagger T_e\right) + 30g_2^2 M_2 + 45\text{Tr}\left(Y_d^\dagger T_d\right) + 4g_1^2 M_1\right) - 6Y_d Y_u^\dagger Y_u \text{Tr}\left(Y_u^\dagger T_u\right) \\ & - 9T_d \text{Tr}\left(Y_d Y_d^\dagger Y_d Y_d^\dagger\right) - 3T_d \text{Tr}\left(Y_d Y_u^\dagger Y_u Y_d^\dagger\right) - 3T_d \text{Tr}\left(Y_e Y_e^\dagger Y_e Y_e^\dagger\right) \\ & - \frac{2}{45}Y_d \left(287g_1^4 M_1 + 45g_1^2 g_2^2 M_1 + 40g_1^2 g_3^2 M_1 + 40g_1^2 g_3^2 M_3 + 360g_2^2 g_3^2 M_3 - 160g_3^4 M_3\right. \\ & + 45g_1^2 g_2^2 M_2 + 675g_2^4 M_2 + 360g_2^2 g_3^2 M_2 - 18\left(-40g_3^2 M_3 + g_1^2 M_1\right) \text{Tr}\left(Y_d Y_d^\dagger\right) \\ & + 54g_1^2 M_1 \text{Tr}\left(Y_e Y_e^\dagger\right) + 18g_1^2 \text{Tr}\left(Y_d^\dagger T_d\right) - 720g_3^2 \text{Tr}\left(Y_d^\dagger T_d\right) - 54g_1^2 \text{Tr}\left(Y_e^\dagger T_e\right) \\ & \left. + 810\text{Tr}\left(Y_d Y_d^\dagger T_d Y_d^\dagger\right) + 135\text{Tr}\left(Y_d Y_u^\dagger T_u Y_d^\dagger\right) + 270\text{Tr}\left(Y_e Y_e^\dagger T_e Y_e^\dagger\right) + 135\text{Tr}\left(Y_u Y_d^\dagger T_d Y_u^\dagger\right)\right) \end{aligned} \quad (42)$$

$$\begin{aligned} \beta_{T_e}^{(1)} = & +4Y_e Y_e^\dagger T_e + 5T_e Y_e^\dagger Y_e - \frac{9}{5}g_1^2 T_e - 3g_2^2 T_e + 3T_e \text{Tr}\left(Y_d Y_d^\dagger\right) + T_e \text{Tr}\left(Y_e Y_e^\dagger\right) \\ & + Y_e \left(2\text{Tr}\left(Y_e^\dagger T_e\right) + 6g_2^2 M_2 + 6\text{Tr}\left(Y_d^\dagger T_d\right) + \frac{18}{5}g_1^2 M_1\right) \end{aligned} \quad (43)$$

$$\begin{aligned} \beta_{T_e}^{(2)} = & +\frac{6}{5}g_1^2 Y_e Y_e^\dagger T_e + 6g_2^2 Y_e Y_e^\dagger T_e - \frac{6}{5}g_1^2 T_e Y_e^\dagger Y_e + 12g_2^2 T_e Y_e^\dagger Y_e \\ & - 6Y_e Y_e^\dagger Y_e Y_e^\dagger T_e - 8Y_e Y_e^\dagger T_e Y_e^\dagger Y_e - 6T_e Y_e^\dagger Y_e Y_e^\dagger Y_e + \frac{27}{2}g_1^4 T_e + \frac{9}{5}g_1^2 g_2^2 T_e + \frac{15}{2}g_2^4 T_e \\ & - 12Y_e Y_e^\dagger T_e \text{Tr}\left(Y_d Y_d^\dagger\right) - 15T_e Y_e^\dagger Y_e \text{Tr}\left(Y_d Y_d^\dagger\right) - \frac{2}{5}g_1^2 T_e \text{Tr}\left(Y_d Y_d^\dagger\right) \end{aligned}$$

$$\begin{aligned}
& + 16g_3^2 T_e \text{Tr}(Y_d Y_d^\dagger) - 4Y_e Y_e^\dagger T_e \text{Tr}(Y_e Y_e^\dagger) - 5T_e Y_e^\dagger Y_e \text{Tr}(Y_e Y_e^\dagger) \\
& + \frac{6}{5} g_1^2 T_e \text{Tr}(Y_e Y_e^\dagger) - 6Y_e Y_e^\dagger Y_e (2g_2^2 M_2 + 3\text{Tr}(Y_d^\dagger T_d) + \text{Tr}(Y_e^\dagger T_e)) - 9T_e \text{Tr}(Y_d Y_d^\dagger Y_d Y_d^\dagger) \\
& - 3T_e \text{Tr}(Y_d Y_u^\dagger Y_u Y_d^\dagger) - 3T_e \text{Tr}(Y_e Y_e^\dagger Y_e Y_e^\dagger) \\
& - \frac{2}{5} Y_e (135g_1^4 M_1 + 9g_1^2 g_2^2 M_1 + 9g_1^2 g_2^2 M_2 + 75g_2^4 M_2 + (-2g_1^2 M_1 + 80g_3^2 M_3) \text{Tr}(Y_d Y_d^\dagger) \\
& + 6g_1^2 M_1 \text{Tr}(Y_e Y_e^\dagger) + 2g_1^2 \text{Tr}(Y_d^\dagger T_d) - 80g_3^2 \text{Tr}(Y_d^\dagger T_d) - 6g_1^2 \text{Tr}(Y_e^\dagger T_e) \\
& + 90\text{Tr}(Y_d Y_d^\dagger T_d Y_d^\dagger) + 15\text{Tr}(Y_d Y_u^\dagger T_u Y_d^\dagger) + 30\text{Tr}(Y_e Y_e^\dagger T_e Y_e^\dagger) + 15\text{Tr}(Y_u Y_d^\dagger T_d Y_u^\dagger)) \tag{44}
\end{aligned}$$

$$\begin{aligned}
\beta_{T_u}^{(1)} & = +2Y_u Y_d^\dagger T_d + 4Y_u Y_u^\dagger T_u + T_u Y_d^\dagger Y_d + 5T_u Y_u^\dagger Y_u - \frac{13}{15} g_1^2 T_u - 3g_2^2 T_u - \frac{16}{3} g_3^2 T_u \\
& + 3T_u \text{Tr}(Y_u Y_u^\dagger) + Y_u (6g_2^2 M_2 + 6\text{Tr}(Y_u^\dagger T_u) + \frac{26}{15} g_1^2 M_1 + \frac{32}{3} g_3^2 M_3) \tag{45}
\end{aligned}$$

$$\begin{aligned}
\beta_{T_u}^{(2)} & = +\frac{4}{5} g_1^2 Y_u Y_d^\dagger T_d - \frac{4}{5} g_1^2 M_1 Y_u Y_u^\dagger Y_u - 12g_2^2 M_2 Y_u Y_u^\dagger Y_u + \frac{6}{5} g_1^2 Y_u Y_u^\dagger T_u \\
& + 6g_2^2 Y_u Y_u^\dagger T_u + \frac{2}{5} g_1^2 T_u Y_d^\dagger Y_d + 12g_2^2 T_u Y_u^\dagger Y_u - 4Y_u Y_d^\dagger Y_d Y_d^\dagger T_d \\
& - 2Y_u Y_d^\dagger Y_d Y_u^\dagger T_u - 4Y_u Y_d^\dagger T_d Y_d^\dagger Y_d - 4Y_u Y_d^\dagger T_d Y_u^\dagger Y_u - 6Y_u Y_u^\dagger Y_u Y_u^\dagger T_u \\
& - 8Y_u Y_u^\dagger T_u Y_u^\dagger Y_u - 2T_u Y_d^\dagger Y_d Y_d^\dagger Y_d - 4T_u Y_d^\dagger Y_d Y_u^\dagger Y_u - 6T_u Y_u^\dagger Y_u Y_u^\dagger Y_u + \frac{2743}{450} g_1^4 T_u \\
& + g_1^2 g_2^2 T_u + \frac{15}{2} g_2^4 T_u + \frac{136}{45} g_1^2 g_3^2 T_u + 8g_2^2 g_3^2 T_u - \frac{16}{9} g_3^4 T_u - 6Y_u Y_d^\dagger T_d \text{Tr}(Y_d Y_d^\dagger) \\
& - 3T_u Y_d^\dagger Y_d \text{Tr}(Y_d Y_d^\dagger) - 2Y_u Y_d^\dagger T_d \text{Tr}(Y_e Y_e^\dagger) - T_u Y_d^\dagger Y_d \text{Tr}(Y_e Y_e^\dagger) \\
& - 12Y_u Y_u^\dagger T_u \text{Tr}(Y_u Y_u^\dagger) - 15T_u Y_u^\dagger Y_u \text{Tr}(Y_u Y_u^\dagger) + \frac{4}{5} g_1^2 T_u \text{Tr}(Y_u Y_u^\dagger) \\
& + 16g_3^2 T_u \text{Tr}(Y_u Y_u^\dagger) - \frac{2}{5} Y_u Y_d^\dagger Y_d (15\text{Tr}(Y_d^\dagger T_d) + 2g_2^2 M_1 + 5\text{Tr}(Y_e^\dagger T_e)) \\
& - 18Y_u Y_u^\dagger Y_u \text{Tr}(Y_u^\dagger T_u) - 3T_u \text{Tr}(Y_d Y_u^\dagger Y_u Y_d^\dagger) - 9T_u \text{Tr}(Y_u Y_u^\dagger Y_u Y_u^\dagger) \\
& - \frac{2}{225} Y_u (2743g_1^4 M_1 + 225g_1^2 g_2^2 M_1 + 680g_1^2 g_3^2 M_1 + 680g_1^2 g_3^2 M_3 + 1800g_2^2 g_3^2 M_3 - 800g_3^4 M_3 \\
& + 225g_1^2 g_2^2 M_2 + 3375g_2^4 M_2 + 1800g_2^2 g_3^2 M_2 + 180(20g_3^2 M_3 + g_1^2 M_1) \text{Tr}(Y_u Y_u^\dagger) \\
& - 180(20g_3^2 + g_1^2) \text{Tr}(Y_u^\dagger T_u) + 675\text{Tr}(Y_d Y_u^\dagger T_u Y_d^\dagger) + 675\text{Tr}(Y_u Y_d^\dagger T_d Y_u^\dagger) \\
& + 4050\text{Tr}(Y_u Y_u^\dagger T_u Y_u^\dagger)) \tag{46}
\end{aligned}$$

3.7 Bilinear Soft-Breaking Parameters

$$\beta_{B_\mu}^{(1)} = +\frac{6}{5} g_1^2 M_1 \mu + 6g_2^2 M_2 \mu + B_\mu (-3g_2^2 + 3\text{Tr}(Y_d Y_d^\dagger) + 3\text{Tr}(Y_u Y_u^\dagger) - \frac{3}{5} g_1^2 + \text{Tr}(Y_e Y_e^\dagger))$$

$$+ 6\mu\text{Tr}\left(Y_d^\dagger T_d\right) + 2\mu\text{Tr}\left(Y_e^\dagger T_e\right) + 6\mu\text{Tr}\left(Y_u^\dagger T_u\right) \quad (47)$$

$$\begin{aligned} \beta_{B_\mu}^{(2)} = & +B_\mu\left(\frac{207}{50}g_1^4 + \frac{9}{5}g_1^2g_2^2 + \frac{15}{2}g_2^4 - \frac{2}{5}\left(-40g_3^2 + g_1^2\right)\text{Tr}\left(Y_dY_d^\dagger\right) + \frac{6}{5}g_1^2\text{Tr}\left(Y_eY_e^\dagger\right) + \frac{4}{5}g_1^2\text{Tr}\left(Y_uY_u^\dagger\right)\right. \\ & + 16g_3^2\text{Tr}\left(Y_uY_u^\dagger\right) - 9\text{Tr}\left(Y_dY_d^\dagger Y_dY_d^\dagger\right) - 6\text{Tr}\left(Y_dY_u^\dagger Y_uY_d^\dagger\right) - 3\text{Tr}\left(Y_eY_e^\dagger Y_eY_e^\dagger\right) - 9\text{Tr}\left(Y_uY_u^\dagger Y_uY_u^\dagger\right) \\ & - \frac{2}{25}\mu\left(207g_1^4M_1 + 45g_1^2g_2^2M_1 + 45g_1^2g_2^2M_2 + 375g_2^4M_2 - 10\left(-40g_3^2M_3 + g_1^2M_1\right)\text{Tr}\left(Y_dY_d^\dagger\right)\right. \\ & + 30g_1^2M_1\text{Tr}\left(Y_eY_e^\dagger\right) + 20g_1^2M_1\text{Tr}\left(Y_uY_u^\dagger\right) + 400g_3^2M_3\text{Tr}\left(Y_uY_u^\dagger\right) + 10g_1^2\text{Tr}\left(Y_d^\dagger T_d\right) \\ & - 400g_3^2\text{Tr}\left(Y_d^\dagger T_d\right) - 30g_1^2\text{Tr}\left(Y_e^\dagger T_e\right) - 20g_1^2\text{Tr}\left(Y_u^\dagger T_u\right) - 400g_3^2\text{Tr}\left(Y_u^\dagger T_u\right) \\ & + 450\text{Tr}\left(Y_dY_d^\dagger T_dY_d^\dagger\right) + 150\text{Tr}\left(Y_dY_u^\dagger T_uY_d^\dagger\right) + 150\text{Tr}\left(Y_eY_e^\dagger T_eY_e^\dagger\right) + 150\text{Tr}\left(Y_uY_d^\dagger T_dY_u^\dagger\right) \\ & \left. + 450\text{Tr}\left(Y_uY_u^\dagger T_uY_u^\dagger\right)\right) \end{aligned} \quad (48)$$

3.8 Soft-Breaking Scalar Masses

$$\sigma_{1,1} = \sqrt{\frac{3}{5}}g_1\left(-2\text{Tr}\left(m_u^2\right) - \text{Tr}\left(m_l^2\right) - m_{H_d}^2 + m_{H_u}^2 + \text{Tr}\left(m_d^2\right) + \text{Tr}\left(m_e^2\right) + \text{Tr}\left(m_q^2\right)\right) \quad (49)$$

$$\sigma_{2,11} = \frac{1}{10}g_1^2\left(2\text{Tr}\left(m_d^2\right) + 3\text{Tr}\left(m_l^2\right) + 3m_{H_d}^2 + 3m_{H_u}^2 + 6\text{Tr}\left(m_e^2\right) + 8\text{Tr}\left(m_u^2\right) + \text{Tr}\left(m_q^2\right)\right) \quad (50)$$

$$\begin{aligned} \sigma_{3,1} = & \frac{1}{20}\frac{1}{\sqrt{15}}g_1\left(-9g_1^2m_{H_d}^2 - 45g_2^2m_{H_d}^2 + 9g_1^2m_{H_u}^2 + 45g_2^2m_{H_u}^2 + 4\left(20g_3^2 + g_1^2\right)\text{Tr}\left(m_d^2\right) + 36g_1^2\text{Tr}\left(m_e^2\right)\right. \\ & - 9g_1^2\text{Tr}\left(m_l^2\right) - 45g_2^2\text{Tr}\left(m_l^2\right) + g_1^2\text{Tr}\left(m_q^2\right) + 45g_2^2\text{Tr}\left(m_q^2\right) + 80g_3^2\text{Tr}\left(m_q^2\right) - 32g_1^2\text{Tr}\left(m_u^2\right) \\ & - 160g_3^2\text{Tr}\left(m_u^2\right) + 90m_{H_d}^2\text{Tr}\left(Y_dY_d^\dagger\right) + 30m_{H_d}^2\text{Tr}\left(Y_eY_e^\dagger\right) - 90m_{H_u}^2\text{Tr}\left(Y_uY_u^\dagger\right) - 60\text{Tr}\left(Y_dY_d^\dagger m_d^{2*}\right) \\ & - 30\text{Tr}\left(Y_d m_q^{2*} Y_d^\dagger\right) - 60\text{Tr}\left(Y_eY_e^\dagger m_e^{2*}\right) + 30\text{Tr}\left(Y_e m_l^{2*} Y_e^\dagger\right) + 120\text{Tr}\left(Y_uY_u^\dagger m_u^{2*}\right) \\ & \left. - 30\text{Tr}\left(Y_u m_q^{2*} Y_u^\dagger\right)\right) \end{aligned} \quad (51)$$

$$\sigma_{2,2} = \frac{1}{2}\left(3\text{Tr}\left(m_q^2\right) + m_{H_d}^2 + m_{H_u}^2 + \text{Tr}\left(m_l^2\right)\right) \quad (52)$$

$$\sigma_{2,3} = \frac{1}{2}\left(2\text{Tr}\left(m_q^2\right) + \text{Tr}\left(m_d^2\right) + \text{Tr}\left(m_u^2\right)\right) \quad (53)$$

$$\begin{aligned} \beta_{m_q^2}^{(1)} = & -\frac{2}{15}g_1^2\mathbf{1}|M_1|^2 - \frac{32}{3}g_3^2\mathbf{1}|M_3|^2 - 6g_2^2\mathbf{1}|M_2|^2 + 2m_{H_d}^2Y_d^\dagger Y_d + 2m_{H_u}^2Y_u^\dagger Y_u + 2T_d^\dagger T_d \\ & + 2T_u^\dagger T_u + m_q^2Y_d^\dagger Y_d + m_q^2Y_u^\dagger Y_u + 2Y_d^\dagger m_d^2 Y_d + Y_d^\dagger Y_d m_q^2 + 2Y_u^\dagger m_u^2 Y_u \\ & + Y_u^\dagger Y_u m_q^2 + \frac{1}{\sqrt{15}}g_1\mathbf{1}\sigma_{1,1} \end{aligned} \quad (54)$$

$$\beta_{m_q^2}^{(2)} = +\frac{2}{5}g_1^2g_2^2\mathbf{1}|M_2|^2 + 33g_2^4\mathbf{1}|M_2|^2 + 32g_2^2g_3^2\mathbf{1}|M_2|^2$$

$$\begin{aligned}
& + \frac{16}{45}g_3^2 \left(15 \left(3g_2^2 (2M_3 + M_2) - 8g_3^2 M_3 \right) + g_1^2 (2M_3 + M_1) \right) \mathbf{1}M_3^* + \frac{1}{5}g_1^2 g_2^2 M_1 \mathbf{1}M_2^* + 16g_2^2 g_3^2 M_3 \mathbf{1}M_2^* \\
& + \frac{4}{5}g_1^2 m_{H_d}^2 Y_d^\dagger Y_d + \frac{8}{5}g_1^2 m_{H_u}^2 Y_u^\dagger Y_u \\
& + \frac{1}{225}g_1^2 M_1^* \left(\left(5 \left(16g_3^2 (2M_1 + M_3) + 9g_2^2 (2M_1 + M_2) \right) + 597g_1^2 M_1 \right) \mathbf{1} \right. \\
& + 180 \left(2M_1 Y_d^\dagger Y_d - 2Y_u^\dagger T_u + 4M_1 Y_u^\dagger Y_u - Y_d^\dagger T_d \right) \\
& - \frac{4}{5}g_1^2 M_1 T_d^\dagger Y_d + \frac{4}{5}g_1^2 T_d^\dagger T_d - \frac{8}{5}g_1^2 M_1 T_u^\dagger Y_u + \frac{8}{5}g_1^2 T_u^\dagger T_u \\
& + \frac{2}{5}g_1^2 m_q^2 Y_d^\dagger Y_d + \frac{4}{5}g_1^2 m_q^2 Y_u^\dagger Y_u + \frac{4}{5}g_1^2 Y_d^\dagger m_d^2 Y_d + \frac{2}{5}g_1^2 Y_d^\dagger Y_d m_q^2 \\
& + \frac{8}{5}g_1^2 Y_u^\dagger m_u^2 Y_u + \frac{4}{5}g_1^2 Y_u^\dagger Y_u m_q^2 - 8m_{H_d}^2 Y_d^\dagger Y_d Y_d^\dagger Y_d - 4Y_d^\dagger Y_d T_d^\dagger T_d \\
& - 4Y_d^\dagger T_d T_d^\dagger Y_d - 8m_{H_u}^2 Y_u^\dagger Y_u Y_u^\dagger Y_u - 4Y_u^\dagger Y_u T_u^\dagger T_u - 4Y_u^\dagger T_u T_u^\dagger Y_u \\
& - 4T_d^\dagger Y_d Y_d^\dagger T_d - 4T_d^\dagger T_d Y_d^\dagger Y_d - 4T_u^\dagger Y_u Y_u^\dagger T_u - 4T_u^\dagger T_u Y_u^\dagger Y_u \\
& - 2m_q^2 Y_d^\dagger Y_d Y_d^\dagger Y_d - 2m_q^2 Y_u^\dagger Y_u Y_u^\dagger Y_u - 4Y_d^\dagger m_d^2 Y_d Y_d^\dagger Y_d - 4Y_d^\dagger Y_d m_q^2 Y_d^\dagger Y_d \\
& - 4Y_d^\dagger Y_d Y_d^\dagger m_d^2 Y_d - 2Y_d^\dagger Y_d Y_d^\dagger Y_d m_q^2 - 4Y_u^\dagger m_u^2 Y_u Y_u^\dagger Y_u - 4Y_u^\dagger Y_u m_q^2 Y_u^\dagger Y_u \\
& - 4Y_u^\dagger Y_u Y_u^\dagger m_u^2 Y_u - 2Y_u^\dagger Y_u Y_u^\dagger Y_u m_q^2 + 6g_2^4 \mathbf{1}\sigma_{2,2} + \frac{32}{3}g_3^4 \mathbf{1}\sigma_{2,3} + \frac{2}{15}g_1^2 \mathbf{1}\sigma_{2,11} + 4\frac{1}{\sqrt{15}}g_1 \mathbf{1}\sigma_{3,1} \\
& - 12m_{H_d}^2 Y_d^\dagger Y_d \text{Tr} \left(Y_d Y_d^\dagger \right) - 6T_d^\dagger T_d \text{Tr} \left(Y_d Y_d^\dagger \right) - 3m_q^2 Y_d^\dagger Y_d \text{Tr} \left(Y_d Y_d^\dagger \right) \\
& - 6Y_d^\dagger m_d^2 Y_d \text{Tr} \left(Y_d Y_d^\dagger \right) - 3Y_d^\dagger Y_d m_q^2 \text{Tr} \left(Y_d Y_d^\dagger \right) - 4m_{H_d}^2 Y_d^\dagger Y_d \text{Tr} \left(Y_e Y_e^\dagger \right) \\
& - 2T_d^\dagger T_d \text{Tr} \left(Y_e Y_e^\dagger \right) - m_q^2 Y_d^\dagger Y_d \text{Tr} \left(Y_e Y_e^\dagger \right) - 2Y_d^\dagger m_d^2 Y_d \text{Tr} \left(Y_e Y_e^\dagger \right) \\
& - Y_d^\dagger Y_d m_q^2 \text{Tr} \left(Y_e Y_e^\dagger \right) - 12m_{H_u}^2 Y_u^\dagger Y_u \text{Tr} \left(Y_u Y_u^\dagger \right) - 6T_u^\dagger T_u \text{Tr} \left(Y_u Y_u^\dagger \right) \\
& - 3m_q^2 Y_u^\dagger Y_u \text{Tr} \left(Y_u Y_u^\dagger \right) - 6Y_u^\dagger m_u^2 Y_u \text{Tr} \left(Y_u Y_u^\dagger \right) - 3Y_u^\dagger Y_u m_q^2 \text{Tr} \left(Y_u Y_u^\dagger \right) \\
& - 6T_d^\dagger Y_d \text{Tr} \left(Y_e^\dagger T_e \right) - 2T_d^\dagger Y_d \text{Tr} \left(Y_e^\dagger T_e \right) - 6T_u^\dagger Y_u \text{Tr} \left(Y_u^\dagger T_u \right) \\
& - 6Y_d^\dagger T_d \text{Tr} \left(T_d^* Y_d^T \right) - 6Y_d^\dagger Y_d \text{Tr} \left(T_d^* T_d^T \right) - 2Y_d^\dagger T_d \text{Tr} \left(T_e^* Y_e^T \right) \\
& - 2Y_d^\dagger Y_d \text{Tr} \left(T_e^* T_e^T \right) - 6Y_u^\dagger T_u \text{Tr} \left(T_u^* Y_u^T \right) - 6Y_u^\dagger Y_u \text{Tr} \left(T_u^* T_u^T \right) \\
& - 6Y_d^\dagger Y_d \text{Tr} \left(m_e^2 Y_e Y_e^\dagger \right) - 2Y_d^\dagger Y_d \text{Tr} \left(m_e^2 Y_e Y_e^\dagger \right) - 2Y_d^\dagger Y_d \text{Tr} \left(m_l^2 Y_e^\dagger Y_e \right) \\
& - 6Y_d^\dagger Y_d \text{Tr} \left(m_q^2 Y_d^\dagger Y_d \right) - 6Y_u^\dagger Y_u \text{Tr} \left(m_q^2 Y_u^\dagger Y_u \right) - 6Y_u^\dagger Y_u \text{Tr} \left(m_u^2 Y_u Y_u^\dagger \right)
\end{aligned} \tag{55}$$

$$\beta_{m_l^2}^{(1)} = -\frac{6}{5}g_1^2 \mathbf{1}|M_1|^2 - 6g_2^2 \mathbf{1}|M_2|^2 + 2m_{H_d}^2 Y_e^\dagger Y_e + 2T_e^\dagger T_e + m_l^2 Y_e^\dagger Y_e + 2Y_e^\dagger m_e^2 Y_e$$

$$+ Y_e^\dagger Y_e m_l^2 - \sqrt{\frac{3}{5}}g_1 \mathbf{1}\sigma_{1,1} \tag{56}$$

$$\beta_{m_l^2}^{(2)} = +\frac{3}{5}g_2^2 \left(3g_1^2 (2M_2 + M_1) + 55g_2^2 M_2 \right) \mathbf{1}M_2^* + \frac{12}{5}g_1^2 m_{H_d}^2 Y_e^\dagger Y_e$$

$$\begin{aligned}
& + \frac{3}{25}g_1^2M_1^* \left(-20Y_e^\dagger T_e + 3 \left(5g_2^2(2M_1 + M_2) + 69g_1^2M_1 \right) \mathbf{1} + 40M_1Y_e^\dagger Y_e \right) - \frac{12}{5}g_1^2M_1T_e^\dagger Y_e \\
& + \frac{12}{5}g_1^2T_e^\dagger T_e + \frac{6}{5}g_1^2m_l^2Y_e^\dagger Y_e + \frac{12}{5}g_1^2Y_e^\dagger m_e^2Y_e + \frac{6}{5}g_1^2Y_e^\dagger Y_e m_l^2 \\
& - 8m_{H_d}^2Y_e^\dagger Y_e Y_e^\dagger Y_e - 4Y_e^\dagger Y_e T_e^\dagger T_e - 4Y_e^\dagger T_e T_e^\dagger Y_e - 4T_e^\dagger Y_e Y_e^\dagger T_e \\
& - 4T_e^\dagger T_e Y_e^\dagger Y_e - 2m_l^2Y_e^\dagger Y_e Y_e^\dagger Y_e - 4Y_e^\dagger m_e^2Y_e Y_e^\dagger Y_e - 4Y_e^\dagger Y_e m_l^2Y_e^\dagger Y_e \\
& - 4Y_e^\dagger Y_e Y_e^\dagger m_e^2Y_e - 2Y_e^\dagger Y_e Y_e^\dagger Y_e m_l^2 + 6g_2^4\mathbf{1}\sigma_{2,2} + \frac{6}{5}g_1^2\mathbf{1}\sigma_{2,11} - 4\sqrt{\frac{3}{5}}g_1\mathbf{1}\sigma_{3,1} \\
& - 12m_{H_d}^2Y_e^\dagger Y_e \text{Tr}(Y_d Y_d^\dagger) - 6T_e^\dagger T_e \text{Tr}(Y_d Y_d^\dagger) - 3m_l^2Y_e^\dagger Y_e \text{Tr}(Y_d Y_d^\dagger) \\
& - 6Y_e^\dagger m_e^2Y_e \text{Tr}(Y_d Y_d^\dagger) - 3Y_e^\dagger Y_e m_l^2 \text{Tr}(Y_d Y_d^\dagger) - 4m_{H_d}^2Y_e^\dagger Y_e \text{Tr}(Y_e Y_e^\dagger) \\
& - 2T_e^\dagger T_e \text{Tr}(Y_e Y_e^\dagger) - m_l^2Y_e^\dagger Y_e \text{Tr}(Y_e Y_e^\dagger) - 2Y_e^\dagger m_e^2Y_e \text{Tr}(Y_e Y_e^\dagger) \\
& - Y_e^\dagger Y_e m_l^2 \text{Tr}(Y_e Y_e^\dagger) - 6T_e^\dagger Y_e \text{Tr}(Y_d^\dagger T_d) - 2T_e^\dagger Y_e \text{Tr}(Y_e^\dagger T_e) \\
& - 6Y_e^\dagger T_e \text{Tr}(T_d^* Y_d^T) - 6Y_e^\dagger Y_e \text{Tr}(T_d^* T_d^T) - 2Y_e^\dagger T_e \text{Tr}(T_e^* Y_e^T) \\
& - 2Y_e^\dagger Y_e \text{Tr}(T_e^* T_e^T) - 6Y_e^\dagger Y_e \text{Tr}(m_d^2 Y_d Y_d^\dagger) - 2Y_e^\dagger Y_e \text{Tr}(m_e^2 Y_e Y_e^\dagger) \\
& - 2Y_e^\dagger Y_e \text{Tr}(m_l^2 Y_e^\dagger Y_e) - 6Y_e^\dagger Y_e \text{Tr}(m_q^2 Y_d^\dagger Y_d) \tag{57}
\end{aligned}$$

$$\begin{aligned}
\beta_{m_{H_d}^2}^{(1)} & = -\frac{6}{5}g_1^2|M_1|^2 - 6g_2^2|M_2|^2 - \sqrt{\frac{3}{5}}g_1\sigma_{1,1} + 6m_{H_d}^2 \text{Tr}(Y_d Y_d^\dagger) + 2m_{H_d}^2 \text{Tr}(Y_e Y_e^\dagger) + 6\text{Tr}(T_d^* T_d^T) \\
& + 2\text{Tr}(T_e^* T_e^T) + 6\text{Tr}(m_d^2 Y_d Y_d^\dagger) + 2\text{Tr}(m_e^2 Y_e Y_e^\dagger) + 2\text{Tr}(m_l^2 Y_e^\dagger Y_e) + 6\text{Tr}(m_q^2 Y_d^\dagger Y_d) \tag{58}
\end{aligned}$$

$$\begin{aligned}
\beta_{m_{H_d}^2}^{(2)} & = \frac{1}{25} \left(15g_2^2(3g_1^2(2M_2 + M_1) + 55g_2^2M_2)M_2^* \right. \\
& + g_1^2M_1^* \left(621g_1^2M_1 + 90g_2^2M_1 + 45g_2^2M_2 - 40M_1 \text{Tr}(Y_d Y_d^\dagger) + 120M_1 \text{Tr}(Y_e Y_e^\dagger) + 20\text{Tr}(Y_d^\dagger T_d) \right. \\
& \left. \left. - 60\text{Tr}(Y_e^\dagger T_e) \right) \right) \\
& + 10 \left(15g_2^4\sigma_{2,2} + 3g_1^2\sigma_{2,11} - 2\sqrt{15}g_1\sigma_{3,1} + \left(160g_3^2|M_3|^2 - 2g_1^2m_{H_d}^2 + 80g_3^2m_{H_d}^2 \right) \text{Tr}(Y_d Y_d^\dagger) \right. \\
& + 6g_1^2m_{H_d}^2 \text{Tr}(Y_e Y_e^\dagger) - 80g_3^2M_3^* \text{Tr}(Y_d^\dagger T_d) + 2g_1^2M_1 \text{Tr}(T_d^* Y_d^T) - 80g_3^2M_3 \text{Tr}(T_d^* Y_d^T) \\
& - 2g_1^2 \text{Tr}(T_d^* T_d^T) + 80g_3^2 \text{Tr}(T_d^* T_d^T) - 6g_1^2M_1 \text{Tr}(T_e^* Y_e^T) + 6g_1^2 \text{Tr}(T_e^* T_e^T) \\
& - 2g_1^2 \text{Tr}(m_d^2 Y_d Y_d^\dagger) + 80g_3^2 \text{Tr}(m_d^2 Y_d Y_d^\dagger) + 6g_1^2 \text{Tr}(m_e^2 Y_e Y_e^\dagger) + 6g_1^2 \text{Tr}(m_l^2 Y_e^\dagger Y_e) \\
& - 2g_1^2 \text{Tr}(m_q^2 Y_d^\dagger Y_d) + 80g_3^2 \text{Tr}(m_q^2 Y_d^\dagger Y_d) - 90m_{H_d}^2 \text{Tr}(Y_d Y_d^\dagger Y_d Y_d^\dagger) - 90\text{Tr}(Y_d Y_d^\dagger T_d T_d^\dagger) \\
& - 15m_{H_d}^2 \text{Tr}(Y_d Y_u^\dagger Y_u Y_d^\dagger) - 15m_{H_d}^2 \text{Tr}(Y_d Y_u^\dagger Y_u Y_d^\dagger) - 15\text{Tr}(Y_d Y_u^\dagger T_u T_u^\dagger) \\
& \left. \left. - 90\text{Tr}(Y_d T_d^\dagger T_d Y_d^\dagger) - 15\text{Tr}(Y_d T_u^\dagger T_u Y_d^\dagger) - 30m_{H_d}^2 \text{Tr}(Y_e Y_e^\dagger Y_e Y_e^\dagger) - 30\text{Tr}(Y_e Y_e^\dagger T_e T_e^\dagger) \right) \right)
\end{aligned}$$

$$\begin{aligned}
& -30\text{Tr}\left(Y_e T_e^\dagger T_e Y_e^\dagger\right) - 15\text{Tr}\left(Y_u Y_d^\dagger T_d T_u^\dagger\right) - 15\text{Tr}\left(Y_u T_d^\dagger T_d Y_u^\dagger\right) - 90\text{Tr}\left(m_d^2 Y_d Y_d^\dagger Y_d Y_d^\dagger\right) \\
& - 15\text{Tr}\left(m_d^2 Y_d Y_u^\dagger Y_u Y_d^\dagger\right) - 30\text{Tr}\left(m_e^2 Y_e Y_e^\dagger Y_e Y_e^\dagger\right) - 30\text{Tr}\left(m_l^2 Y_e^\dagger Y_e Y_e^\dagger Y_e\right) - 90\text{Tr}\left(m_q^2 Y_d^\dagger Y_d Y_d^\dagger Y_d\right) \\
& - 15\text{Tr}\left(m_q^2 Y_d^\dagger Y_d Y_u^\dagger Y_u\right) - 15\text{Tr}\left(m_q^2 Y_u^\dagger Y_u Y_d^\dagger Y_d\right) - 15\text{Tr}\left(m_u^2 Y_u Y_d^\dagger Y_d Y_u^\dagger\right)
\end{aligned} \tag{59}$$

$$\begin{aligned}
\beta_{m_{H_u}^2}^{(1)} &= -\frac{6}{5}g_1^2|M_1|^2 - 6g_2^2|M_2|^2 + \sqrt{\frac{3}{5}}g_1\sigma_{1,1} + 6m_{H_u}^2\text{Tr}\left(Y_u Y_u^\dagger\right) + 6\text{Tr}\left(T_u^* T_u^T\right) + 6\text{Tr}\left(m_q^2 Y_u^\dagger Y_u\right) \\
&+ 6\text{Tr}\left(m_u^2 Y_u Y_u^\dagger\right)
\end{aligned} \tag{60}$$

$$\begin{aligned}
\beta_{m_{H_u}^2}^{(2)} &= +\frac{3}{5}g_2^2\left(3g_1^2\left(2M_2 + M_1\right) + 55g_2^2M_2\right)M_2^* + 6g_2^4\sigma_{2,2} + \frac{6}{5}g_1^2\sigma_{2,11} + 4\sqrt{\frac{3}{5}}g_1\sigma_{3,1} + \frac{8}{5}g_1^2m_{H_u}^2\text{Tr}\left(Y_u Y_u^\dagger\right) \\
&+ 32g_3^2m_{H_u}^2\text{Tr}\left(Y_u Y_u^\dagger\right) + 64g_3^2|M_3|^2\text{Tr}\left(Y_u Y_u^\dagger\right) \\
&+ \frac{1}{25}g_1^2M_1^*\left(-40\text{Tr}\left(Y_u^\dagger T_u\right) + 45g_2^2M_2 + 621g_1^2M_1 + 80M_1\text{Tr}\left(Y_u Y_u^\dagger\right) + 90g_2^2M_1\right) \\
&- 32g_3^2M_3^*\text{Tr}\left(Y_u^\dagger T_u\right) - \frac{8}{5}g_1^2M_1\text{Tr}\left(T_u^* Y_u^T\right) - 32g_3^2M_3\text{Tr}\left(T_u^* Y_u^T\right) + \frac{8}{5}g_1^2\text{Tr}\left(T_u^* T_u^T\right) \\
&+ 32g_3^2\text{Tr}\left(T_u^* T_u^T\right) + \frac{8}{5}g_1^2\text{Tr}\left(m_q^2 Y_u^\dagger Y_u\right) + 32g_3^2\text{Tr}\left(m_q^2 Y_u^\dagger Y_u\right) + \frac{8}{5}g_1^2\text{Tr}\left(m_u^2 Y_u Y_u^\dagger\right) \\
&+ 32g_3^2\text{Tr}\left(m_u^2 Y_u Y_u^\dagger\right) - 6m_{H_d}^2\text{Tr}\left(Y_d Y_u^\dagger Y_u Y_d^\dagger\right) - 6m_{H_u}^2\text{Tr}\left(Y_d Y_u^\dagger Y_u Y_d^\dagger\right) \\
&- 6\text{Tr}\left(Y_d Y_u^\dagger T_u T_d^\dagger\right) - 6\text{Tr}\left(Y_d T_u^\dagger T_u Y_d^\dagger\right) - 6\text{Tr}\left(Y_u Y_d^\dagger T_d T_u^\dagger\right) - 36m_{H_u}^2\text{Tr}\left(Y_u Y_u^\dagger Y_u Y_u^\dagger\right) \\
&- 36\text{Tr}\left(Y_u Y_u^\dagger T_u T_u^\dagger\right) - 6\text{Tr}\left(Y_u T_d^\dagger T_d Y_u^\dagger\right) - 36\text{Tr}\left(Y_u T_u^\dagger T_u Y_u^\dagger\right) \\
&- 6\text{Tr}\left(m_d^2 Y_d Y_u^\dagger Y_u Y_d^\dagger\right) - 6\text{Tr}\left(m_q^2 Y_d^\dagger Y_d Y_u^\dagger Y_u\right) - 6\text{Tr}\left(m_q^2 Y_u^\dagger Y_u Y_d^\dagger Y_d\right) \\
&- 36\text{Tr}\left(m_q^2 Y_u^\dagger Y_u Y_u^\dagger Y_u\right) - 6\text{Tr}\left(m_u^2 Y_u Y_d^\dagger Y_d Y_u^\dagger\right) - 36\text{Tr}\left(m_u^2 Y_u Y_u^\dagger Y_u Y_u^\dagger\right)
\end{aligned} \tag{61}$$

$$\begin{aligned}
\beta_{m_d^2}^{(1)} &= -\frac{8}{15}g_1^2\mathbf{1}|M_1|^2 - \frac{32}{3}g_3^2\mathbf{1}|M_3|^2 + 4m_{H_d}^2 Y_d Y_d^\dagger + 4T_d T_d^\dagger + 2m_d^2 Y_d Y_d^\dagger + 4Y_d m_q^2 Y_d^\dagger \\
&+ 2Y_d Y_d^\dagger m_d^2 + 2\frac{1}{\sqrt{15}}g_1\mathbf{1}\sigma_{1,1}
\end{aligned} \tag{62}$$

$$\begin{aligned}
\beta_{m_d^2}^{(2)} &= +\frac{64}{45}g_3^2\left(-30g_3^2M_3 + g_1^2\left(2M_3 + M_1\right)\right)\mathbf{1}M_3^* + \frac{4}{5}g_1^2m_{H_d}^2 Y_d Y_d^\dagger + 12g_2^2m_{H_d}^2 Y_d Y_d^\dagger \\
&+ 24g_2^2|M_2|^2 Y_d Y_d^\dagger - \frac{4}{5}g_1^2M_1 Y_d T_d^\dagger - 12g_2^2M_2 Y_d T_d^\dagger \\
&+ \frac{4}{225}g_1^2M_1^*\left(2\left(303g_1^2M_1 + 40g_3^2\left(2M_1 + M_3\right)\right)\mathbf{1} - 45T_d Y_d^\dagger + 90M_1 Y_d Y_d^\dagger\right) - 12g_2^2M_2^* T_d Y_d^\dagger \\
&+ \frac{4}{5}g_1^2 T_d T_d^\dagger + 12g_2^2 T_d T_d^\dagger + \frac{2}{5}g_1^2 m_d^2 Y_d Y_d^\dagger + 6g_2^2 m_d^2 Y_d Y_d^\dagger \\
&+ \frac{4}{5}g_1^2 Y_d m_q^2 Y_d^\dagger + 12g_2^2 Y_d m_q^2 Y_d^\dagger + \frac{2}{5}g_1^2 Y_d Y_d^\dagger m_d^2 + 6g_2^2 Y_d Y_d^\dagger m_d^2 \\
&- 8m_{H_d}^2 Y_d Y_d^\dagger Y_d Y_d^\dagger - 4Y_d Y_d^\dagger T_d T_d^\dagger - 4m_{H_d}^2 Y_d Y_u^\dagger Y_u Y_d^\dagger \\
&- 4m_{H_u}^2 Y_d Y_u^\dagger Y_u Y_d^\dagger - 4Y_d Y_u^\dagger T_u T_d^\dagger - 4Y_d T_d^\dagger T_d Y_d^\dagger - 4Y_d T_u^\dagger T_u Y_d^\dagger
\end{aligned}$$

$$\begin{aligned}
& -4T_d Y_d^\dagger Y_d T_d^\dagger - 4T_d Y_u^\dagger Y_u T_d^\dagger - 4T_d T_d^\dagger Y_d Y_d^\dagger - 4T_d T_d^\dagger Y_u Y_u^\dagger \\
& -2m_d^2 Y_d Y_d^\dagger Y_d Y_d^\dagger - 2m_d^2 Y_d Y_u^\dagger Y_u Y_d^\dagger - 4Y_d m_q^2 Y_d^\dagger Y_d Y_d^\dagger - 4Y_d m_q^2 Y_u^\dagger Y_u Y_d^\dagger \\
& -4Y_d Y_d^\dagger m_d^2 Y_d Y_d^\dagger - 4Y_d Y_d^\dagger Y_d m_q^2 Y_d^\dagger - 2Y_d Y_d^\dagger Y_d Y_d^\dagger m_d^2 - 4Y_d Y_u^\dagger m_u^2 Y_u Y_d^\dagger \\
& -4Y_d Y_u^\dagger Y_u m_q^2 Y_d^\dagger - 2Y_d Y_u^\dagger Y_u Y_d^\dagger m_d^2 + \frac{32}{3} g_3^4 \mathbf{1}\sigma_{2,3} + \frac{8}{15} g_1^2 \mathbf{1}\sigma_{2,11} + 8 \frac{1}{\sqrt{15}} g_1 \mathbf{1}\sigma_{3,1} \\
& -24m_{H_d}^2 Y_d Y_d^\dagger \text{Tr}(Y_d Y_d^\dagger) - 12T_d T_d^\dagger \text{Tr}(Y_d Y_d^\dagger) - 6m_d^2 Y_d Y_d^\dagger \text{Tr}(Y_d Y_d^\dagger) \\
& -12Y_d m_q^2 Y_d^\dagger \text{Tr}(Y_d Y_d^\dagger) - 6Y_d Y_d^\dagger m_d^2 \text{Tr}(Y_d Y_d^\dagger) - 8m_{H_d}^2 Y_d Y_d^\dagger \text{Tr}(Y_e Y_e^\dagger) \\
& -4T_d T_d^\dagger \text{Tr}(Y_e Y_e^\dagger) - 2m_d^2 Y_d Y_d^\dagger \text{Tr}(Y_e Y_e^\dagger) - 4Y_d m_q^2 Y_d^\dagger \text{Tr}(Y_e Y_e^\dagger) \\
& -2Y_d Y_d^\dagger m_d^2 \text{Tr}(Y_e Y_e^\dagger) - 12Y_d T_d^\dagger \text{Tr}(Y_d^\dagger T_d) - 4Y_d T_d^\dagger \text{Tr}(Y_e^\dagger T_e) \\
& -12T_d Y_d^\dagger \text{Tr}(T_d^* Y_d^T) - 12Y_d Y_d^\dagger \text{Tr}(T_d^* T_d^T) - 4T_d Y_d^\dagger \text{Tr}(T_e^* Y_e^T) \\
& -4Y_d Y_d^\dagger \text{Tr}(T_e^* T_e^T) - 12Y_d Y_d^\dagger \text{Tr}(m_d^2 Y_d Y_d^\dagger) - 4Y_d Y_d^\dagger \text{Tr}(m_e^2 Y_e Y_e^\dagger) \\
& -4Y_d Y_d^\dagger \text{Tr}(m_l^2 Y_e^\dagger Y_e) - 12Y_d Y_d^\dagger \text{Tr}(m_q^2 Y_d^\dagger Y_d)
\end{aligned} \tag{63}$$

$$\begin{aligned}
\beta_{m_u^2}^{(1)} &= -\frac{32}{15} g_1^2 \mathbf{1}|M_1|^2 - \frac{32}{3} g_3^2 \mathbf{1}|M_3|^2 + 4m_{H_u}^2 Y_u Y_u^\dagger + 4T_u T_u^\dagger + 2m_u^2 Y_u Y_u^\dagger + 4Y_u m_q^2 Y_u^\dagger \\
&+ 2Y_u Y_u^\dagger m_u^2 - 4 \frac{1}{\sqrt{15}} g_1 \mathbf{1}\sigma_{1,1}
\end{aligned} \tag{64}$$

$$\begin{aligned}
\beta_{m_u^2}^{(2)} &= -\frac{128}{45} g_3^2 (15g_3^2 M_3 - 2g_1^2 (2M_3 + M_1)) \mathbf{1}M_3^* - \frac{4}{5} g_1^2 m_{H_u}^2 Y_u Y_u^\dagger + 12g_2^2 m_{H_u}^2 Y_u Y_u^\dagger \\
&+ 24g_2^2 |M_2|^2 Y_u Y_u^\dagger + \frac{4}{5} g_1^2 M_1 Y_u T_u^\dagger - 12g_2^2 M_2 Y_u T_u^\dagger - 12g_2^2 M_2^* T_u Y_u^\dagger \\
&+ \frac{4}{225} g_1^2 M_1^* (45(-2M_1 Y_u Y_u^\dagger + T_u Y_u^\dagger) + 8(321g_1^2 M_1 + 40g_3^2 (2M_1 + M_3)) \mathbf{1}) - \frac{4}{5} g_1^2 T_u T_u^\dagger \\
&+ 12g_2^2 T_u T_u^\dagger - \frac{2}{5} g_1^2 m_u^2 Y_u Y_u^\dagger + 6g_2^2 m_u^2 Y_u Y_u^\dagger - \frac{4}{5} g_1^2 Y_u m_q^2 Y_u^\dagger \\
&+ 12g_2^2 Y_u m_q^2 Y_u^\dagger - \frac{2}{5} g_1^2 Y_u Y_u^\dagger m_u^2 + 6g_2^2 Y_u Y_u^\dagger m_u^2 - 4m_{H_d}^2 Y_u Y_d^\dagger Y_d Y_u^\dagger \\
&- 4m_{H_u}^2 Y_u Y_d^\dagger Y_d Y_u^\dagger - 4Y_u Y_d^\dagger T_d T_u^\dagger - 8m_{H_u}^2 Y_u Y_u^\dagger Y_u Y_u^\dagger - 4Y_u Y_u^\dagger T_u T_u^\dagger \\
&- 4Y_u T_d^\dagger T_d Y_u^\dagger - 4Y_u T_u^\dagger T_u Y_u^\dagger - 4T_u Y_d^\dagger Y_d T_u^\dagger - 4T_u Y_u^\dagger Y_u T_u^\dagger \\
&- 4T_u T_d^\dagger Y_d Y_u^\dagger - 4T_u T_u^\dagger Y_u Y_u^\dagger - 2m_u^2 Y_u Y_d^\dagger Y_d Y_u^\dagger - 2m_u^2 Y_u Y_u^\dagger Y_u Y_u^\dagger \\
&- 4Y_u m_q^2 Y_d^\dagger Y_d Y_u^\dagger - 4Y_u m_q^2 Y_u^\dagger Y_u Y_u^\dagger - 4Y_u Y_d^\dagger m_d^2 Y_d Y_u^\dagger \\
&- 4Y_u Y_d^\dagger Y_d m_q^2 Y_u^\dagger - 2Y_u Y_d^\dagger Y_d Y_u^\dagger m_u^2 - 4Y_u Y_u^\dagger m_u^2 Y_u Y_u^\dagger - 4Y_u Y_u^\dagger Y_u m_q^2 Y_u^\dagger \\
&- 2Y_u Y_u^\dagger Y_u Y_u^\dagger m_u^2 + \frac{32}{3} g_3^4 \mathbf{1}\sigma_{2,3} + \frac{32}{15} g_1^2 \mathbf{1}\sigma_{2,11} - 16 \frac{1}{\sqrt{15}} g_1 \mathbf{1}\sigma_{3,1} - 24m_{H_u}^2 Y_u Y_u^\dagger \text{Tr}(Y_u Y_u^\dagger) \\
&- 12T_u T_u^\dagger \text{Tr}(Y_u Y_u^\dagger) - 6m_u^2 Y_u Y_u^\dagger \text{Tr}(Y_u Y_u^\dagger) - 12Y_u m_q^2 Y_u^\dagger \text{Tr}(Y_u Y_u^\dagger)
\end{aligned}$$

$$\begin{aligned}
& -6Y_u Y_u^\dagger m_u^2 \text{Tr}(Y_u Y_u^\dagger) - 12Y_u T_u^\dagger \text{Tr}(Y_u^\dagger T_u) - 12T_u Y_u^\dagger \text{Tr}(T_u^* Y_u^T) \\
& - 12Y_u Y_u^\dagger \text{Tr}(T_u^* T_u^T) - 12Y_u Y_u^\dagger \text{Tr}(m_q^2 Y_u^\dagger Y_u) - 12Y_u Y_u^\dagger \text{Tr}(m_u^2 Y_u Y_u^\dagger)
\end{aligned} \tag{65}$$

$$\begin{aligned}
\beta_{m_e^2}^{(1)} &= -\frac{24}{5} g_1^2 \mathbf{1} |M_1|^2 + 2 \left(2m_{H_d}^2 Y_e Y_e^\dagger + 2T_e T_e^\dagger + 2Y_e m_l^2 Y_e^\dagger + m_e^2 Y_e Y_e^\dagger + Y_e Y_e^\dagger m_e^2 \right) \\
&+ 2\sqrt{\frac{3}{5}} g_1 \mathbf{1} \sigma_{1,1}
\end{aligned} \tag{66}$$

$$\begin{aligned}
\beta_{m_e^2}^{(2)} &= \frac{2}{25} \left(6g_1^2 M_1^* \left(234g_1^2 M_1 \mathbf{1} + 5 \left(-2M_1 Y_e Y_e^\dagger + T_e Y_e^\dagger \right) \right) + 20g_1 \mathbf{1} \left(3g_1 \sigma_{2,11} + \sqrt{15} \sigma_{3,1} \right) \right. \\
&- 5 \left(30g_2^2 M_2^* T_e Y_e^\dagger + 6g_1^2 T_e T_e^\dagger - 30g_2^2 T_e T_e^\dagger + 3g_1^2 m_e^2 Y_e Y_e^\dagger \right. \\
&- 15g_2^2 m_e^2 Y_e Y_e^\dagger + 6g_1^2 Y_e m_l^2 Y_e^\dagger - 30g_2^2 Y_e m_l^2 Y_e^\dagger + 3g_1^2 Y_e Y_e^\dagger m_e^2 \\
&- 15g_2^2 Y_e Y_e^\dagger m_e^2 + 20m_{H_d}^2 Y_e Y_e^\dagger Y_e Y_e^\dagger + 10Y_e Y_e^\dagger T_e T_e^\dagger + 10Y_e T_e^\dagger T_e Y_e^\dagger \\
&+ 10T_e Y_e^\dagger Y_e T_e^\dagger + 10T_e T_e^\dagger Y_e Y_e^\dagger + 5m_e^2 Y_e Y_e^\dagger Y_e Y_e^\dagger + 10Y_e m_l^2 Y_e^\dagger Y_e Y_e^\dagger \\
&+ 10Y_e Y_e^\dagger m_e^2 Y_e Y_e^\dagger + 10Y_e Y_e^\dagger Y_e m_l^2 Y_e^\dagger + 5Y_e Y_e^\dagger Y_e Y_e^\dagger m_e^2 + 30T_e T_e^\dagger \text{Tr}(Y_d Y_d^\dagger) \\
&+ 15m_e^2 Y_e Y_e^\dagger \text{Tr}(Y_d Y_d^\dagger) + 30Y_e m_l^2 Y_e^\dagger \text{Tr}(Y_d Y_d^\dagger) + 15Y_e Y_e^\dagger m_e^2 \text{Tr}(Y_d Y_d^\dagger) \\
&+ 10T_e T_e^\dagger \text{Tr}(Y_e Y_e^\dagger) + 5m_e^2 Y_e Y_e^\dagger \text{Tr}(Y_e Y_e^\dagger) + 10Y_e m_l^2 Y_e^\dagger \text{Tr}(Y_e Y_e^\dagger) \\
&+ 5Y_e Y_e^\dagger m_e^2 \text{Tr}(Y_e Y_e^\dagger) + Y_e T_e^\dagger \left(10\text{Tr}(Y_e^\dagger T_e) + 30g_2^2 M_2 + 30\text{Tr}(Y_d^\dagger T_d) - 6g_1^2 M_1 \right) \\
&+ 30T_e Y_e^\dagger \text{Tr}(T_d^* Y_d^T) + 10T_e Y_e^\dagger \text{Tr}(T_e^* Y_e^T) \\
&+ 2Y_e Y_e^\dagger \left(3g_1^2 m_{H_d}^2 - 15g_2^2 m_{H_d}^2 - 30g_2^2 |M_2|^2 + 30m_{H_d}^2 \text{Tr}(Y_d Y_d^\dagger) + 10m_{H_d}^2 \text{Tr}(Y_e Y_e^\dagger) + 15\text{Tr}(T_d^* T_d^T) \right. \\
&\left. + 5\text{Tr}(T_e^* T_e^T) + 15\text{Tr}(m_d^2 Y_d Y_d^\dagger) + 5\text{Tr}(m_e^2 Y_e Y_e^\dagger) + 5\text{Tr}(m_l^2 Y_e^\dagger Y_e) + 15\text{Tr}(m_q^2 Y_d^\dagger Y_d) \right) \left. \right)
\end{aligned} \tag{67}$$

3.9 Vacuum expectation values

$$\beta_{v_d}^{(1)} = \frac{1}{20} v_d \left(-20\text{Tr}(Y_e Y_e^\dagger) + 3(5g_2^2 + g_1^2)(1 + \text{Xi}) - 60\text{Tr}(Y_d Y_d^\dagger) \right) \tag{68}$$

$$\begin{aligned}
\beta_{v_d}^{(2)} &= \frac{1}{400} v_d \left(-414g_1^4 - 180g_1^2 g_2^2 - 1200g_2^4 - 9g_1^4 \text{Xi} - 90g_1^2 g_2^2 \text{Xi} + 875g_2^4 \text{Xi} + 9g_1^4 \text{Xi}^2 + 90g_1^2 g_2^2 \text{Xi}^2 \right. \\
&- 225g_2^4 \text{Xi}^2 - 40 \left(5(32g_3^2 + 9g_2^2 \text{Xi}) + g_1^2(9\text{Xi} - 4) \right) \text{Tr}(Y_d Y_d^\dagger) - 120(5g_2^2 \text{Xi} + g_1^2(4 + \text{Xi})) \text{Tr}(Y_e Y_e^\dagger) \\
&\left. + 3600\text{Tr}(Y_d Y_d^\dagger Y_d Y_d^\dagger) + 1200\text{Tr}(Y_d Y_u^\dagger Y_u Y_d^\dagger) + 1200\text{Tr}(Y_e Y_e^\dagger Y_e Y_e^\dagger) \right)
\end{aligned} \tag{69}$$

$$\beta_{v_u}^{(1)} = \frac{3}{20} v_u \left(-20\text{Tr}(Y_u Y_u^\dagger) + (5g_2^2 + g_1^2)(1 + \text{Xi}) \right) \tag{70}$$

$$\beta_{v_u}^{(2)} = \frac{1}{400} v_u \left(-414g_1^4 - 180g_1^2 g_2^2 - 1200g_2^4 - 9g_1^4 \text{Xi} - 90g_1^2 g_2^2 \text{Xi} + 875g_2^4 \text{Xi} + 9g_1^4 \text{Xi}^2 + 90g_1^2 g_2^2 \text{Xi}^2 \right)$$

$$-225g_2^4 X_i^2 - 40\left(5\left(32g_3^2 + 9g_2^2 X_i\right) + g_1^2\left(9X_i + 8\right)\right)\text{Tr}\left(Y_u Y_u^\dagger\right) + 1200\text{Tr}\left(Y_d Y_u^\dagger Y_u Y_d^\dagger\right) + 3600\text{Tr}\left(Y_u Y_u^\dagger Y_u Y_u^\dagger\right) \quad (71)$$

4 Field Rotations

4.1 Rotations in gauge sector for eigenstates 'EWSB'

$$\begin{pmatrix} B_\rho \\ W_{3\rho} \end{pmatrix} = Z^{\gamma Z} \begin{pmatrix} \gamma_\rho \\ Z_\rho \end{pmatrix} \quad (72)$$

$$\begin{pmatrix} W_{1\rho} \\ W_{2\rho} \end{pmatrix} = Z^W \begin{pmatrix} W_\rho^- \\ W_\rho^- \end{pmatrix} \quad (73)$$

$$\begin{pmatrix} \lambda_{\tilde{W},1} \\ \lambda_{\tilde{W},2} \\ \lambda_{\tilde{W},3} \end{pmatrix} = Z^{\tilde{W}} \begin{pmatrix} \tilde{W}^- \\ \tilde{W}^+ \\ \tilde{W}^0 \end{pmatrix} \quad (74)$$

$$(75)$$

The mixing matrices are parametrized by

$$Z^{\gamma Z} = \begin{pmatrix} \cos \Theta_W & -\sin \Theta_W \\ \sin \Theta_W & \cos \Theta_W \end{pmatrix} \quad (76)$$

$$Z^W = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ -i\frac{1}{\sqrt{2}} & i\frac{1}{\sqrt{2}} \end{pmatrix} \quad (77)$$

$$Z^{\tilde{W}} = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 \\ -i\frac{1}{\sqrt{2}} & i\frac{1}{\sqrt{2}} & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad (78)$$

$$(79)$$

4.2 Rotations in Mass sector for eigenstates 'EWSB'

4.2.1 Mass Matrices for Scalars

- **Mass matrix for Higgs**, Basis: $(\phi_d, \phi_u), (\phi_d, \phi_u)$

$$m_h^2 = \begin{pmatrix} \frac{1}{8}(g_1^2 + g_2^2)(3v_d^2 - v_u^2) + m_{H_d}^2 + |\mu|^2 & -\frac{1}{4}(g_1^2 + g_2^2)v_d v_u - \Re(B_\mu) \\ -\frac{1}{4}(g_1^2 + g_2^2)v_d v_u - \Re(B_\mu) & -\frac{1}{8}(g_1^2 + g_2^2)(-3v_u^2 + v_d^2) + m_{H_u}^2 + |\mu|^2 \end{pmatrix} \quad (80)$$

This matrix is diagonalized by Z^H :

$$Z^H m_h^2 Z^{H,\dagger} = m_{2,h}^{dia} \quad (81)$$

with

$$\phi_d = \sum_j Z_{j1}^H h_j, \quad \phi_u = \sum_j Z_{j2}^H h_j \quad (82)$$

- **Mass matrix for Pseudo-Scalar Higgs**, Basis: $(\sigma_d, \sigma_u), (\sigma_d, \sigma_u)$

$$m_{A^0}^2 = \begin{pmatrix} \frac{1}{8}(g_1^2 + g_2^2)(-v_u^2 + v_d^2) + m_{H_d}^2 + |\mu|^2 & \Re(B_\mu) \\ \Re(B_\mu) & -\frac{1}{8}(g_1^2 + g_2^2)(-v_u^2 + v_d^2) + m_{H_u}^2 + |\mu|^2 \end{pmatrix} + \xi_Z m^2(Z) \quad (83)$$

Gauge fixing contributions:

$$m^2(\xi_Z) = \begin{pmatrix} \frac{1}{4}v_d^2(g_1 \sin \Theta_W + g_2 \cos \Theta_W)^2 & -\frac{1}{4}v_d v_u (g_1 \sin \Theta_W + g_2 \cos \Theta_W)^2 \\ -\frac{1}{4}v_d v_u (g_1 \sin \Theta_W + g_2 \cos \Theta_W)^2 & \frac{1}{4}v_u^2(g_1 \sin \Theta_W + g_2 \cos \Theta_W)^2 \end{pmatrix} \quad (84)$$

This matrix is diagonalized by Z^A :

$$Z^A m_{A^0}^2 Z^{A,\dagger} = m_{2,A^0}^{dia} \quad (85)$$

with

$$\sigma_d = \sum_j Z_{j1}^A A_j^0, \quad \sigma_u = \sum_j Z_{j2}^A A_j^0 \quad (86)$$

- **Mass matrix for Charged Higgs**, Basis: $(H_d^-, H_u^{+,*}), (H_d^{-,*}, H_u^+)$

$$m_{H^-}^2 = \begin{pmatrix} m_{H_d^- H_d^{-,*}} & \frac{1}{4}g_2^2 v_d v_u + B_\mu^* \\ \frac{1}{4}g_2^2 v_d v_u + B_\mu & m_{H_u^{+,*} H_u^+} \end{pmatrix} + \xi_{W^-} m^2(W^-) \quad (87)$$

$$m_{H_d^- H_d^{-,*}} = \frac{1}{8}(g_1^2(-v_u^2 + v_d^2) + g_2^2(v_d^2 + v_u^2)) + m_{H_d}^2 + |\mu|^2 \quad (88)$$

$$m_{H_u^{+,*} H_u^+} = \frac{1}{8}(g_1^2(-v_d^2 + v_u^2) + g_2^2(v_d^2 + v_u^2)) + m_{H_u}^2 + |\mu|^2 \quad (89)$$

Gauge fixing contributions:

$$m^2(\xi_{W^-}) = \begin{pmatrix} \frac{1}{4}g_2^2 v_d^2 & -\frac{1}{4}g_2^2 v_d v_u \\ -\frac{1}{4}g_2^2 v_d v_u & \frac{1}{4}g_2^2 v_u^2 \end{pmatrix} \quad (90)$$

This matrix is diagonalized by Z^+ :

$$Z^+ m_{H^-}^2 Z^{+,\dagger} = m_{2,H^-}^{dia} \quad (91)$$

with

$$H_d^- = \sum_j Z_{j1}^+ H_j^-, \quad H_u^+ = \sum_j Z_{j2}^+ H_j^+ \quad (92)$$

- **Mass matrix for Down-Squarks**, Basis: $(\tilde{d}_{L,\alpha_1}, \tilde{d}_{R,\alpha_2}), (\tilde{d}_{L,\beta_1}^*, \tilde{d}_{R,\beta_2}^*)$

$$m_{\tilde{d}}^2 = \begin{pmatrix} m_{\tilde{d}_L \tilde{d}_L^*} & \frac{1}{\sqrt{2}} \text{Delta} (v_d T_d^\dagger - v_u \mu Y_d^\dagger) \delta_{\alpha_1 \beta_2} \\ \frac{1}{\sqrt{2}} \text{Delta} \delta_{\alpha_2 \beta_1} (v_d T_d - v_u Y_d \mu^*) & m_{\tilde{d}_R \tilde{d}_R^*} \end{pmatrix} \quad (93)$$

$$m_{\tilde{d}_L \tilde{d}_L^*} = -\frac{1}{24} (3g_2^2 + g_1^2) \mathbf{1} (-v_u^2 + v_d^2) \delta_{\alpha_1 \beta_1} + \frac{1}{2} \mathbf{1} (2m_q^2 + v_d^2 Y_d Y_{d,o_1 o_1}^*) \delta_{\alpha_1 \beta_1} \quad (94)$$

$$m_{\tilde{d}_R \tilde{d}_R^*} = \frac{1}{12} g_1^2 \mathbf{1} (-v_d^2 + v_u^2) \delta_{\alpha_2 \beta_2} + \frac{1}{2} \mathbf{1} \delta_{\alpha_2 \beta_2} (2m_d^2 + v_d^2 Y_d^\dagger Y_{d,o_2 o_2}) \quad (95)$$

This matrix is diagonalized by Z^D :

$$Z^D m_{\tilde{d}}^2 Z^{D,\dagger} = m_{2,\tilde{d}}^{dia} \quad (96)$$

with

$$\tilde{d}_{L,i\alpha} = \sum_j Z_{ji}^{D,*} \tilde{d}_{j\text{ft}1\alpha}, \quad \tilde{d}_{R,i\alpha} = \sum_j Z_{ji}^{D,*} \tilde{d}_{j\text{ft}1\alpha} \quad (97)$$

- **Mass matrix for Up-Squarks**, Basis: $(\tilde{u}_{L,\alpha_1}, \tilde{u}_{R,\alpha_2}), (\tilde{u}_{L,\beta_1}^*, \tilde{u}_{R,\beta_2}^*)$

$$m_{\tilde{u}}^2 = \begin{pmatrix} m_{\tilde{u}_L \tilde{u}_L^*} & \frac{1}{\sqrt{2}} \text{Delta} (-v_d \mu Y_u^\dagger + v_u T_u^\dagger) \delta_{\alpha_1 \beta_2} \\ \frac{1}{\sqrt{2}} \text{Delta} \delta_{\alpha_2 \beta_1} (-v_d Y_u \mu^* + v_u T_u) & m_{\tilde{u}_R \tilde{u}_R^*} \end{pmatrix} \quad (98)$$

$$m_{\tilde{u}_L \tilde{u}_L^*} = -\frac{1}{24} (-3g_2^2 + g_1^2) \mathbf{1} (-v_u^2 + v_d^2) \delta_{\alpha_1 \beta_1} + \frac{1}{2} \mathbf{1} (2m_q^2 + v_u^2 Y_u Y_{u,o_1 o_1}^*) \delta_{\alpha_1 \beta_1} \quad (99)$$

$$m_{\tilde{u}_R \tilde{u}_R^*} = \frac{1}{2} \mathbf{1} \delta_{\alpha_2 \beta_2} (2m_u^2 + v_u^2 Y_u^\dagger Y_{u,o_2 o_2}) + \frac{1}{6} g_1^2 \mathbf{1} (-v_u^2 + v_d^2) \delta_{\alpha_2 \beta_2} \quad (100)$$

This matrix is diagonalized by Z^U :

$$Z^U m_{\tilde{u}}^2 Z^{U,\dagger} = m_{2,\tilde{u}}^{dia} \quad (101)$$

with

$$\tilde{u}_{L,i\alpha} = \sum_j Z_{ji}^{U,*} \tilde{u}_{j\text{ft}1\alpha}, \quad \tilde{u}_{R,i\alpha} = \sum_j Z_{ji}^{U,*} \tilde{u}_{j\text{ft}1\alpha} \quad (102)$$

- **Mass matrix for Sleptons**, Basis: $(\tilde{e}_L, \tilde{e}_R), (\tilde{e}_L^*, \tilde{e}_R^*)$

$$m_{\tilde{e}}^2 = \begin{pmatrix} m_{\tilde{e}_L \tilde{e}_L^*} & \frac{1}{\sqrt{2}} \text{Delta} (v_d T_e^\dagger - v_u \mu Y_e^\dagger) \\ \frac{1}{\sqrt{2}} \text{Delta} (v_d T_e - v_u Y_e \mu^*) & m_{\tilde{e}_R \tilde{e}_R^*} \end{pmatrix} \quad (103)$$

$$m_{\tilde{e}_L \tilde{e}_L^*} = \frac{1}{2} \mathbf{1} (2m_l^2 + v_d^2 Y_e Y_{e,o_1 o_1}^*) + \frac{1}{8} (-g_2^2 + g_1^2) \mathbf{1} (-v_u^2 + v_d^2) \quad (104)$$

$$m_{\tilde{e}_R \tilde{e}_R^*} = \frac{1}{2} \mathbf{1} \left(2m_e^2 + v_d^2 Y_e^\dagger Y_{e, o_2 o_2} \right) + \frac{1}{4} g_1^2 \mathbf{1} \left(-v_d^2 + v_u^2 \right) \quad (105)$$

This matrix is diagonalized by Z^E :

$$Z^E m_{\tilde{e}}^2 Z^{E, \dagger} = m_{2, \tilde{e}}^{dia} \quad (106)$$

with

$$\tilde{e}_{L, i} = \sum_j Z_{ji}^{E, *} \tilde{e}_{jft1}, \quad \tilde{e}_{R, i} = \sum_j Z_{ji}^{E, *} \tilde{e}_{jft1} \quad (107)$$

4.2.2 Mass Matrices for Fermions

- **Mass matrix for Neutralinos**, Basis: $(\lambda_{\tilde{B}}, \tilde{W}^0, \tilde{H}_d^0, \tilde{H}_u^0), (\lambda_{\tilde{B}}, \tilde{W}^0, \tilde{H}_d^0, \tilde{H}_u^0)$

$$m_{\tilde{\chi}^0} = \begin{pmatrix} M_1 & 0 & -\frac{1}{2} g_1 v_d & \frac{1}{2} g_1 v_u \\ 0 & M_2 & \frac{1}{2} g_2 v_d & -\frac{1}{2} g_2 v_u \\ -\frac{1}{2} g_1 v_d & \frac{1}{2} g_2 v_d & 0 & -\mu \\ \frac{1}{2} g_1 v_u & -\frac{1}{2} g_2 v_u & -\mu & 0 \end{pmatrix} \quad (108)$$

This matrix is diagonalized by N :

$$N^* m_{\tilde{\chi}^0} N^\dagger = m_{\tilde{\chi}^0}^{dia} \quad (109)$$

with

$$\lambda_{\tilde{B}} = \sum_j N_{j1}^* \lambda_j^0, \quad \tilde{W}^0 = \sum_j N_{j2}^* \lambda_j^0, \quad \tilde{H}_d^0 = \sum_j N_{j3}^* \lambda_j^0 \quad (110)$$

$$\tilde{H}_u^0 = \sum_j N_{j4}^* \lambda_j^0 \quad (111)$$

- **Mass matrix for Charginos**, Basis: $(\tilde{W}^-, \tilde{H}_d^-), (\tilde{W}^+, \tilde{H}_u^+)$

$$m_{\tilde{\chi}^\pm} = \begin{pmatrix} M_2 & \frac{1}{\sqrt{2}} g_2 v_u \\ \frac{1}{\sqrt{2}} g_2 v_d & \mu \end{pmatrix} \quad (112)$$

This matrix is diagonalized by U and V

$$U^* m_{\tilde{\chi}^\pm} V^\dagger = m_{\tilde{\chi}^\pm}^{dia} \quad (113)$$

with

$$\tilde{W}^- = \sum_{t_2} U_{j1}^* \lambda_j^-, \quad \tilde{H}_d^- = \sum_{t_2} U_{j2}^* \lambda_j^- \quad (114)$$

$$\tilde{W}^+ = \sum_{t_2} V_{1j}^* \lambda_j^+, \quad \tilde{H}_u^+ = \sum_{t_2} V_{2j}^* \lambda_j^+ \quad (115)$$

5 Vacuum Expectation Values

$$H_d^0 = \frac{1}{\sqrt{2}}\phi_d + \frac{1}{\sqrt{2}}v_d + i\frac{1}{\sqrt{2}}\sigma_d \quad (116)$$

$$H_u^0 = \frac{1}{\sqrt{2}}\phi_u + \frac{1}{\sqrt{2}}v_u + i\frac{1}{\sqrt{2}}\sigma_u \quad (117)$$

6 Tadpole Equations

$$\frac{\partial V}{\partial \phi_d} = -\frac{1}{2}v_u(B_\mu + B_\mu^*) + \frac{1}{8}(g_1^2 + g_2^2)v_d(-v_u + v_d)(v_d + v_u) + v_d(m_{H_d}^2 + |\mu|^2) \quad (118)$$

$$\frac{\partial V}{\partial \phi_u} = \frac{1}{8}(g_1^2 + g_2^2)v_u(-v_d^2 + v_u^2) - v_d\Re(B_\mu) + v_u(m_{H_u}^2 + |\mu|^2) \quad (119)$$

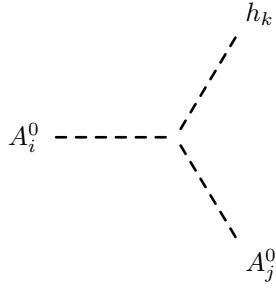
7 Particle content for eigenstates 'EWSB'

Name	Type	complex/real	Generations	Indices
$\tilde{\nu}_L$	Scalar	complex	3	generation, 3
h	Scalar	real	2	generation, 2
A^0	Scalar	real	2	generation, 2
H^-	Scalar	complex	2	generation, 2
\tilde{d}	Scalar	complex	3	generation, 3, flavor, 2, color, 3
\tilde{u}	Scalar	complex	3	generation, 3, flavor, 2, color, 3
\tilde{e}	Scalar	complex	3	generation, 3, flavor, 2
\tilde{g}	Fermion	Majorana	1	color, 8
d	Fermion	Dirac	3	generation, 3, color, 3
u	Fermion	Dirac	3	generation, 3, color, 3
e	Fermion	Dirac	3	generation, 3
ν	Fermion	Dirac	3	generation, 3
$\tilde{\chi}^0$	Fermion	Majorana	4	generation, 4
$\tilde{\chi}^-$	Fermion	Dirac	2	generation, 2
g	Vector	real	1	color, 8, lorentz, 4
γ	Vector	real	1	lorentz, 4
Z	Vector	real	1	lorentz, 4
W^-	Vector	complex	1	lorentz, 4
η^G	Ghost	real	1	color, 8

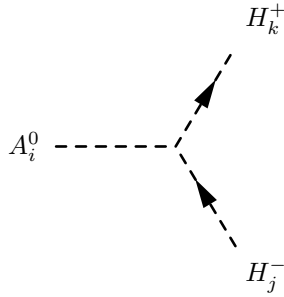
η^γ	Ghost	real	1
η^Z	Ghost	real	1
η^-	Ghost	complex	1
η^+	Ghost	complex	1

8 Interactions for eigenstates 'EWSB'

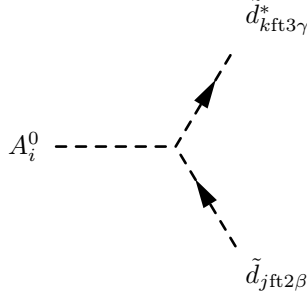
8.1 Three Scalar-Interaction



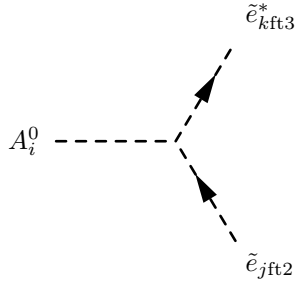
$$-\frac{i}{4}(g_1^2 + g_2^2)(Z_{i1}^A Z_{j1}^A - Z_{i2}^A Z_{j2}^A)(v_d Z_{k1}^H - v_u Z_{k2}^H) \quad (120)$$



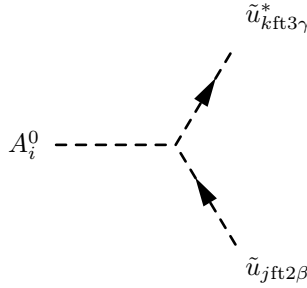
$$\frac{1}{4}g_2^2(v_d Z_{i2}^A + v_u Z_{i1}^A)(-Z_{j1}^+ Z_{k2}^+ + Z_{j2}^+ Z_{k1}^+) \quad (121)$$



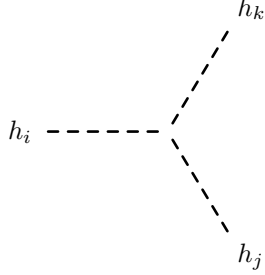
$$-\frac{1}{\sqrt{2}}\delta_{\beta\gamma}\delta_{jk}\left(\mu Y_{d,jk}^*\text{conj}\left(\text{ZD}\left(\text{gt2}\right)\left(\text{ft2},2\right)\right)Z_{i2}^A\text{ZD}\left(\text{gt3}\right)\left(\text{ft3},1\right)+T_{d,jk}^*\text{conj}\left(\text{ZD}\left(\text{gt2}\right)\left(\text{ft2},2\right)\right)Z_{i1}^A\text{ZD}\left(\text{gt3}\right)\left(\text{ft3},1\right)-\text{conj}\left(\text{ZD}\left(\text{gt2}\right)\left(\text{ft2},2\right)\right)Z_{i2}^AZ_{i1}^A\right) \quad (122)$$



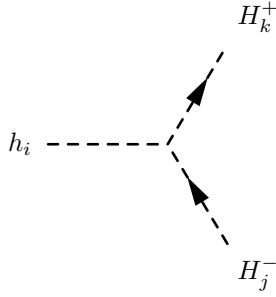
$$-\frac{1}{\sqrt{2}}\delta_{jk}\left(\mu Y_{e,jk}^*\text{conj}\left(\text{ZE}\left(\text{gt2}\right)\left(\text{ft2},2\right)\right)Z_{i2}^AZ_{i1}^A\text{ZE}\left(\text{gt3}\right)\left(\text{ft3},1\right)+T_{e,jk}^*\text{conj}\left(\text{ZE}\left(\text{gt2}\right)\left(\text{ft2},2\right)\right)Z_{i1}^AZ_{i2}^A\text{ZE}\left(\text{gt3}\right)\left(\text{ft3},1\right)-\text{conj}\left(\text{ZE}\left(\text{gt2}\right)\left(\text{ft2},2\right)\right)Z_{i2}^AZ_{i1}^AZ_{i1}^AZ_{i2}^A\right) \quad (123)$$



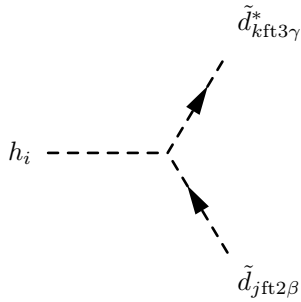
$$-\frac{1}{\sqrt{2}}\delta_{\beta\gamma}\delta_{jk}\left(\mu Y_{u,jk}^*\text{conj}\left(\text{ZU}\left(\text{gt2}\right)\left(\text{ft2},2\right)\right)Z_{i1}^AZ_{i2}^AZ_{i1}^AZ_{i2}^A\text{ZU}\left(\text{gt3}\right)\left(\text{ft3},1\right)-\text{conj}\left(\text{ZU}\left(\text{gt2}\right)\left(\text{ft2},1\right)\right)\left(\mu^*Y_{u,kj}Z_{i1}^AZ_{i2}^AZ_{i1}^AZ_{i2}^A+Z_{i2}^AZ_{i1}^AZ_{i2}^AZ_{i1}^A\right)\text{ZU}\left(\text{gt3}\right)\left(\text{ft3},2\right)\right) \quad (124)$$



$$\begin{aligned}
& \frac{i}{4} (g_1^2 + g_2^2) \left(Z_{i2}^H \left(Z_{j1}^H (v_d Z_{k2}^H + v_u Z_{k1}^H) + Z_{j2}^H (-3v_u Z_{k2}^H + v_d Z_{k1}^H) \right) \right. \\
& \left. + Z_{i1}^H \left(Z_{j1}^H (-3v_d Z_{k1}^H + v_u Z_{k2}^H) + Z_{j2}^H (v_d Z_{k2}^H + v_u Z_{k1}^H) \right) \right)
\end{aligned} \tag{125}$$

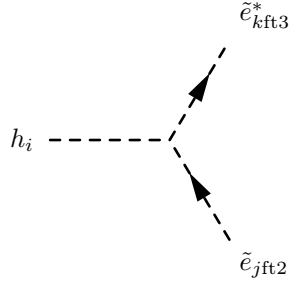


$$\begin{aligned}
& \frac{i}{4} \left(-Z_{i1}^H \left(Z_{j1}^+ \left((g_1^2 + g_2^2) v_d Z_{k1}^+ + g_2^2 v_u Z_{k2}^+ \right) + Z_{j2}^+ \left((-g_1^2 + g_2^2) v_d Z_{k2}^+ + g_2^2 v_u Z_{k1}^+ \right) \right) \right. \\
& \left. + Z_{i2}^H \left(Z_{j1}^+ \left((-g_2^2 + g_1^2) v_u Z_{k1}^+ - g_2^2 v_d Z_{k2}^+ \right) - Z_{j2}^+ \left((g_1^2 + g_2^2) v_u Z_{k2}^+ + g_2^2 v_d Z_{k1}^+ \right) \right) \right)
\end{aligned} \tag{126}$$

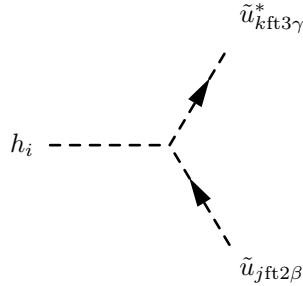


$$\frac{i}{12} \delta_{\beta\gamma} \delta_{jk} \left(-2 \text{conj} \left(\text{ZD}(\text{gt}2) (\text{ft}2, 2) \right) \left(-3\sqrt{2} \mu Y_{d,jk}^* Z_{i2}^H \text{ZD}(\text{gt}3) (\text{ft}3, 1) + 3\sqrt{2} T_{d,jk}^* Z_{i1}^H \text{ZD}(\text{gt}3) (\text{ft}3, 1) + (g_1^2 v_u Z_{i2}^H - v_d (-6Y_{d,jk}^* \right. \right.$$

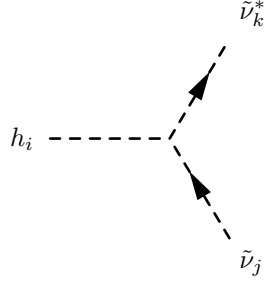
$$\begin{aligned}
& + \text{conj}\left(\text{ZD}(\text{gt}2)(\text{ft}2, 1)\right)\left(-Z_{i2}^H\left((3g_2^2 + g_1^2)v_u\text{ZD}(\text{gt}3)(\text{ft}3, 1) - 6\sqrt{2}\mu^*Y_{d,kj}\text{ZD}(\text{gt}3)(\text{ft}3, 2)\right)\right. \\
& \left.+ Z_{i1}^H\left(-6\sqrt{2}T_{d,kj}\text{ZD}(\text{gt}3)(\text{ft}3, 2) + v_d\left(-12Y_{d,jk}^*Y_{d,jj} + 3g_2^2 + g_1^2\right)\text{ZD}(\text{gt}3)(\text{ft}3, 1)\right)\right)
\end{aligned} \tag{127}$$



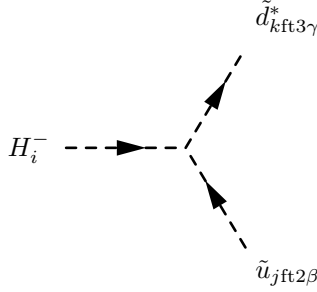
$$\begin{aligned}
& - \frac{i}{4}\delta_{jk}\left(2\text{conj}\left(\text{ZE}(\text{gt}2)(\text{ft}2, 2)\right)\left(\left(g_1^2v_uZ_{i2}^H - v_d\left(-2Y_{e,jj}^*Y_{e,kj} + g_1^2\right)Z_{i1}^H\right)\text{ZE}(\text{gt}3)(\text{ft}3, 2) - \sqrt{2}\mu Y_{e,jk}^*Z_{i2}^H\text{ZE}(\text{gt}3)(\text{ft}3, 1) + \sqrt{2}T_{e,kj}\right.\right. \\
& \left.\left.+ \text{conj}\left(\text{ZE}(\text{gt}2)(\text{ft}2, 1)\right)\left(Z_{i2}^H\left(-2\sqrt{2}\mu^*Y_{e,kj}\text{ZE}(\text{gt}3)(\text{ft}3, 2) + \left(-g_1^2 + g_2^2\right)v_u\text{ZE}(\text{gt}3)(\text{ft}3, 1)\right)\right.\right. \\
& \left.\left.+ Z_{i1}^H\left(2\sqrt{2}T_{e,kj}\text{ZE}(\text{gt}3)(\text{ft}3, 2) + v_d\left(4Y_{e,jk}^*Y_{e,jj} - g_2^2 + g_1^2\right)\text{ZE}(\text{gt}3)(\text{ft}3, 1)\right)\right)\right)
\end{aligned} \tag{128}$$



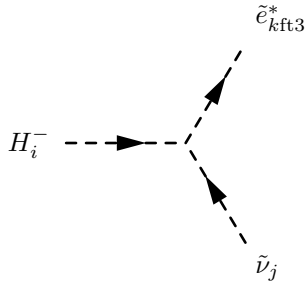
$$\begin{aligned}
& \frac{i}{12}\delta_{\beta\gamma}\delta_{jk}\left(2\text{conj}\left(\text{ZU}(\text{gt}2)(\text{ft}2, 2)\right)\left(-2\left(g_1^2v_dZ_{i1}^H - v_u\left(-3Y_{u,jj}^*Y_{u,kj} + g_1^2\right)Z_{i2}^H\right)\text{ZU}(\text{gt}3)(\text{ft}3, 2) + 3\sqrt{2}\mu Y_{u,jk}^*Z_{i1}^H\text{ZU}(\text{gt}3)(\text{ft}3, 1)\right.\right. \\
& \left.\left.+ \text{conj}\left(\text{ZU}(\text{gt}2)(\text{ft}2, 1)\right)\left(Z_{i1}^H\left(\left(-3g_2^2 + g_1^2\right)v_d\text{ZU}(\text{gt}3)(\text{ft}3, 1) + 6\sqrt{2}\mu^*Y_{u,kj}\text{ZU}(\text{gt}3)(\text{ft}3, 2)\right)\right.\right. \\
& \left.\left.- Z_{i2}^H\left(6\sqrt{2}T_{u,kj}\text{ZU}(\text{gt}3)(\text{ft}3, 2) + v_u\left(12Y_{u,jk}^*Y_{u,jj} - 3g_2^2 + g_1^2\right)\text{ZU}(\text{gt}3)(\text{ft}3, 1)\right)\right)\right)
\end{aligned} \tag{129}$$



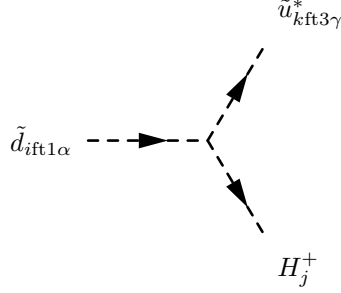
$$-\frac{i}{4}(g_1^2 + g_2^2)\delta_{jk}(v_d Z_{i1}^H - v_u Z_{i2}^H) \quad (130)$$



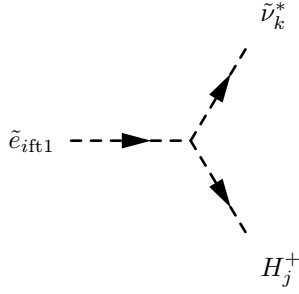
$$\begin{aligned} & -\frac{i}{4}\delta_{\beta\gamma}\delta_{jk}\left(-2\text{conj}\left(\text{ZU}\left(\text{gt}2\right)\left(\text{ft}2,2\right)\right)\left(2\mu Y_{u,jk}^* Z_{i1}^+ \text{ZD}\left(\text{gt}3\right)\left(\text{ft}3,1\right) + 2T_{u,jk}^* Z_{i2}^+ \text{ZD}\left(\text{gt}3\right)\left(\text{ft}3,1\right) + \sqrt{2}Y_{u,jj}^* Y_{d,kj}\left(v_d Z_{i2}^+ + v_u Z_{i1}^+\right)\text{ZD}\left(\text{gt}3\right)\left(\text{ft}3,1\right)\right) \right. \\ & + \text{conj}\left(\text{ZU}\left(\text{gt}2\right)\left(\text{ft}2,1\right)\right)\left(Z_{i2}^+\left(-4\mu^* Y_{d,kj}\text{ZD}\left(\text{gt}3\right)\left(\text{ft}3,2\right) + \sqrt{2}v_u\left(-2Y_{u,jk}^* Y_{u,jj} + g_2^2\right)\text{ZD}\left(\text{gt}3\right)\left(\text{ft}3,1\right)\right)\right) \\ & \left. + Z_{i1}^+\left(-4T_{d,kj}\text{ZD}\left(\text{gt}3\right)\left(\text{ft}3,2\right) + \sqrt{2}v_d\left(-2Y_{d,jk}^* Y_{d,jj} + g_2^2\right)\text{ZD}\left(\text{gt}3\right)\left(\text{ft}3,1\right)\right)\right) \end{aligned} \quad (131)$$



$$-\frac{i}{4}\delta_{jk}\left(Z_{i1}^+\left(-4T_{e,kj}\text{ZE}\left(\text{gt}3\right)\left(\text{ft}3,2\right) + \sqrt{2}v_d\left(-2Y_{e,jk}^* Y_{e,jj} + g_2^2\right)\text{ZE}\left(\text{gt}3\right)\left(\text{ft}3,1\right)\right) + Z_{i2}^+\left(-4\mu^* Y_{e,kj}\text{ZE}\left(\text{gt}3\right)\left(\text{ft}3,2\right) + \sqrt{2}g_2^2 v_u\right)\right) \quad (132)$$

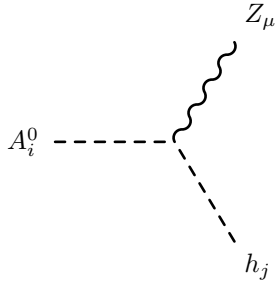


$$\begin{aligned}
& -\frac{i}{4}\delta_{\alpha\gamma}\delta_{ik}\left(-2\text{conj}\left(\text{ZD}\left(\text{gt1}\right)\left(\text{ft1},2\right)\right)\left(2\mu Y_{d,ik}^*Z_{j2}^+Z\text{U}\left(\text{gt3}\right)\left(\text{ft3},1\right)+2T_{d,ik}^*Z_{j1}^+Z\text{U}\left(\text{gt3}\right)\left(\text{ft3},1\right)+\sqrt{2}Y_{d,ii}^*Y_{u,ki}\left(v_dZ_{j2}^++v_uZ_{j1}^+\right)Z\text{U}\left(\text{gt3}\right)\left(\text{ft3},1\right)\right)\right. \\
& +\text{conj}\left(\text{ZD}\left(\text{gt1}\right)\left(\text{ft1},1\right)\right)\left(Z_{j1}^+\left(-4\mu^*Y_{u,ki}Z\text{U}\left(\text{gt3}\right)\left(\text{ft3},2\right)+\sqrt{2}v_d\left(-2Y_{d,ik}^*Y_{d,ii}+g_2^2\right)Z\text{U}\left(\text{gt3}\right)\left(\text{ft3},1\right)\right)\right. \\
& \left.\left.+Z_{j2}^+\left(-4T_{u,ki}Z\text{U}\left(\text{gt3}\right)\left(\text{ft3},2\right)+\sqrt{2}v_u\left(-2Y_{u,ik}^*Y_{u,ii}+g_2^2\right)Z\text{U}\left(\text{gt3}\right)\left(\text{ft3},1\right)\right)\right)\right) \quad (133)
\end{aligned}$$

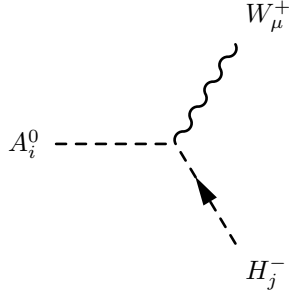


$$-\frac{i}{4}\delta_{ik}\left(-4\text{conj}\left(\text{ZE}\left(\text{gt1}\right)\left(\text{ft1},2\right)\right)\left(\mu Y_{e,ik}^*Z_{j2}^++T_{e,ik}^*Z_{j1}^+\right)+\sqrt{2}\text{conj}\left(\text{ZE}\left(\text{gt1}\right)\left(\text{ft1},1\right)\right)\left(g_2^2v_uZ_{j2}^++v_d\left(-2Y_{e,ik}^*Y_{e,ii}+g_2^2\right)Z_{j1}^+\right)\right) \quad (134)$$

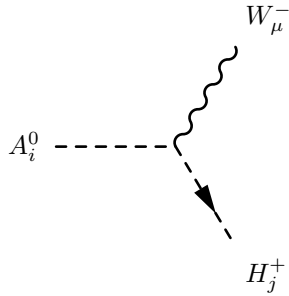
8.2 Two Scalar-One Vector Boson-Interaction



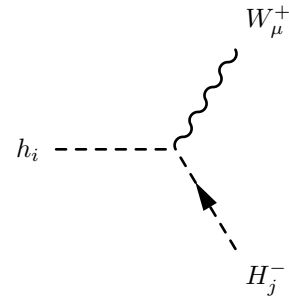
$$\frac{1}{2} \left(g_1 \sin \Theta_W + g_2 \cos \Theta_W \right) \left(Z_{i1}^A Z_{j1}^H - Z_{i2}^A Z_{j2}^H \right) \left(-p_\mu^{h_j} + p_\mu^{A_i^0} \right) \quad (135)$$



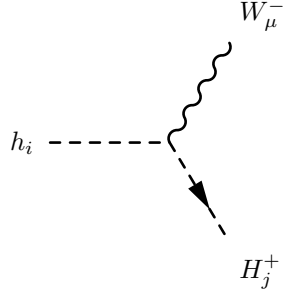
$$\frac{1}{2} g_2 \left(Z_{i1}^A Z_{j1}^+ + Z_{i2}^A Z_{j2}^+ \right) \left(-p_\mu^{H_j^-} + p_\mu^{A_i^0} \right) \quad (136)$$



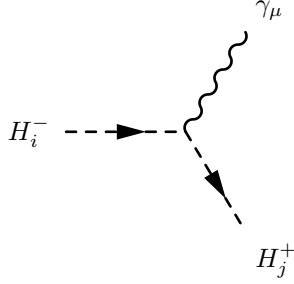
$$\frac{1}{2} g_2 \left(Z_{i1}^A Z_{j1}^+ + Z_{i2}^A Z_{j2}^+ \right) \left(-p_\mu^{H_j^+} + p_\mu^{A_i^0} \right) \quad (137)$$



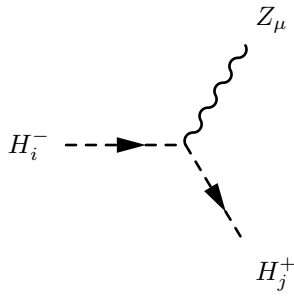
$$\frac{i}{2} g_2 \left(Z_{i1}^H Z_{j1}^+ - Z_{i2}^H Z_{j2}^+ \right) \left(-p_\mu^{H_j^-} + p_\mu^{h_i} \right) \quad (138)$$



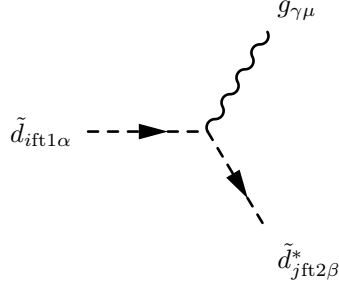
$$-\frac{i}{2}g_2\left(Z_{i1}^H Z_{j1}^+ - Z_{i2}^H Z_{j2}^+\right)\left(-p_\mu^{H_j^+} + p_\mu^{h_i}\right) \quad (139)$$



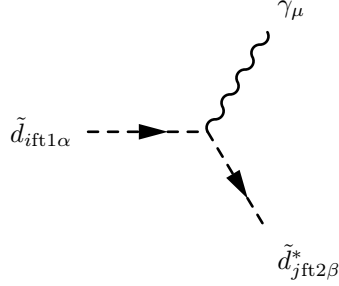
$$\frac{i}{2}\delta_{ij}\left(g_1 \cos \Theta_W + g_2 \sin \Theta_W\right)\left(-p_\mu^{H_j^+} + p_\mu^{H_i^-}\right) \quad (140)$$



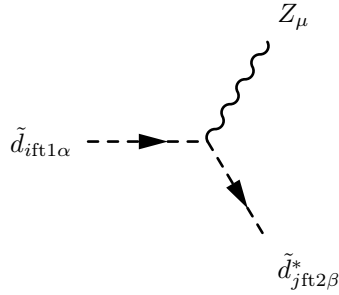
$$\frac{i}{2}\delta_{ij}\left(-g_1 \sin \Theta_W + g_2 \cos \Theta_W\right)\left(-p_\mu^{H_j^+} + p_\mu^{H_i^-}\right) \quad (141)$$



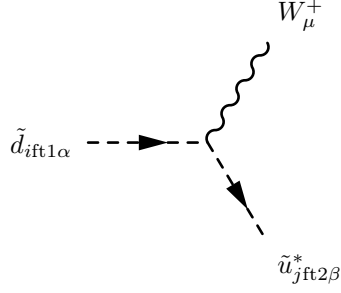
$$-\frac{i}{2}g_3\delta_{ft1ft2}\delta_{ij}\lambda_{\beta,\alpha}^\gamma\left(-p_\mu^{\tilde{d}_{jft2\beta}^*}+p_\mu^{\tilde{d}_{ift1\alpha}}\right) \quad (142)$$



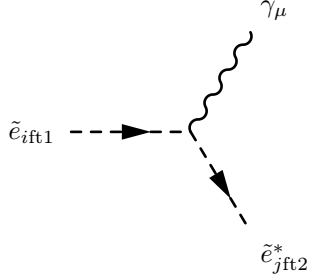
$$-\frac{i}{6}\delta_{\alpha\beta}\delta_{ij}\left(-2g_1\text{conj}\left(\text{ZD}\left(\text{gt1}\right)\left(\text{ft1},2\right)\right)\cos\Theta_W\text{ZD}\left(\text{gt2}\right)\left(\text{ft2},2\right)+\text{conj}\left(\text{ZD}\left(\text{gt1}\right)\left(\text{ft1},1\right)\right)\left(-3g_2\sin\Theta_W+g_1\cos\Theta_W\right)\text{ZD}\left(\text{gt2}\right)\left(\text{ft2},1\right)\right) \quad (143)$$



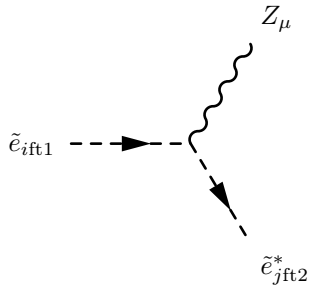
$$\frac{i}{6}\delta_{\alpha\beta}\delta_{ij}\left(-2g_1\text{conj}\left(\text{ZD}\left(\text{gt1}\right)\left(\text{ft1},2\right)\right)\sin\Theta_W\text{ZD}\left(\text{gt2}\right)\left(\text{ft2},2\right)+\text{conj}\left(\text{ZD}\left(\text{gt1}\right)\left(\text{ft1},1\right)\right)\left(3g_2\cos\Theta_W+g_1\sin\Theta_W\right)\text{ZD}\left(\text{gt2}\right)\left(\text{ft2},1\right)\right) \quad (144)$$



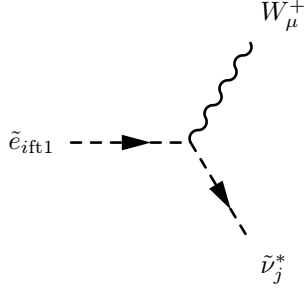
$$-i \frac{1}{\sqrt{2}} g_2 \text{conj} \left(\text{ZD}(\text{gt1}) \left(\text{ft1}, 1 \right) \right) \delta_{\alpha\beta} \delta_{ij} \text{ZU}(\text{gt2}) \left(\text{ft2}, 1 \right) \left(-p_\mu^{\tilde{u}_{jft2\beta}^*} + p_\mu^{\tilde{d}_{ift1\alpha}} \right) \quad (145)$$



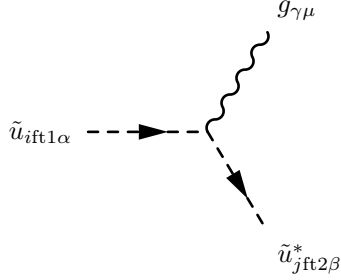
$$\frac{i}{2} \delta_{ij} \left(2g_1 \text{conj} \left(\text{ZE}(\text{gt1}) \left(\text{ft1}, 2 \right) \right) \cos \Theta_W \text{ZE}(\text{gt2}) \left(\text{ft2}, 2 \right) + \text{conj} \left(\text{ZE}(\text{gt1}) \left(\text{ft1}, 1 \right) \right) \left(g_1 \cos \Theta_W + g_2 \sin \Theta_W \right) \text{ZE}(\text{gt2}) \left(\text{ft2}, 1 \right) \right) \left(-p_\mu^{\tilde{e}_{jft2}^*} + p_\mu^{\tilde{e}_{ift1}} \right) \quad (146)$$



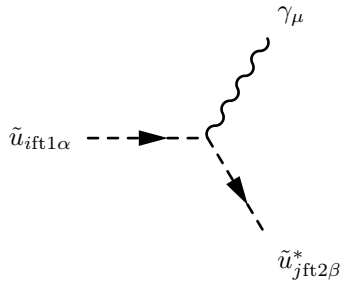
$$\frac{i}{2} \delta_{ij} \left(-2g_1 \text{conj} \left(\text{ZE}(\text{gt1}) \left(\text{ft1}, 2 \right) \right) \sin \Theta_W \text{ZE}(\text{gt2}) \left(\text{ft2}, 2 \right) + \text{conj} \left(\text{ZE}(\text{gt1}) \left(\text{ft1}, 1 \right) \right) \left(-g_1 \sin \Theta_W + g_2 \cos \Theta_W \right) \text{ZE}(\text{gt2}) \left(\text{ft2}, 1 \right) \right) \left(-p_\mu^{\tilde{e}_{jft2}^*} + p_\mu^{\tilde{e}_{ift1}} \right) \quad (147)$$



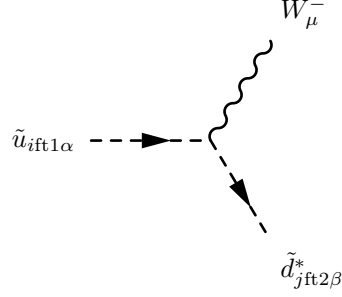
$$-i \frac{1}{\sqrt{2}} g_2 \text{conj} \left(\text{ZE}(\text{gt1}) \left(\text{ft1}, 1 \right) \right) \delta_{ij} \left(-p_\mu^{\tilde{\nu}_j^*} + p_\mu^{\tilde{e}_{ift1}} \right) \quad (148)$$



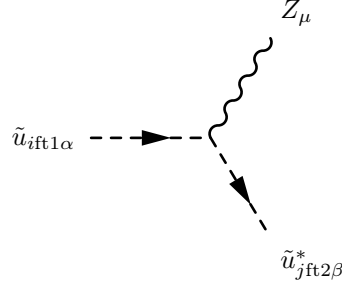
$$-\frac{i}{2} g_3 \delta_{\text{ft1ft2}} \delta_{ij} \lambda_{\beta,\alpha}^\gamma \left(-p_\mu^{\tilde{u}_{jft2\beta}^*} + p_\mu^{\tilde{u}_{ift1\alpha}} \right) \quad (149)$$



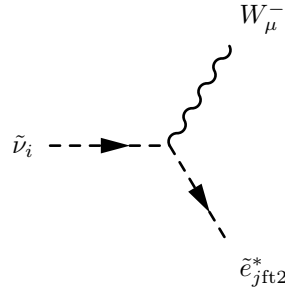
$$-\frac{i}{6} \delta_{\alpha\beta} \delta_{ij} \left(4g_1 \text{conj} \left(\text{ZU}(\text{gt1}) \left(\text{ft1}, 2 \right) \right) \cos \Theta_W \text{ZU}(\text{gt2}) \left(\text{ft2}, 2 \right) + \text{conj} \left(\text{ZU}(\text{gt1}) \left(\text{ft1}, 1 \right) \right) \left(3g_2 \sin \Theta_W + g_1 \cos \Theta_W \right) \text{ZU}(\text{gt2}) \left(\text{ft2}, 1 \right) \right) \quad (150)$$



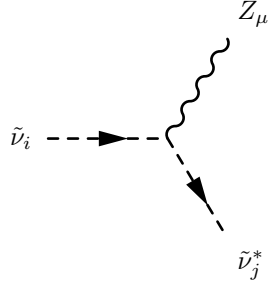
$$-i \frac{1}{\sqrt{2}} g_2 \text{conj} \left(\text{ZU}(\text{gt1}) (\text{ft1}, 1) \right) \delta_{\alpha\beta} \delta_{ij} \text{ZD}(\text{gt2}) (\text{ft2}, 1) \left(-p_\mu^{\tilde{d}_{jft2\beta}^*} + p_\mu^{\tilde{u}_{ift1\alpha}} \right) \quad (151)$$



$$-\frac{i}{6} \delta_{\alpha\beta} \delta_{ij} \left(-4g_1 \text{conj} \left(\text{ZU}(\text{gt1}) (\text{ft1}, 2) \right) \sin \Theta_W \text{ZU}(\text{gt2}) (\text{ft2}, 2) + \text{conj} \left(\text{ZU}(\text{gt1}) (\text{ft1}, 1) \right) \left(3g_2 \cos \Theta_W - g_1 \sin \Theta_W \right) \text{ZU}(\text{gt2}) (\text{ft2}, 1) \right) \quad (152)$$

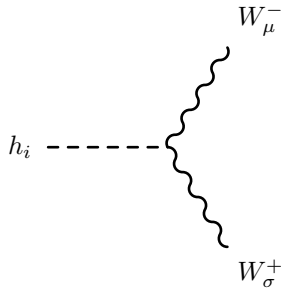


$$-i \frac{1}{\sqrt{2}} g_2 \delta_{ij} \text{ZE}(\text{gt2}) (\text{ft2}, 1) \left(-p_\mu^{\tilde{e}_{jft2}^*} + p_\mu^{\tilde{\nu}_i} \right) \quad (153)$$

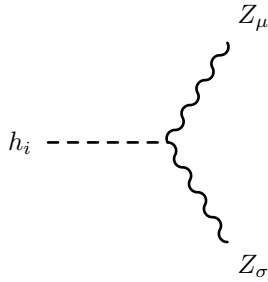


$$-\frac{i}{2}\delta_{ij}(g_1 \sin \Theta_W + g_2 \cos \Theta_W)(-p_\mu^{\tilde{\nu}_j^*} + p_\mu^{\tilde{\nu}_i}) \quad (154)$$

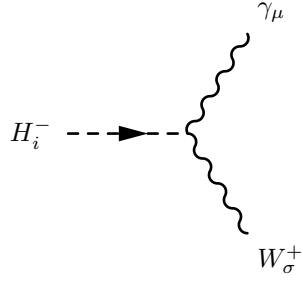
8.3 One Scalar-Two Vector Boson-Interaction



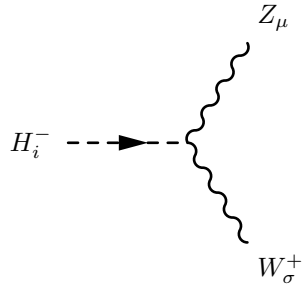
$$\frac{i}{2}g_2^2(v_d Z_{i1}^H + v_u Z_{i2}^H)(g_{\sigma\mu}) \quad (155)$$



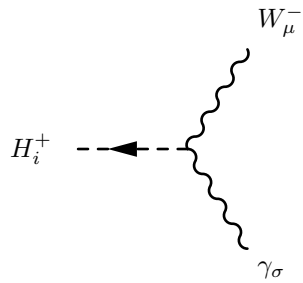
$$\frac{i}{2}(g_1 \sin \Theta_W + g_2 \cos \Theta_W)^2(v_d Z_{i1}^H + v_u Z_{i2}^H)(g_{\sigma\mu}) \quad (156)$$



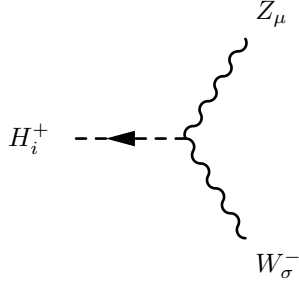
$$-\frac{i}{2}g_1g_2\cos\Theta_W\left(v_dZ_{i1}^+ - v_uZ_{i2}^+\right)\left(g_{\sigma\mu}\right) \quad (157)$$



$$\frac{i}{2}g_1g_2\sin\Theta_W\left(v_dZ_{i1}^+ - v_uZ_{i2}^+\right)\left(g_{\sigma\mu}\right) \quad (158)$$

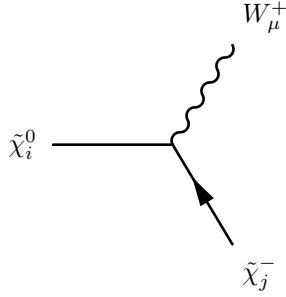


$$-\frac{i}{2}g_1g_2\cos\Theta_W\left(v_dZ_{i1}^+ - v_uZ_{i2}^+\right)\left(g_{\sigma\mu}\right) \quad (159)$$



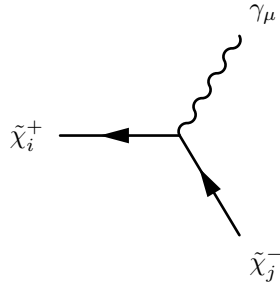
$$\frac{i}{2} g_1 g_2 \sin \Theta_W (v_d Z_{i1}^+ - v_u Z_{i2}^+) (g_{\sigma\mu}) \quad (160)$$

8.4 Two Fermion-One Vector Boson-Interaction



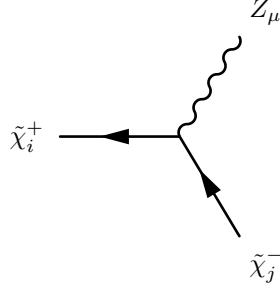
$$-\frac{i}{2} g_2 (2U_{j1}^* N_{i2} + \sqrt{2} U_{j2}^* N_{i3}) \left(\gamma_\mu \cdot \frac{1 - \gamma_5}{2} \right) \quad (161)$$

$$+\frac{i}{2} g_2 (2N_{i2}^* V_{j1} - \sqrt{2} N_{i4}^* V_{j2}) \left(\gamma_\mu \cdot \frac{1 + \gamma_5}{2} \right) \quad (162)$$



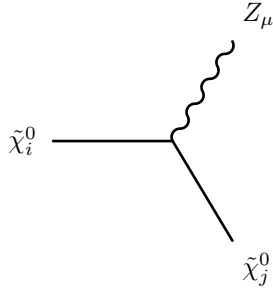
$$\frac{i}{2} \left(2g_2 U_{j1}^* \sin \Theta_W U_{i1} + U_{j2}^* (g_1 \cos \Theta_W + g_2 \sin \Theta_W) U_{i2} \right) \left(\gamma_\mu \cdot \frac{1 - \gamma_5}{2} \right) \quad (163)$$

$$+\frac{i}{2} \left(2g_2 V_{i1}^* \sin \Theta_W V_{j1} + V_{i2}^* (g_1 \cos \Theta_W + g_2 \sin \Theta_W) V_{j2} \right) \left(\gamma_\mu \cdot \frac{1 + \gamma_5}{2} \right) \quad (164)$$



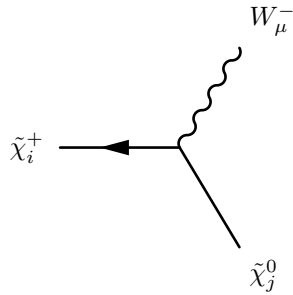
$$\frac{i}{2} \left(2g_2 U_{j1}^* \cos \Theta_W U_{i1} + U_{j2}^* \left(-g_1 \sin \Theta_W + g_2 \cos \Theta_W \right) U_{i2} \right) \left(\gamma_\mu \cdot \frac{1 - \gamma_5}{2} \right) \quad (165)$$

$$+ \frac{i}{2} \left(2g_2 V_{i1}^* \cos \Theta_W V_{j1} + V_{i2}^* \left(-g_1 \sin \Theta_W + g_2 \cos \Theta_W \right) V_{j2} \right) \left(\gamma_\mu \cdot \frac{1 + \gamma_5}{2} \right) \quad (166)$$



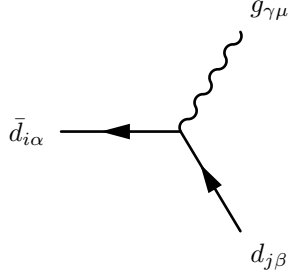
$$- \frac{i}{2} \left(g_1 \sin \Theta_W + g_2 \cos \Theta_W \right) \left(N_{j3}^* N_{i3} - N_{j4}^* N_{i4} \right) \left(\gamma_\mu \cdot \frac{1 - \gamma_5}{2} \right) \quad (167)$$

$$+ \frac{i}{2} \left(g_1 \sin \Theta_W + g_2 \cos \Theta_W \right) \left(N_{i3}^* N_{j3} - N_{i4}^* N_{j4} \right) \left(\gamma_\mu \cdot \frac{1 + \gamma_5}{2} \right) \quad (168)$$



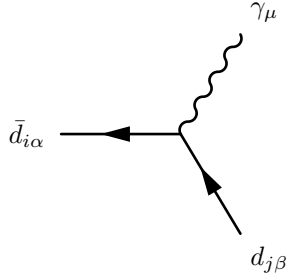
$$- \frac{i}{2} g_2 \left(2N_{j2}^* U_{i1} + \sqrt{2} N_{j3}^* U_{i2} \right) \left(\gamma_\mu \cdot \frac{1 - \gamma_5}{2} \right) \quad (169)$$

$$+ - \frac{i}{2} g_2 \left(2V_{i1}^* N_{j2} - \sqrt{2} V_{i2}^* N_{j4} \right) \left(\gamma_\mu \cdot \frac{1 + \gamma_5}{2} \right) \quad (170)$$



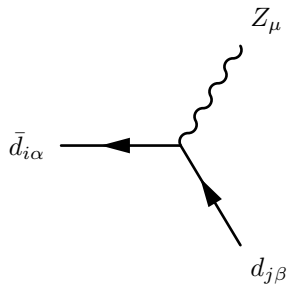
$$-\frac{i}{2}g_3\delta_{ij}\lambda_{\alpha,\beta}^\gamma\left(\gamma_\mu\cdot\frac{1-\gamma_5}{2}\right) \quad (171)$$

$$+\frac{i}{2}g_3\delta_{ij}\lambda_{\alpha,\beta}^\gamma\left(\gamma_\mu\cdot\frac{1+\gamma_5}{2}\right) \quad (172)$$



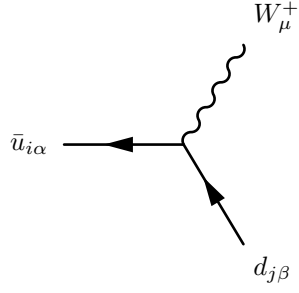
$$-\frac{i}{6}\delta_{\alpha\beta}\delta_{ij}\left(-3g_2\sin\Theta_W+g_1\cos\Theta_W\right)\left(\gamma_\mu\cdot\frac{1-\gamma_5}{2}\right) \quad (173)$$

$$+\frac{i}{3}g_1\cos\Theta_W\delta_{\alpha\beta}\delta_{ij}\left(\gamma_\mu\cdot\frac{1+\gamma_5}{2}\right) \quad (174)$$

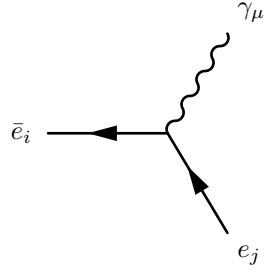


$$\frac{i}{6}\delta_{\alpha\beta}\delta_{ij}\left(3g_2\cos\Theta_W+g_1\sin\Theta_W\right)\left(\gamma_\mu\cdot\frac{1-\gamma_5}{2}\right) \quad (175)$$

$$+\frac{i}{3}g_1\delta_{\alpha\beta}\delta_{ij}\sin\Theta_W\left(\gamma_\mu\cdot\frac{1+\gamma_5}{2}\right) \quad (176)$$

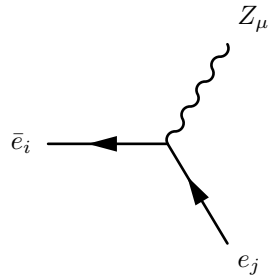


$$-i \frac{1}{\sqrt{2}} g_2 \delta_{\alpha\beta} \delta_{ij} \left(\gamma_\mu \cdot \frac{1 - \gamma_5}{2} \right) \quad (177)$$



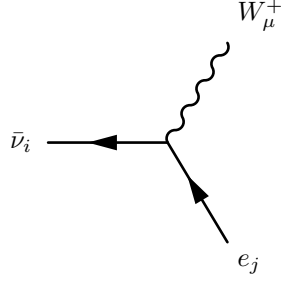
$$\frac{i}{2} \delta_{ij} \left(g_1 \cos \Theta_W + g_2 \sin \Theta_W \right) \left(\gamma_\mu \cdot \frac{1 - \gamma_5}{2} \right) \quad (178)$$

$$+ i g_1 \cos \Theta_W \delta_{ij} \left(\gamma_\mu \cdot \frac{1 + \gamma_5}{2} \right) \quad (179)$$

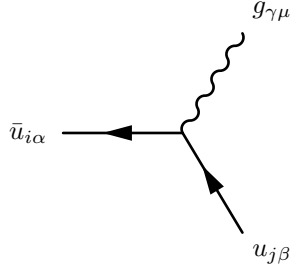


$$\frac{i}{2} \delta_{ij} \left(-g_1 \sin \Theta_W + g_2 \cos \Theta_W \right) \left(\gamma_\mu \cdot \frac{1 - \gamma_5}{2} \right) \quad (180)$$

$$+ -i g_1 \delta_{ij} \sin \Theta_W \left(\gamma_\mu \cdot \frac{1 + \gamma_5}{2} \right) \quad (181)$$

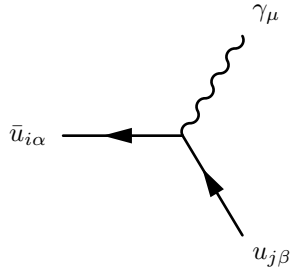


$$-i \frac{1}{\sqrt{2}} g_2 \delta_{ij} \left(\gamma_\mu \cdot \frac{1 - \gamma_5}{2} \right) \quad (182)$$



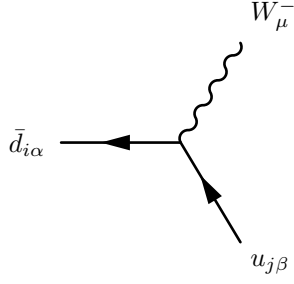
$$-\frac{i}{2} g_3 \delta_{ij} \lambda_{\alpha,\beta}^\gamma \left(\gamma_\mu \cdot \frac{1 - \gamma_5}{2} \right) \quad (183)$$

$$+ \frac{i}{2} g_3 \delta_{ij} \lambda_{\alpha,\beta}^\gamma \left(\gamma_\mu \cdot \frac{1 + \gamma_5}{2} \right) \quad (184)$$

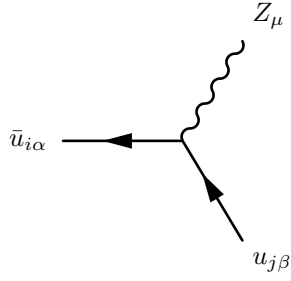


$$-\frac{i}{6} \delta_{\alpha\beta} \delta_{ij} \left(3g_2 \sin \Theta_W + g_1 \cos \Theta_W \right) \left(\gamma_\mu \cdot \frac{1 - \gamma_5}{2} \right) \quad (185)$$

$$+ \frac{2i}{3} g_1 \cos \Theta_W \delta_{\alpha\beta} \delta_{ij} \left(\gamma_\mu \cdot \frac{1 + \gamma_5}{2} \right) \quad (186)$$

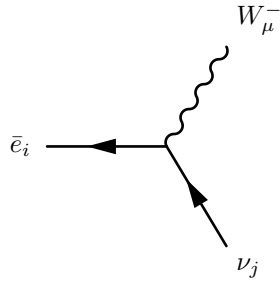


$$-i \frac{1}{\sqrt{2}} g_2 \delta_{\alpha\beta} \delta_{ij} \left(\gamma_\mu \cdot \frac{1 - \gamma_5}{2} \right) \quad (187)$$

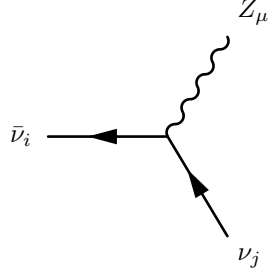


$$-\frac{i}{6} \delta_{\alpha\beta} \delta_{ij} \left(3g_2 \cos \Theta_W - g_1 \sin \Theta_W \right) \left(\gamma_\mu \cdot \frac{1 - \gamma_5}{2} \right) \quad (188)$$

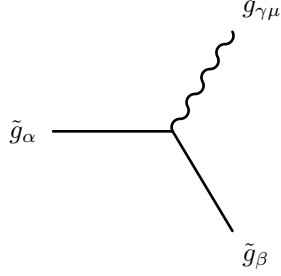
$$+\frac{2i}{3} g_1 \delta_{\alpha\beta} \delta_{ij} \sin \Theta_W \left(\gamma_\mu \cdot \frac{1 + \gamma_5}{2} \right) \quad (189)$$



$$-i \frac{1}{\sqrt{2}} g_2 \delta_{ij} \left(\gamma_\mu \cdot \frac{1 - \gamma_5}{2} \right) \quad (190)$$



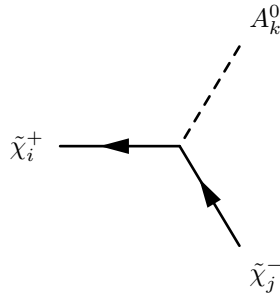
$$-\frac{i}{2}\delta_{ij}\left(g_1\sin\Theta_W+g_2\cos\Theta_W\right)\left(\gamma_\mu\cdot\frac{1-\gamma_5}{2}\right) \quad (191)$$



$$-g_3|\phi_{\tilde{g}}|^2f_{\alpha,\beta,\gamma}\left(\gamma_\mu\cdot\frac{1-\gamma_5}{2}\right) \quad (192)$$

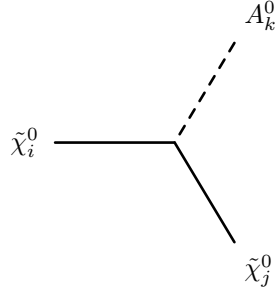
$$+g_3|\phi_{\tilde{g}}|^2f_{\alpha,\beta,\gamma}\left(\gamma_\mu\cdot\frac{1+\gamma_5}{2}\right) \quad (193)$$

8.5 Two Fermion-One Scalar Boson-Interaction



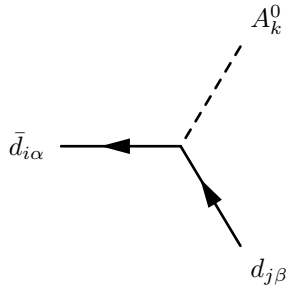
$$-\frac{1}{\sqrt{2}}g_2\left(U_{j1}^*V_{i2}^*Z_{k2}^A+U_{j2}^*V_{i1}^*Z_{k1}^A\right)\left(\frac{1-\gamma_5}{2}\right) \quad (194)$$

$$+ \frac{1}{\sqrt{2}} g_2 (U_{i1} V_{j2} Z_{k2}^A + U_{i2} V_{j1} Z_{k1}^A) \left(\frac{1 + \gamma_5}{2} \right) \quad (195)$$



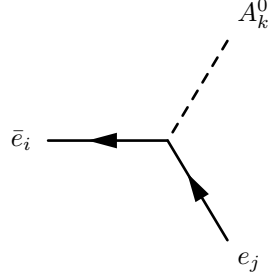
$$\begin{aligned} & \frac{1}{2} \left(N_{i3}^* (g_1 N_{j1}^* - g_2 N_{j2}^*) Z_{k1}^A - g_2 N_{i2}^* N_{j3}^* Z_{k1}^A - g_1 N_{i4}^* N_{j1}^* Z_{k2}^A + g_2 N_{i4}^* N_{j2}^* Z_{k2}^A \right. \\ & \left. + g_2 N_{i2}^* N_{j4}^* Z_{k2}^A + g_1 N_{i1}^* (N_{j3}^* Z_{k1}^A - N_{j4}^* Z_{k2}^A) \right) \left(\frac{1 - \gamma_5}{2} \right) \end{aligned} \quad (196)$$

$$\begin{aligned} & + \frac{1}{2} \left(-Z_{k1}^A \left((g_1 N_{i1} - g_2 N_{i2}) N_{j3} + N_{i3} (g_1 N_{j1} - g_2 N_{j2}) \right) \right. \\ & \left. - Z_{k2}^A \left((-g_1 N_{i1} + g_2 N_{i2}) N_{j4} + N_{i4} (-g_1 N_{j1} + g_2 N_{j2}) \right) \right) \left(\frac{1 + \gamma_5}{2} \right) \end{aligned} \quad (197)$$



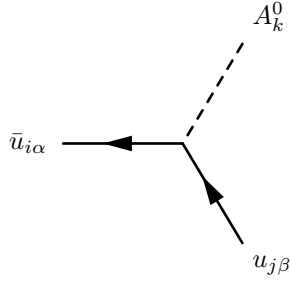
$$\frac{1}{\sqrt{2}} \delta_{\alpha\beta} \delta_{ij} Y_{d,ij} Z_{k1}^A \left(\frac{1 - \gamma_5}{2} \right) \quad (198)$$

$$+ -\frac{1}{\sqrt{2}} Y_{d,ji}^* \delta_{\alpha\beta} \delta_{ij} Z_{k1}^A \left(\frac{1 + \gamma_5}{2} \right) \quad (199)$$



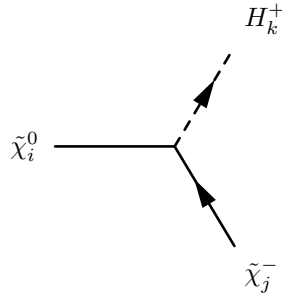
$$\frac{1}{\sqrt{2}}\delta_{ij}Y_{e,ij}Z_{k1}^A\left(\frac{1-\gamma_5}{2}\right) \quad (200)$$

$$+ -\frac{1}{\sqrt{2}}Y_{e,ji}^*\delta_{ij}Z_{k1}^A\left(\frac{1+\gamma_5}{2}\right) \quad (201)$$



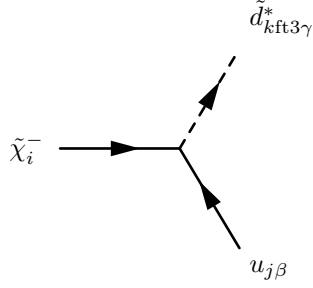
$$\frac{1}{\sqrt{2}}\delta_{\alpha\beta}\delta_{ij}Y_{u,ij}Z_{k2}^A\left(\frac{1-\gamma_5}{2}\right) \quad (202)$$

$$+ -\frac{1}{\sqrt{2}}Y_{u,ji}^*\delta_{\alpha\beta}\delta_{ij}Z_{k2}^A\left(\frac{1+\gamma_5}{2}\right) \quad (203)$$



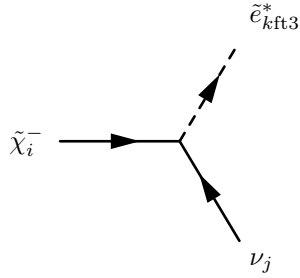
$$\frac{i}{2}\left(-2g_2U_{j1}^*N_{i3}^* + \sqrt{2}U_{j2}^*(g_1N_{i1}^* + g_2N_{i2}^*)\right)Z_{k1}^+\left(\frac{1-\gamma_5}{2}\right) \quad (204)$$

$$+ -\frac{i}{2} \left(2g_2 V_{j1} N_{i4} + \sqrt{2} V_{j2} (g_1 N_{i1} + g_2 N_{i2}) \right) Z_{k2}^+ \left(\frac{1 + \gamma_5}{2} \right) \quad (205)$$

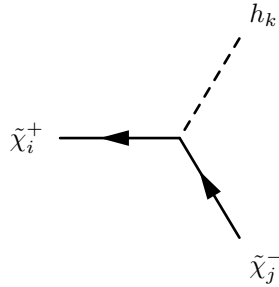


$$i\delta_{\beta\gamma}\delta_{jk} \left(-g_2 U_{i1}^* \text{ZD}(\text{gt3})(\text{ft3}, 1) + U_{i2}^* Y_{d,kj} \text{ZD}(\text{gt3})(\text{ft3}, 2) \right) \left(\frac{1 - \gamma_5}{2} \right) \quad (206)$$

$$+ iY_{u,jk}^* \delta_{\beta\gamma}\delta_{jk} V_{i2} \text{ZD}(\text{gt3})(\text{ft3}, 1) \left(\frac{1 + \gamma_5}{2} \right) \quad (207)$$

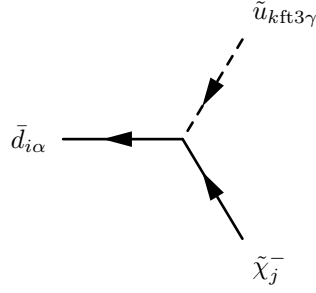


$$i\delta_{jk} \left(-g_2 U_{i1}^* \text{ZE}(\text{gt3})(\text{ft3}, 1) + U_{i2}^* Y_{e,kj} \text{ZE}(\text{gt3})(\text{ft3}, 2) \right) \left(\frac{1 - \gamma_5}{2} \right) \quad (208)$$



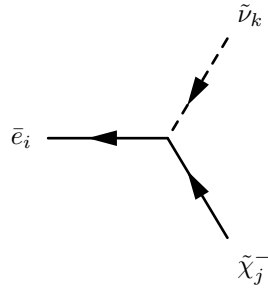
$$-i\frac{1}{\sqrt{2}}g_2\left(U_{j_1}^*V_{i_2}^*Z_{k_2}^H+U_{j_2}^*V_{i_1}^*Z_{k_1}^H\right)\left(\frac{1-\gamma_5}{2}\right) \quad (209)$$

$$+i\frac{1}{\sqrt{2}}g_2\left(U_{i_1}V_{j_2}Z_{k_2}^H+U_{i_2}V_{j_1}Z_{k_1}^H\right)\left(\frac{1+\gamma_5}{2}\right) \quad (210)$$



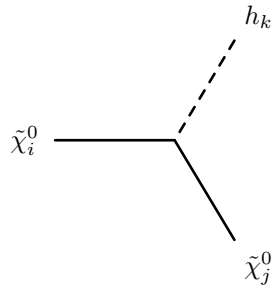
$$iU_{j_2}^*\text{conj}\left(\text{ZU}\left(\text{gt3}\right)\left(\text{ft3},1\right)\right)\delta_{\alpha\gamma}\delta_{ik}Y_{d,ik}\left(\frac{1-\gamma_5}{2}\right) \quad (211)$$

$$+i\delta_{\alpha\gamma}\delta_{ik}\left(-g_2\text{conj}\left(\text{ZU}\left(\text{gt3}\right)\left(\text{ft3},1\right)\right)V_{j_1}+Y_{u,ki}^*\text{conj}\left(\text{ZU}\left(\text{gt3}\right)\left(\text{ft3},2\right)\right)V_{j_2}\right)\left(\frac{1+\gamma_5}{2}\right) \quad (212)$$



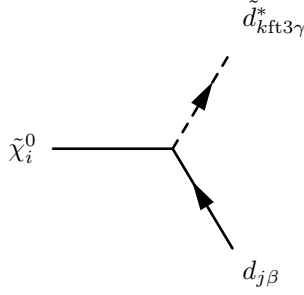
$$iU_{j_2}^*\delta_{ik}Y_{e,ik}\left(\frac{1-\gamma_5}{2}\right) \quad (213)$$

$$+ig_2\delta_{ik}V_{j_1}\left(\frac{1+\gamma_5}{2}\right) \quad (214)$$



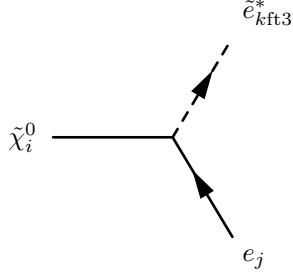
$$\begin{aligned} & \frac{i}{2} \left(N_{i3}^* \left(g_1 N_{j1}^* - g_2 N_{j2}^* \right) Z_{k1}^H - g_2 N_{i2}^* N_{j3}^* Z_{k1}^H - g_1 N_{i4}^* N_{j1}^* Z_{k2}^H + g_2 N_{i4}^* N_{j2}^* Z_{k2}^H \right. \\ & \left. + g_2 N_{i2}^* N_{j4}^* Z_{k2}^H + g_1 N_{i1}^* \left(N_{j3}^* Z_{k1}^H - N_{j4}^* Z_{k2}^H \right) \right) \left(\frac{1 - \gamma_5}{2} \right) \end{aligned} \quad (215)$$

$$\begin{aligned} & + \frac{i}{2} \left(Z_{k1}^H \left(\left(g_1 N_{i1} - g_2 N_{i2} \right) N_{j3} + N_{i3} \left(g_1 N_{j1} - g_2 N_{j2} \right) \right) \right. \\ & \left. + Z_{k2}^H \left(\left(-g_1 N_{i1} + g_2 N_{i2} \right) N_{j4} + N_{i4} \left(-g_1 N_{j1} + g_2 N_{j2} \right) \right) \right) \left(\frac{1 + \gamma_5}{2} \right) \end{aligned} \quad (216)$$



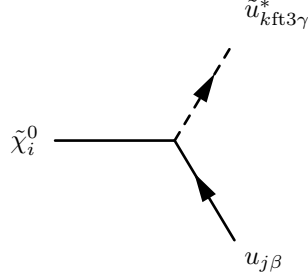
$$- \frac{i}{6} \delta_{\beta\gamma} \delta_{jk} \left(-3\sqrt{2} g_2 N_{i2}^* \text{ZD}(\text{gt3}) (\text{ft3}, 1) + 6N_{i3}^* Y_{d,kj} \text{ZD}(\text{gt3}) (\text{ft3}, 2) + \sqrt{2} g_1 N_{i1}^* \text{ZD}(\text{gt3}) (\text{ft3}, 1) \right) \left(\frac{1 - \gamma_5}{2} \right) \quad (217)$$

$$+ - \frac{i}{3} \delta_{\beta\gamma} \delta_{jk} \left(3Y_{d,jk}^* N_{i3} \text{ZD}(\text{gt3}) (\text{ft3}, 1) + \sqrt{2} g_1 N_{i1} \text{ZD}(\text{gt3}) (\text{ft3}, 2) \right) \left(\frac{1 + \gamma_5}{2} \right) \quad (218)$$



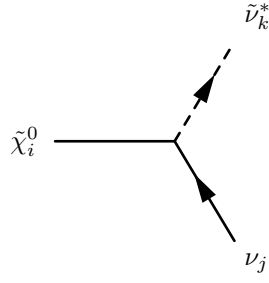
$$\frac{i}{2} \delta_{jk} \left(-2N_{i3}^* Y_{e,kj} \text{ZE}(\text{gt3}) (\text{ft3}, 2) + \sqrt{2} g_1 N_{i1}^* \text{ZE}(\text{gt3}) (\text{ft3}, 1) + \sqrt{2} g_2 N_{i2}^* \text{ZE}(\text{gt3}) (\text{ft3}, 1) \right) \left(\frac{1 - \gamma_5}{2} \right) \quad (219)$$

$$+ -i \delta_{jk} \left(\sqrt{2} g_1 N_{i1} \text{ZE}(\text{gt3}) (\text{ft3}, 2) + Y_{e,jk}^* N_{i3} \text{ZE}(\text{gt3}) (\text{ft3}, 1) \right) \left(\frac{1 + \gamma_5}{2} \right) \quad (220)$$

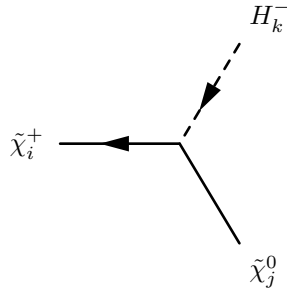


$$-\frac{i}{6}\delta_{\beta\gamma}\delta_{jk}\left(3\sqrt{2}g_2N_{i2}^*ZU(\text{gt3})(\text{ft3},1)+6N_{i4}^*Y_{u,kj}ZU(\text{gt3})(\text{ft3},2)+\sqrt{2}g_1N_{i1}^*ZU(\text{gt3})(\text{ft3},1)\right)\left(\frac{1-\gamma_5}{2}\right) \quad (221)$$

$$+\frac{i}{3}\delta_{\beta\gamma}\delta_{jk}\left(2\sqrt{2}g_1N_{i1}ZU(\text{gt3})(\text{ft3},2)-3Y_{u,jk}^*N_{i4}ZU(\text{gt3})(\text{ft3},1)\right)\left(\frac{1+\gamma_5}{2}\right) \quad (222)$$

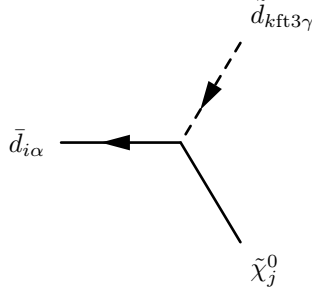


$$i\frac{1}{\sqrt{2}}\left(g_1N_{i1}^*-g_2N_{i2}^*\right)\delta_{jk}\left(\frac{1-\gamma_5}{2}\right) \quad (223)$$



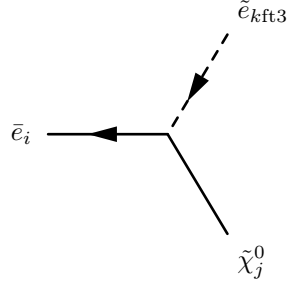
$$-\frac{i}{2}\left(2g_2V_{i1}^*N_{j4}^*+\sqrt{2}V_{i2}^*(g_1N_{j1}^*+g_2N_{j2}^*)\right)Z_{k2}^+\left(\frac{1-\gamma_5}{2}\right) \quad (224)$$

$$+\frac{i}{2}\left(-2g_2U_{i1}N_{j3}+\sqrt{2}U_{i2}(g_1N_{j1}+g_2N_{j2})\right)Z_{k1}^+\left(\frac{1+\gamma_5}{2}\right) \quad (225)$$



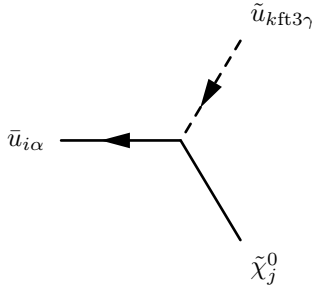
$$-\frac{i}{3}\delta_{\alpha\gamma}\delta_{ik}\left(3N_{j3}^*\text{conj}\left(\text{ZD}\left(\text{gt3}\right)\left(\text{ft3},1\right)\right)Y_{d,ik}+\sqrt{2}g_1N_{j1}^*\text{conj}\left(\text{ZD}\left(\text{gt3}\right)\left(\text{ft3},2\right)\right)\right)\left(\frac{1-\gamma_5}{2}\right) \quad (226)$$

$$+\frac{i}{6}\delta_{\alpha\gamma}\delta_{ik}\left(6Y_{d,ki}^*\text{conj}\left(\text{ZD}\left(\text{gt3}\right)\left(\text{ft3},2\right)\right)N_{j3}+\sqrt{2}\text{conj}\left(\text{ZD}\left(\text{gt3}\right)\left(\text{ft3},1\right)\right)\left(-3g_2N_{j2}+g_1N_{j1}\right)\right)\left(\frac{1+\gamma_5}{2}\right) \quad (227)$$



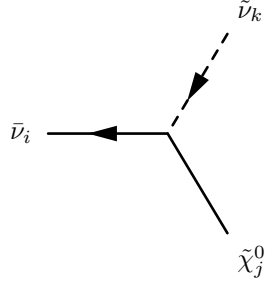
$$-i\delta_{ik}\left(N_{j3}^*\text{conj}\left(\text{ZE}\left(\text{gt3}\right)\left(\text{ft3},1\right)\right)Y_{e,ik}+\sqrt{2}g_1N_{j1}^*\text{conj}\left(\text{ZE}\left(\text{gt3}\right)\left(\text{ft3},2\right)\right)\right)\left(\frac{1-\gamma_5}{2}\right) \quad (228)$$

$$+\frac{i}{2}\delta_{ik}\left(-2Y_{e,ki}^*\text{conj}\left(\text{ZE}\left(\text{gt3}\right)\left(\text{ft3},2\right)\right)N_{j3}+\sqrt{2}\text{conj}\left(\text{ZE}\left(\text{gt3}\right)\left(\text{ft3},1\right)\right)\left(g_1N_{j1}+g_2N_{j2}\right)\right)\left(\frac{1+\gamma_5}{2}\right) \quad (229)$$



$$\frac{i}{3}\delta_{\alpha\gamma}\delta_{ik}\left(2\sqrt{2}g_1N_{j1}^*\text{conj}\left(\text{ZU}\left(\text{gt3}\right)\left(\text{ft3},2\right)\right)-3N_{j4}^*\text{conj}\left(\text{ZU}\left(\text{gt3}\right)\left(\text{ft3},1\right)\right)Y_{u,ik}\right)\left(\frac{1-\gamma_5}{2}\right) \quad (230)$$

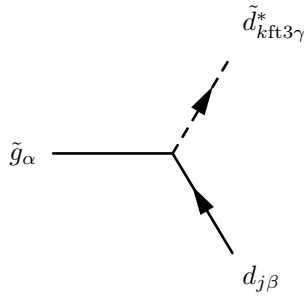
$$+\frac{i}{6}\delta_{\alpha\gamma}\delta_{ik}\left(6Y_{u,ki}^*\text{conj}\left(\text{ZU}\left(\text{gt3}\right)\left(\text{ft3},2\right)\right)N_{j4}+\sqrt{2}\text{conj}\left(\text{ZU}\left(\text{gt3}\right)\left(\text{ft3},1\right)\right)\left(3g_2N_{j2}+g_1N_{j1}\right)\right)\left(\frac{1+\gamma_5}{2}\right) \quad (231)$$



(232)

$$+ i \frac{1}{\sqrt{2}} \delta_{ik} (g_1 N_{j1} - g_2 N_{j2}) \left(\frac{1 + \gamma_5}{2} \right)$$

(233)

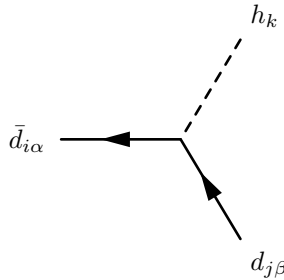


$$- i \frac{1}{\sqrt{2}} g_3 \phi_{\tilde{g}} \delta_{jk} \lambda_{\gamma,\beta}^\alpha \text{ZD}(\text{gt}3) (\text{ft}3, 1) \left(\frac{1 - \gamma_5}{2} \right)$$

(234)

$$+ i \frac{1}{\sqrt{2}} g_3 \phi_{\tilde{g}}^* \delta_{jk} \lambda_{\gamma,\beta}^\alpha \text{ZD}(\text{gt}3) (\text{ft}3, 2) \left(\frac{1 + \gamma_5}{2} \right)$$

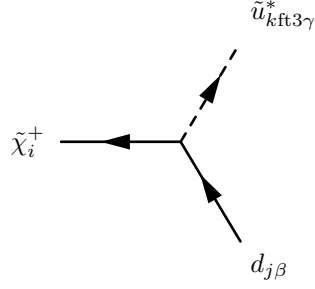
(235)



$$- i \frac{1}{\sqrt{2}} \delta_{\alpha\beta} \delta_{ij} Y_{d,ij} Z_{k1}^H \left(\frac{1 - \gamma_5}{2} \right)$$

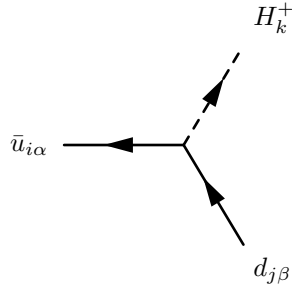
(236)

$$+ -i\frac{1}{\sqrt{2}}Y_{d,ji}^*\delta_{\alpha\beta}\delta_{ij}Z_{k1}^H\left(\frac{1+\gamma_5}{2}\right) \quad (237)$$



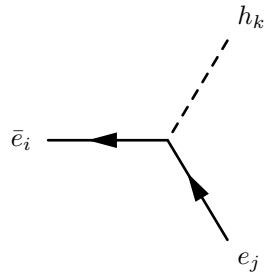
$$i\delta_{\beta\gamma}\delta_{jk}\left(-g_2V_{i1}^*ZU(\text{gt}3)(\text{ft}3,1) + V_{i2}^*Y_{u,kj}ZU(\text{gt}3)(\text{ft}3,2)\right)\left(\frac{1-\gamma_5}{2}\right) \quad (238)$$

$$+ iY_{d,jk}^*\delta_{\beta\gamma}\delta_{jk}U_{i2}ZU(\text{gt}3)(\text{ft}3,1)\left(\frac{1+\gamma_5}{2}\right) \quad (239)$$



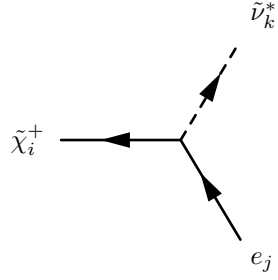
$$i\delta_{\alpha\beta}\delta_{ij}Y_{u,ij}Z_{k2}^+\left(\frac{1-\gamma_5}{2}\right) \quad (240)$$

$$+ iY_{d,ji}^*\delta_{\alpha\beta}\delta_{ij}Z_{k1}^+\left(\frac{1+\gamma_5}{2}\right) \quad (241)$$



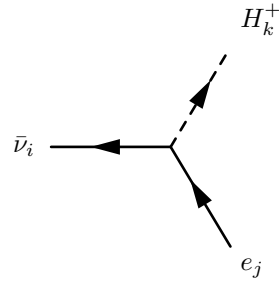
$$-i \frac{1}{\sqrt{2}} \delta_{ij} Y_{e,ij} Z_{k1}^H \left(\frac{1 - \gamma_5}{2} \right) \quad (242)$$

$$+ -i \frac{1}{\sqrt{2}} Y_{e,ji}^* \delta_{ij} Z_{k1}^H \left(\frac{1 + \gamma_5}{2} \right) \quad (243)$$



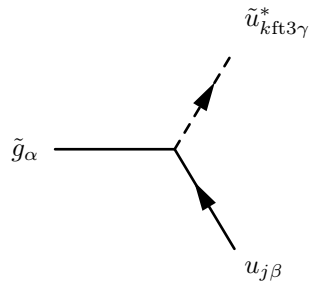
$$-ig_2 V_{i1}^* \delta_{jk} \left(\frac{1 - \gamma_5}{2} \right) \quad (244)$$

$$+ iY_{e,jk}^* \delta_{jk} U_{i2} \left(\frac{1 + \gamma_5}{2} \right) \quad (245)$$



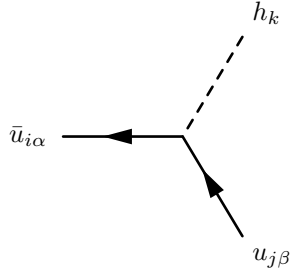
$$(246)$$

$$+ iY_{e,ji}^* \delta_{ij} Z_{k1}^+ \left(\frac{1 + \gamma_5}{2} \right) \quad (247)$$



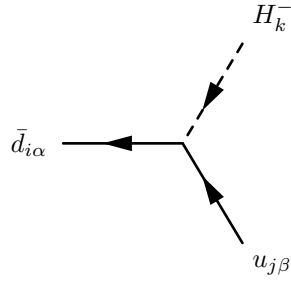
$$-i \frac{1}{\sqrt{2}} g_3 \phi_{\bar{g}} \delta_{jk} \lambda_{\gamma, \beta}^{\alpha} Z U(\text{gt}3) (\text{ft}3, 1) \left(\frac{1 - \gamma_5}{2} \right) \quad (248)$$

$$+ i \frac{1}{\sqrt{2}} g_3 \phi_{\bar{g}}^* \delta_{jk} \lambda_{\gamma, \beta}^{\alpha} Z U(\text{gt}3) (\text{ft}3, 2) \left(\frac{1 + \gamma_5}{2} \right) \quad (249)$$



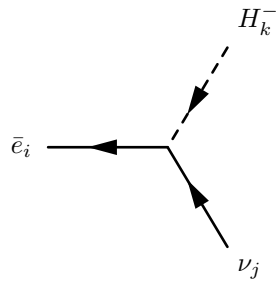
$$-i \frac{1}{\sqrt{2}} \delta_{\alpha\beta} \delta_{ij} Y_{u,ij} Z_{k2}^H \left(\frac{1 - \gamma_5}{2} \right) \quad (250)$$

$$+ -i \frac{1}{\sqrt{2}} Y_{u,ji}^* \delta_{\alpha\beta} \delta_{ij} Z_{k2}^H \left(\frac{1 + \gamma_5}{2} \right) \quad (251)$$

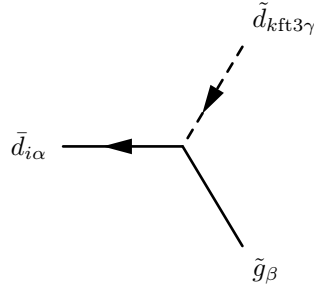


$$i \delta_{\alpha\beta} \delta_{ij} Y_{d,ij} Z_{k1}^+ \left(\frac{1 - \gamma_5}{2} \right) \quad (252)$$

$$+ i Y_{u,ji}^* \delta_{\alpha\beta} \delta_{ij} Z_{k2}^+ \left(\frac{1 + \gamma_5}{2} \right) \quad (253)$$

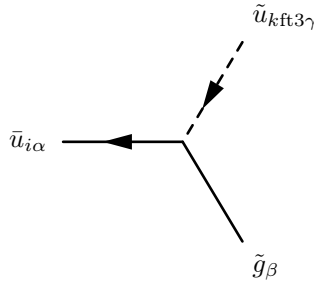


$$i\delta_{ij}Y_{e,ij}Z_{k1}^+\left(\frac{1-\gamma_5}{2}\right) \quad (254)$$



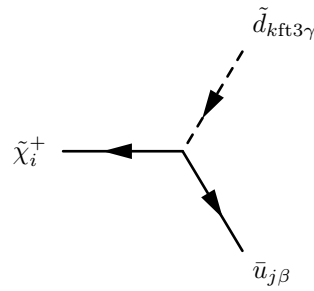
$$i\frac{1}{\sqrt{2}}g_3\phi_{\tilde{g}}\text{conj}\left(\text{ZD}(\text{gt3})(\text{ft3}, 2)\right)\delta_{ik}\lambda_{\alpha,\gamma}^\beta\left(\frac{1-\gamma_5}{2}\right) \quad (255)$$

$$+ -i\frac{1}{\sqrt{2}}g_3\phi_{\tilde{g}}^*\text{conj}\left(\text{ZD}(\text{gt3})(\text{ft3}, 1)\right)\delta_{ik}\lambda_{\alpha,\gamma}^\beta\left(\frac{1+\gamma_5}{2}\right) \quad (256)$$



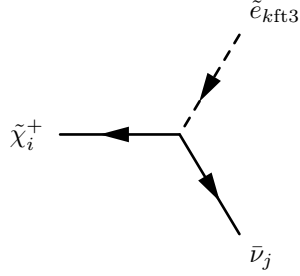
$$i\frac{1}{\sqrt{2}}g_3\phi_{\tilde{g}}\text{conj}\left(\text{ZU}(\text{gt3})(\text{ft3}, 2)\right)\delta_{ik}\lambda_{\alpha,\gamma}^\beta\left(\frac{1-\gamma_5}{2}\right) \quad (257)$$

$$+ -i\frac{1}{\sqrt{2}}g_3\phi_{\tilde{g}}^*\text{conj}\left(\text{ZU}(\text{gt3})(\text{ft3}, 1)\right)\delta_{ik}\lambda_{\alpha,\gamma}^\beta\left(\frac{1+\gamma_5}{2}\right) \quad (258)$$



$$iV_{i2}^* \text{conj}\left(\text{ZD}(\text{gt3})(\text{ft3}, 1)\right) \delta_{\beta\gamma} \delta_{jk} Y_{u,jk} \left(\frac{1-\gamma_5}{2}\right) \quad (259)$$

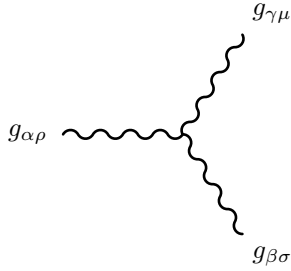
$$+ i\delta_{\beta\gamma} \delta_{jk} \left(-g_2 \text{conj}\left(\text{ZD}(\text{gt3})(\text{ft3}, 1)\right) U_{i1} + Y_{d,kj}^* \text{conj}\left(\text{ZD}(\text{gt3})(\text{ft3}, 2)\right) U_{i2}\right) \left(\frac{1+\gamma_5}{2}\right) \quad (260)$$



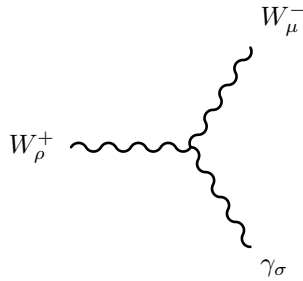
$$(261)$$

$$+ i\delta_{jk} \left(-g_2 \text{conj}\left(\text{ZE}(\text{gt3})(\text{ft3}, 1)\right) U_{i1} + Y_{e,kj}^* \text{conj}\left(\text{ZE}(\text{gt3})(\text{ft3}, 2)\right) U_{i2}\right) \left(\frac{1+\gamma_5}{2}\right) \quad (262)$$

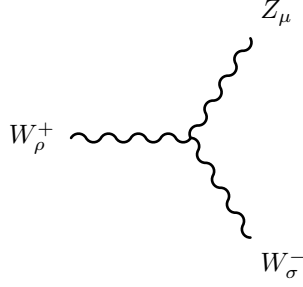
8.6 Three Vector Boson-Interaction



$$g_3 f_{\alpha,\beta,\gamma} \left(g_{\rho\mu} \left(-p_\sigma^{g\gamma\mu} + p_\sigma^{g\alpha\rho} \right) + g_{\rho\sigma} \left(-p_\mu^{g\alpha\rho} + p_\mu^{g\beta\sigma} \right) + g_{\sigma\mu} \left(-p_\rho^{g\beta\sigma} + p_\rho^{g\gamma\mu} \right) \right) \quad (263)$$

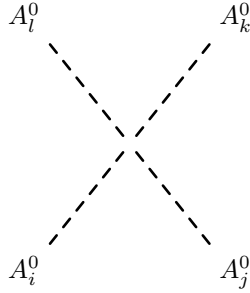


$$ig_2 \sin \Theta_W \left(g_{\rho\mu} \left(-p_\sigma^{W^-} + p_\sigma^{W^+} \right) + g_{\rho\sigma} \left(-p_\mu^{W^+} + p_\mu^{\gamma^0} \right) + g_{\sigma\mu} \left(-p_\rho^{\gamma^0} + p_\rho^{W^-} \right) \right) \quad (264)$$

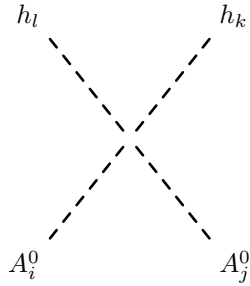


$$-ig_2 \cos \Theta_W \left(g_{\rho\mu} \left(-p_\sigma^{Z^0} + p_\sigma^{W^+} \right) + g_{\rho\sigma} \left(-p_\mu^{W^+} + p_\mu^{W^-} \right) + g_{\sigma\mu} \left(-p_\rho^{W^-} + p_\rho^{Z^0} \right) \right) \quad (265)$$

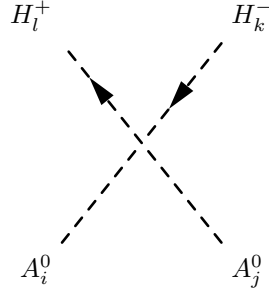
8.7 Four Scalar-Interaction



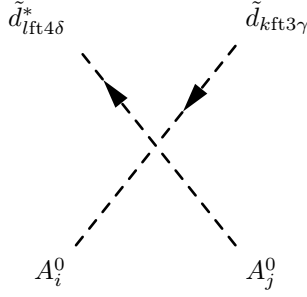
$$\begin{aligned} & \frac{i}{4} \left(g_1^2 + g_2^2 \right) \left(Z_{i2}^A \left(Z_{j1}^A \left(Z_{k1}^A Z_{l2}^A + Z_{k2}^A Z_{l1}^A \right) + Z_{j2}^A \left(-3Z_{k2}^A Z_{l2}^A + Z_{k1}^A Z_{l1}^A \right) \right) \right. \\ & \left. + Z_{i1}^A \left(Z_{j1}^A \left(-3Z_{k1}^A Z_{l1}^A + Z_{k2}^A Z_{l2}^A \right) + Z_{j2}^A \left(Z_{k1}^A Z_{l2}^A + Z_{k2}^A Z_{l1}^A \right) \right) \right) \end{aligned} \quad (266)$$



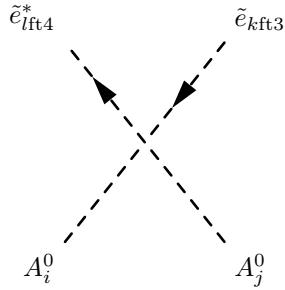
$$-\frac{i}{4}(g_1^2 + g_2^2)(Z_{i1}^A Z_{j1}^A - Z_{i2}^A Z_{j2}^A)(Z_{k1}^H Z_{l1}^H - Z_{k2}^H Z_{l2}^H) \quad (267)$$



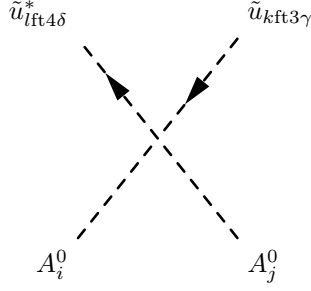
$$\begin{aligned} & \frac{i}{4} \left(Z_{i1}^A \left(g_2^2 Z_{j2}^A (Z_{k1}^+ Z_{l2}^+ + Z_{k2}^+ Z_{l1}^+) \right) - Z_{j1}^A \left((g_1^2 + g_2^2) Z_{k1}^+ Z_{l1}^+ + (-g_1^2 + g_2^2) Z_{k2}^+ Z_{l2}^+ \right) \right) \\ & + Z_{i2}^A \left(g_2^2 Z_{j1}^A (Z_{k1}^+ Z_{l2}^+ + Z_{k2}^+ Z_{l1}^+) \right) + Z_{j2}^A \left(-(g_1^2 + g_2^2) Z_{k2}^+ Z_{l2}^+ + (-g_2^2 + g_1^2) Z_{k1}^+ Z_{l1}^+ \right) \end{aligned} \quad (268)$$



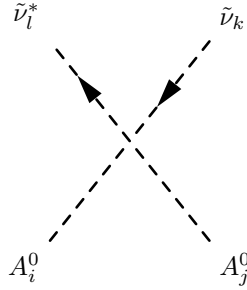
$$\begin{aligned} & \frac{i}{12} \delta_{\gamma\delta} \delta_{kl} \left(\text{conj} \left(\text{ZD}(\text{gt3})(\text{ft3}, 1) \right) \left((-12Y_{d,kl}^* Y_{d,kk} + 3g_2^2 + g_1^2) Z_{i1}^A Z_{j1}^A - (3g_2^2 + g_1^2) Z_{i2}^A Z_{j2}^A \right) \text{ZD}(\text{gt4})(\text{ft4}, 1) \right) \\ & + 2 \text{conj} \left(\text{ZD}(\text{gt3})(\text{ft3}, 2) \right) \left((-6Y_{d,kl}^* Y_{d,lk} + g_1^2) Z_{i1}^A Z_{j1}^A - g_1^2 Z_{i2}^A Z_{j2}^A \right) \text{ZD}(\text{gt4})(\text{ft4}, 2) \end{aligned} \quad (269)$$



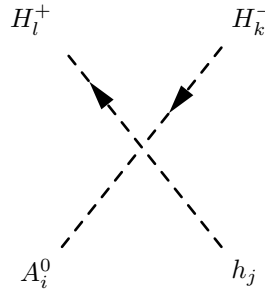
$$\begin{aligned}
& -\frac{i}{4}\delta_{kl}\left(\text{conj}\left(\text{ZE}\left(\text{gt3}\right)\left(\text{ft3},1\right)\right)\right)\left(\left(4Y_{e,kl}^*Y_{e,kk}-g_2^2+g_1^2\right)Z_{i1}^AZ_{j1}^A+\left(-g_1^2+g_2^2\right)Z_{i2}^AZ_{j2}^A\right)\text{ZE}\left(\text{gt4}\right)\left(\text{ft4},1\right) \\
& +2\text{conj}\left(\text{ZE}\left(\text{gt3}\right)\left(\text{ft3},2\right)\right)\left(-\left(-2Y_{e,kk}^*Y_{e,lk}+g_1^2\right)Z_{i1}^AZ_{j1}^A+g_1^2Z_{i2}^AZ_{j2}^A\right)\text{ZE}\left(\text{gt4}\right)\left(\text{ft4},2\right)
\end{aligned} \tag{270}$$



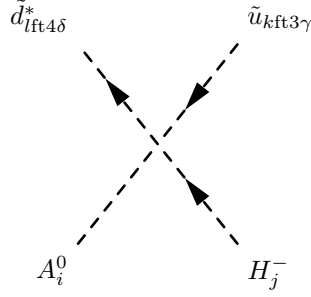
$$\begin{aligned}
& \frac{i}{12}\delta_{\gamma\delta}\delta_{kl}\left(\text{conj}\left(\text{ZU}\left(\text{gt3}\right)\left(\text{ft3},1\right)\right)\right)\left(-\left(12Y_{u,kl}^*Y_{u,kk}-3g_2^2+g_1^2\right)Z_{i2}^AZ_{j2}^A+\left(-3g_2^2+g_1^2\right)Z_{i1}^AZ_{j1}^A\right)\text{ZU}\left(\text{gt4}\right)\left(\text{ft4},1\right) \\
& -4\text{conj}\left(\text{ZU}\left(\text{gt3}\right)\left(\text{ft3},2\right)\right)\left(-\left(-3Y_{u,kk}^*Y_{u,lk}+g_1^2\right)Z_{i2}^AZ_{j2}^A+g_1^2Z_{i1}^AZ_{j1}^A\right)\text{ZU}\left(\text{gt4}\right)\left(\text{ft4},2\right)
\end{aligned} \tag{271}$$



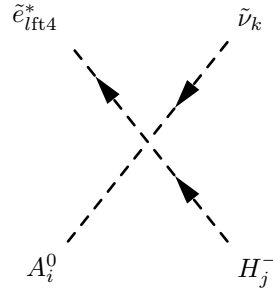
$$-\frac{i}{4}\left(g_1^2+g_2^2\right)\delta_{kl}\left(Z_{i1}^AZ_{j1}^A-Z_{i2}^AZ_{j2}^A\right) \tag{272}$$



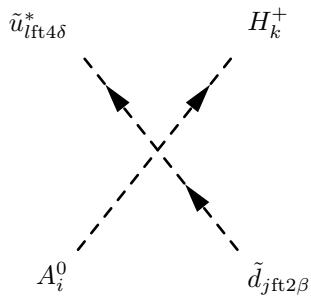
$$\frac{1}{4}g_2^2 \left(Z_{i1}^A Z_{j2}^H + Z_{i2}^A Z_{j1}^H \right) \left(-Z_{k1}^+ Z_{l2}^+ + Z_{k2}^+ Z_{l1}^+ \right) \quad (273)$$



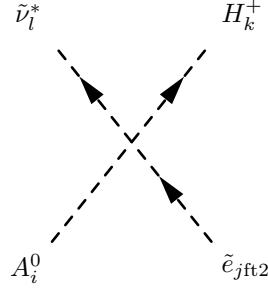
$$\begin{aligned} & -\frac{1}{2} \frac{1}{\sqrt{2}} \delta_{\gamma\delta} \delta_{kl} \left(\text{conj} \left(\text{ZU}(\text{gt3}) (\text{ft3}, 1) \right) \right) \left(\left(-2Y_{d,kl}^* Y_{d,kk} + g_2^2 \right) Z_{i1}^A Z_{j1}^+ - \left(-2Y_{u,kl}^* Y_{u,kk} + g_2^2 \right) Z_{i2}^A Z_{j2}^+ \right) \text{ZD}(\text{gt4}) (\text{ft4}, 1) \\ & + 2Y_{u,kl}^* \text{conj} \left(\text{ZU}(\text{gt3}) (\text{ft3}, 2) \right) Y_{d,lk} \left(Z_{i1}^A Z_{j2}^+ - Z_{i2}^A Z_{j1}^+ \right) \text{ZD}(\text{gt4}) (\text{ft4}, 2) \end{aligned} \quad (274)$$



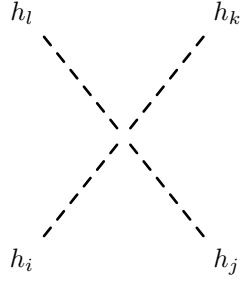
$$-\frac{1}{2} \frac{1}{\sqrt{2}} \delta_{kl} \left(\left(-2Y_{e,kl}^* Y_{e,kk} + g_2^2 \right) Z_{i1}^A Z_{j1}^+ - g_2^2 Z_{i2}^A Z_{j2}^+ \right) \text{ZE}(\text{gt4}) (\text{ft4}, 1) \quad (275)$$



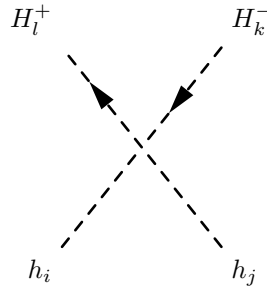
$$\begin{aligned}
& \frac{1}{2} \frac{1}{\sqrt{2}} \delta_{\beta\delta} \delta_{jl} \left(\text{conj} \left(\text{ZD}(\text{gt2}) \left(\text{ft2}, 1 \right) \right) \left(\left(-2Y_{d,jl}^* Y_{d,jj} + g_2^2 \right) Z_{i1}^A Z_{k1}^+ - \left(-2Y_{u,jl}^* Y_{u,jj} + g_2^2 \right) Z_{i2}^A Z_{k2}^+ \right) \text{ZU}(\text{gt4}) \left(\text{ft4}, 1 \right) \right. \\
& \left. + 2Y_{d,jj}^* \text{conj} \left(\text{ZD}(\text{gt2}) \left(\text{ft2}, 2 \right) \right) Y_{u,lj} \left(Z_{i1}^A Z_{k2}^+ - Z_{i2}^A Z_{k1}^+ \right) \text{ZU}(\text{gt4}) \left(\text{ft4}, 2 \right) \right)
\end{aligned} \tag{276}$$



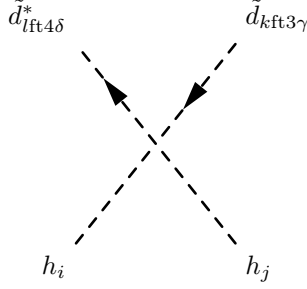
$$\frac{1}{2} \frac{1}{\sqrt{2}} \text{conj} \left(\text{ZE}(\text{gt2}) \left(\text{ft2}, 1 \right) \right) \delta_{jl} \left(\left(-2Y_{e,jl}^* Y_{e,jj} + g_2^2 \right) Z_{i1}^A Z_{k1}^+ - g_2^2 Z_{i2}^A Z_{k2}^+ \right) \tag{277}$$



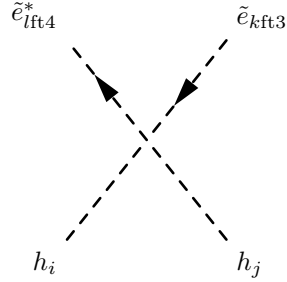
$$\begin{aligned}
& \frac{i}{4} \left(g_1^2 + g_2^2 \right) \left(Z_{i2}^H \left(Z_{j1}^H \left(Z_{k1}^H Z_{l2}^H + Z_{k2}^H Z_{l1}^H \right) + Z_{j2}^H \left(-3Z_{k2}^H Z_{l2}^H + Z_{k1}^H Z_{l1}^H \right) \right) \right. \\
& \left. + Z_{i1}^H \left(Z_{j1}^H \left(-3Z_{k1}^H Z_{l1}^H + Z_{k2}^H Z_{l2}^H \right) + Z_{j2}^H \left(Z_{k1}^H Z_{l2}^H + Z_{k2}^H Z_{l1}^H \right) \right) \right)
\end{aligned} \tag{278}$$



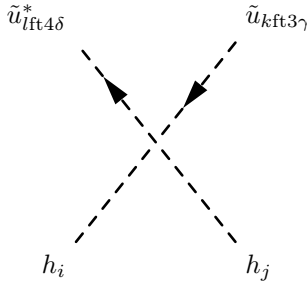
$$\begin{aligned}
& \frac{i}{4} \left(-Z_{i1}^H \left(g_2^2 Z_{j2}^H \left(Z_{k1}^+ Z_{l2}^+ + Z_{k2}^+ Z_{l1}^+ \right) + Z_{j1}^H \left(\left(g_1^2 + g_2^2 \right) Z_{k1}^+ Z_{l1}^+ + \left(-g_1^2 + g_2^2 \right) Z_{k2}^+ Z_{l2}^+ \right) \right) \right. \\
& \left. + Z_{i2}^H \left(-g_2^2 Z_{j1}^H \left(Z_{k1}^+ Z_{l2}^+ + Z_{k2}^+ Z_{l1}^+ \right) + Z_{j2}^H \left(- \left(g_1^2 + g_2^2 \right) Z_{k2}^+ Z_{l2}^+ + \left(-g_2^2 + g_1^2 \right) Z_{k1}^+ Z_{l1}^+ \right) \right) \right) \quad (279)
\end{aligned}$$



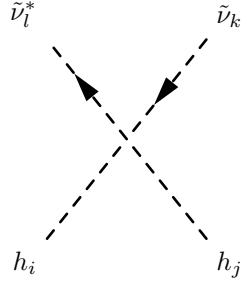
$$\begin{aligned}
& \frac{i}{12} \delta_{\gamma\delta} \delta_{kl} \left(\text{conj} \left(\text{ZD} \left(\text{gt3} \right) \left(\text{ft3}, 1 \right) \right) \left(\left(-12Y_{d,kl}^* Y_{d,kk} + 3g_2^2 + g_1^2 \right) Z_{i1}^H Z_{j1}^H - \left(3g_2^2 + g_1^2 \right) Z_{i2}^H Z_{j2}^H \right) \text{ZD} \left(\text{gt4} \right) \left(\text{ft4}, 1 \right) \right. \\
& \left. + 2\text{conj} \left(\text{ZD} \left(\text{gt3} \right) \left(\text{ft3}, 2 \right) \right) \left(\left(-6Y_{d,kl}^* Y_{d,lk} + g_1^2 \right) Z_{i1}^H Z_{j1}^H - g_1^2 Z_{i2}^H Z_{j2}^H \right) \text{ZD} \left(\text{gt4} \right) \left(\text{ft4}, 2 \right) \right) \quad (280)
\end{aligned}$$



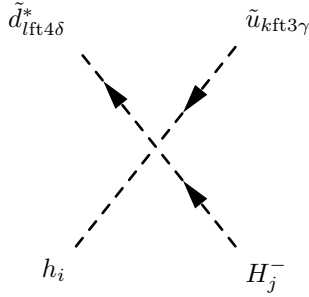
$$\begin{aligned}
& -\frac{i}{4} \delta_{kl} \left(\text{conj} \left(\text{ZE} \left(\text{gt3} \right) \left(\text{ft3}, 1 \right) \right) \left(\left(4Y_{e,kl}^* Y_{e,kk} - g_2^2 + g_1^2 \right) Z_{i1}^H Z_{j1}^H + \left(-g_1^2 + g_2^2 \right) Z_{i2}^H Z_{j2}^H \right) \text{ZE} \left(\text{gt4} \right) \left(\text{ft4}, 1 \right) \right. \\
& \left. + 2\text{conj} \left(\text{ZE} \left(\text{gt3} \right) \left(\text{ft3}, 2 \right) \right) \left(- \left(-2Y_{e,kl}^* Y_{e,lk} + g_1^2 \right) Z_{i1}^H Z_{j1}^H + g_1^2 Z_{i2}^H Z_{j2}^H \right) \text{ZE} \left(\text{gt4} \right) \left(\text{ft4}, 2 \right) \right) \quad (281)
\end{aligned}$$



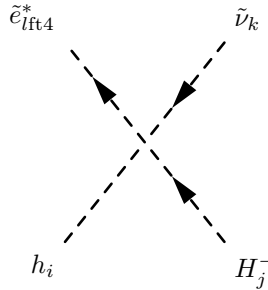
$$\begin{aligned} & \frac{i}{12} \delta_{\gamma\delta} \delta_{kl} \left(\text{conj} \left(\text{ZU}(\text{gt3}) \left(\text{ft3}, 1 \right) \right) \left(- \left(12Y_{u,kl}^* Y_{u,kk} - 3g_2^2 + g_1^2 \right) Z_{i2}^H Z_{j2}^H + \left(-3g_2^2 + g_1^2 \right) Z_{i1}^H Z_{j1}^H \right) \text{ZU}(\text{gt4}) \left(\text{ft4}, 1 \right) \right. \\ & \left. - 4 \text{conj} \left(\text{ZU}(\text{gt3}) \left(\text{ft3}, 2 \right) \right) \left(- \left(-3Y_{u,kk}^* Y_{u,lk} + g_1^2 \right) Z_{i2}^H Z_{j2}^H + g_1^2 Z_{i1}^H Z_{j1}^H \right) \text{ZU}(\text{gt4}) \left(\text{ft4}, 2 \right) \right) \end{aligned} \quad (282)$$



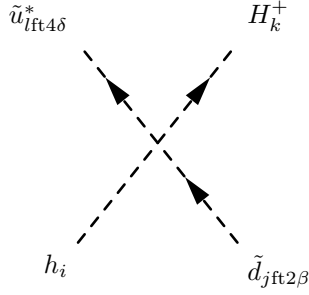
$$- \frac{i}{4} \left(g_1^2 + g_2^2 \right) \delta_{kl} \left(Z_{i1}^H Z_{j1}^H - Z_{i2}^H Z_{j2}^H \right) \quad (283)$$



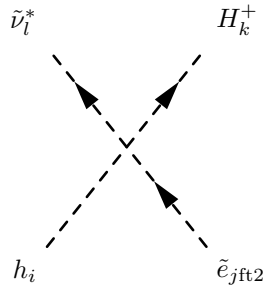
$$\begin{aligned} & \frac{i}{2} \frac{1}{\sqrt{2}} \delta_{\gamma\delta} \delta_{kl} \left(- \text{conj} \left(\text{ZU}(\text{gt3}) \left(\text{ft3}, 1 \right) \right) \left(\left(-2Y_{d,kl}^* Y_{d,kk} + g_2^2 \right) Z_{i1}^H Z_{j1}^+ + \left(-2Y_{u,kl}^* Y_{u,kk} + g_2^2 \right) Z_{i2}^H Z_{j2}^+ \right) \text{ZD}(\text{gt4}) \left(\text{ft4}, 1 \right) \right. \\ & \left. + 2Y_{u,kk}^* \text{conj} \left(\text{ZU}(\text{gt3}) \left(\text{ft3}, 2 \right) \right) Y_{d,lk} \left(Z_{i1}^H Z_{j2}^+ + Z_{i2}^H Z_{j1}^+ \right) \text{ZD}(\text{gt4}) \left(\text{ft4}, 2 \right) \right) \end{aligned} \quad (284)$$



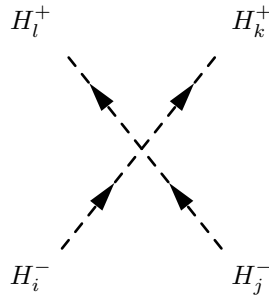
$$-\frac{i}{2} \frac{1}{\sqrt{2}} \delta_{kl} \left(\left(-2Y_{e,kl}^* Y_{e,kk} + g_2^2 \right) Z_{i1}^H Z_{j1}^+ + g_2^2 Z_{i2}^H Z_{j2}^+ \right) \text{ZE}(\text{gt4}) (\text{ft4}, 1) \quad (285)$$



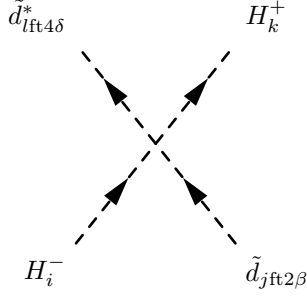
$$\begin{aligned} & \frac{i}{2} \frac{1}{\sqrt{2}} \delta_{\beta\delta} \delta_{jl} \left(-\text{conj} \left(\text{ZD}(\text{gt2}) (\text{ft2}, 1) \right) \left(\left(-2Y_{d,jl}^* Y_{d,jj} + g_2^2 \right) Z_{i1}^H Z_{k1}^+ + \left(-2Y_{u,jl}^* Y_{u,jj} + g_2^2 \right) Z_{i2}^H Z_{k2}^+ \right) \text{ZU}(\text{gt4}) (\text{ft4}, 1) \right. \\ & \left. + 2Y_{d,jj}^* \text{conj} \left(\text{ZD}(\text{gt2}) (\text{ft2}, 2) \right) Y_{u,lj} \left(Z_{i1}^H Z_{k2}^+ + Z_{i2}^H Z_{k1}^+ \right) \text{ZU}(\text{gt4}) (\text{ft4}, 2) \right) \quad (286) \end{aligned}$$



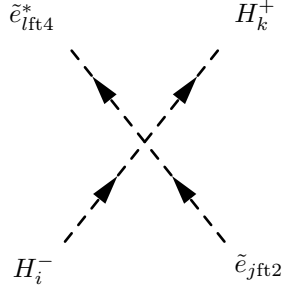
$$-\frac{i}{2} \frac{1}{\sqrt{2}} \text{conj} \left(\text{ZE}(\text{gt2}) (\text{ft2}, 1) \right) \delta_{jl} \left(\left(-2Y_{e,jl}^* Y_{e,jj} + g_2^2 \right) Z_{i1}^H Z_{k1}^+ + g_2^2 Z_{i2}^H Z_{k2}^+ \right) \quad (287)$$



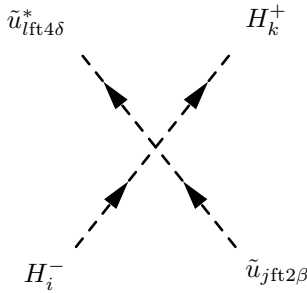
$$\begin{aligned}
& -\frac{i}{4}(g_1^2 + g_2^2) \left(-Z_{i2}^+ \left(-2Z_{j2}^+ Z_{k2}^+ Z_{l2}^+ + Z_{j1}^+ \left(Z_{k1}^+ Z_{l2}^+ + Z_{k2}^+ Z_{l1}^+ \right) \right) \right. \\
& \left. + Z_{i1}^+ \left(2Z_{j1}^+ Z_{k1}^+ Z_{l1}^+ - Z_{j2}^+ \left(Z_{k1}^+ Z_{l2}^+ + Z_{k2}^+ Z_{l1}^+ \right) \right) \right)
\end{aligned} \tag{288}$$



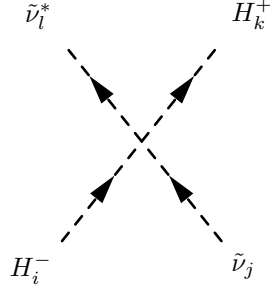
$$\begin{aligned}
& \frac{i}{12} \delta_{\beta\delta} \delta_{jl} \left(\text{conj} \left(\text{ZD}(\text{gt2})(\text{ft2}, 1) \right) \left(- \left(12Y_{u,jl}^* Y_{u,jj} - 3g_2^2 + g_1^2 \right) Z_{i2}^+ Z_{k2}^+ + \left(-3g_2^2 + g_1^2 \right) Z_{i1}^+ Z_{k1}^+ \right) \text{ZD}(\text{gt4})(\text{ft4}, 1) \right. \\
& \left. + 2 \text{conj} \left(\text{ZD}(\text{gt2})(\text{ft2}, 2) \right) \left(\left(-6Y_{d,jj}^* Y_{d,lj} + g_1^2 \right) Z_{i1}^+ Z_{k1}^+ - g_1^2 Z_{i2}^+ Z_{k2}^+ \right) \text{ZD}(\text{gt4})(\text{ft4}, 2) \right)
\end{aligned} \tag{289}$$



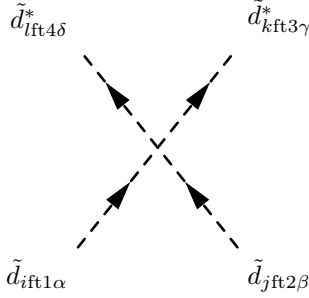
$$\begin{aligned}
& -\frac{i}{4} \delta_{jl} \left(\left(g_1^2 + g_2^2 \right) \text{conj} \left(\text{ZE}(\text{gt2})(\text{ft2}, 1) \right) \left(Z_{i1}^+ Z_{k1}^+ - Z_{i2}^+ Z_{k2}^+ \right) \text{ZE}(\text{gt4})(\text{ft4}, 1) \right. \\
& \left. + 2 \text{conj} \left(\text{ZE}(\text{gt2})(\text{ft2}, 2) \right) \left(- \left(-2Y_{e,jj}^* Y_{e,lj} + g_1^2 \right) Z_{i1}^+ Z_{k1}^+ + g_1^2 Z_{i2}^+ Z_{k2}^+ \right) \text{ZE}(\text{gt4})(\text{ft4}, 2) \right)
\end{aligned} \tag{290}$$



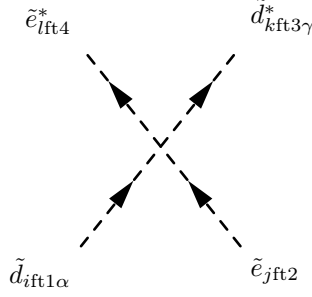
$$\begin{aligned} & \frac{i}{12} \delta_{\beta\delta} \delta_{jl} \left(\text{conj} \left(\text{ZU}(\text{gt}2) \left(\text{ft}2, 1 \right) \right) \left(\left(-12Y_{d,jl}^* Y_{d,jj} + 3g_2^2 + g_1^2 \right) Z_{i1}^+ Z_{k1}^+ - \left(3g_2^2 + g_1^2 \right) Z_{i2}^+ Z_{k2}^+ \right) \text{ZU}(\text{gt}4) \left(\text{ft}4, 1 \right) \right. \\ & \left. - 4 \text{conj} \left(\text{ZU}(\text{gt}2) \left(\text{ft}2, 2 \right) \right) \left(- \left(-3Y_{u,jj}^* Y_{u,lj} + g_1^2 \right) Z_{i2}^+ Z_{k2}^+ + g_1^2 Z_{i1}^+ Z_{k1}^+ \right) \text{ZU}(\text{gt}4) \left(\text{ft}4, 2 \right) \right) \end{aligned} \quad (291)$$



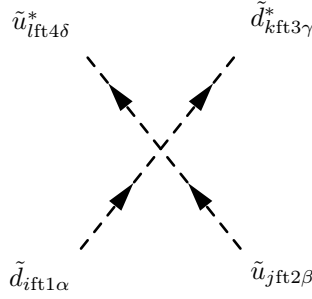
$$\frac{i}{4} \delta_{jl} \left(\left(-4Y_{e,jl}^* Y_{e,jj} - g_1^2 + g_2^2 \right) Z_{i1}^+ Z_{k1}^+ + \left(-g_2^2 + g_1^2 \right) Z_{i2}^+ Z_{k2}^+ \right) \quad (292)$$



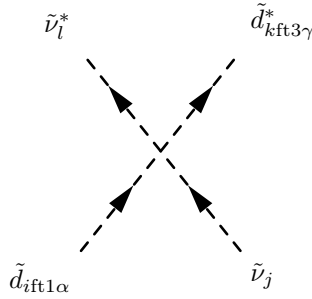
$$\begin{aligned} & \frac{i}{36} \left(- \text{conj} \left(\text{ZD}(\text{gt}1) \left(\text{ft}1, 1 \right) \right) \left(\text{conj} \left(\text{ZD}(\text{gt}2) \left(\text{ft}2, 1 \right) \right) \left(\delta_{\alpha\delta} \delta_{\beta\gamma} \left(18g_3^2 \delta_{ik} \delta_{jl} + \left(-6g_3^2 + 9g_2^2 + g_1^2 \right) \delta_{il} \delta_{jk} \right) \right. \right. \\ & \left. \left. + \delta_{\alpha\gamma} \delta_{\beta\delta} \left(18g_3^2 \delta_{il} \delta_{jk} + \left(-6g_3^2 + 9g_2^2 + g_1^2 \right) \delta_{ik} \delta_{jl} \right) \right) \text{ZD}(\text{gt}3) \left(\text{ft}3, 1 \right) \text{ZD}(\text{gt}4) \left(\text{ft}4, 1 \right) \right. \\ & \left. + 2 \text{conj} \left(\text{ZD}(\text{gt}2) \left(\text{ft}2, 2 \right) \right) \left(\delta_{\alpha\gamma} \delta_{\beta\delta} \left(-9g_3^2 \delta_{il} \delta_{jk} \text{ZD}(\text{gt}3) \left(\text{ft}3, 2 \right) \text{ZD}(\text{gt}4) \left(\text{ft}4, 1 \right) + \delta_{ik} \delta_{jl} \left(18Y_{d,jl}^* Y_{d,ki} \text{ZD}(\text{gt}3) \left(\text{ft}3, 2 \right) \text{ZD}(\text{gt}4) \left(\text{ft}4, 1 \right) \right) \right. \right. \right. \\ & \left. \left. + \delta_{\alpha\delta} \delta_{\beta\gamma} \left(-9g_3^2 \delta_{ik} \delta_{jl} \text{ZD}(\text{gt}3) \left(\text{ft}3, 1 \right) \text{ZD}(\text{gt}4) \left(\text{ft}4, 2 \right) + \delta_{il} \delta_{jk} \left(18Y_{d,jk}^* Y_{d,li} \text{ZD}(\text{gt}3) \left(\text{ft}3, 1 \right) \text{ZD}(\text{gt}4) \left(\text{ft}4, 2 \right) + \left(3g_3^2 + g_1^2 \right) \text{ZD}(\text{gt}4) \left(\text{ft}4, 2 \right) \right) \right) \right. \right. \\ & \left. \left. + 2 \text{conj} \left(\text{ZD}(\text{gt}1) \left(\text{ft}1, 2 \right) \right) \left(- \text{conj} \left(\text{ZD}(\text{gt}2) \left(\text{ft}2, 2 \right) \right) \left(\delta_{\alpha\delta} \delta_{\beta\gamma} \left(\left(2g_1^2 - 3g_3^2 \right) \delta_{il} \delta_{jk} + 9g_3^2 \delta_{ik} \delta_{jl} \right) \right. \right. \right. \\ & \left. \left. + \delta_{\alpha\gamma} \delta_{\beta\delta} \left(\left(2g_1^2 - 3g_3^2 \right) \delta_{ik} \delta_{jl} + 9g_3^2 \delta_{il} \delta_{jk} \right) \right) \text{ZD}(\text{gt}3) \left(\text{ft}3, 2 \right) \text{ZD}(\text{gt}4) \left(\text{ft}4, 2 \right) \right. \\ & \left. + \text{conj} \left(\text{ZD}(\text{gt}2) \left(\text{ft}2, 1 \right) \right) \left(\delta_{\alpha\delta} \delta_{\beta\gamma} \left(9g_3^2 \delta_{ik} \delta_{jl} \text{ZD}(\text{gt}3) \left(\text{ft}3, 2 \right) \text{ZD}(\text{gt}4) \left(\text{ft}4, 1 \right) - \delta_{il} \delta_{jk} \left(18Y_{d,il}^* Y_{d,kj} \text{ZD}(\text{gt}3) \left(\text{ft}3, 2 \right) \text{ZD}(\text{gt}4) \left(\text{ft}4, 1 \right) \right) \right. \right. \\ & \left. \left. - \delta_{\alpha\gamma} \delta_{\beta\delta} \left(-9g_3^2 \delta_{il} \delta_{jk} \text{ZD}(\text{gt}3) \left(\text{ft}3, 1 \right) \text{ZD}(\text{gt}4) \left(\text{ft}4, 2 \right) + \delta_{ik} \delta_{jl} \left(18Y_{d,ik}^* Y_{d,lj} \text{ZD}(\text{gt}3) \left(\text{ft}3, 1 \right) \text{ZD}(\text{gt}4) \left(\text{ft}4, 2 \right) + \left(3g_3^2 + g_1^2 \right) \text{ZD}(\text{gt}4) \left(\text{ft}4, 2 \right) \right) \right) \right) \end{aligned} \quad (293)$$



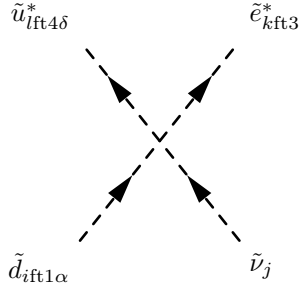
$$\begin{aligned} & \frac{i}{12} \delta_{\alpha\gamma} \delta_{ik} \delta_{jl} \left(\text{conj} \left(\text{ZD}(\text{gt1}) \left(\text{ft1}, 1 \right) \right) \left(-2 \text{conj} \left(\text{ZE}(\text{gt2}) \left(\text{ft2}, 2 \right) \right) \left(6 Y_{e,jl}^* Y_{d,ki} \text{ZD}(\text{gt3}) \left(\text{ft3}, 2 \right) \text{ZE}(\text{gt4}) \left(\text{ft4}, 1 \right) + g_1^2 \text{ZD}(\text{gt3}) \left(\text{ft3}, 1 \right) \right. \right. \\ & \left. \left. + 2 \text{conj} \left(\text{ZD}(\text{gt1}) \left(\text{ft1}, 2 \right) \right) \left(-2 g_1^2 \text{conj} \left(\text{ZE}(\text{gt2}) \left(\text{ft2}, 2 \right) \right) \text{ZD}(\text{gt3}) \left(\text{ft3}, 2 \right) \text{ZE}(\text{gt4}) \left(\text{ft4}, 2 \right) + \text{conj} \left(\text{ZE}(\text{gt2}) \left(\text{ft2}, 1 \right) \right) \left(-6 Y_{d,ik}^* Y_{e,jl} \right) \right) \right) \end{aligned} \quad (294)$$



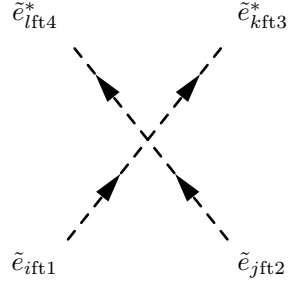
$$\begin{aligned} & \frac{i}{36} \left(2 \text{conj} \left(\text{ZD}(\text{gt1}) \left(\text{ft1}, 2 \right) \right) \text{ZD}(\text{gt3}) \left(\text{ft3}, 2 \right) \left(\text{conj} \left(\text{ZU}(\text{gt2}) \left(\text{ft2}, 1 \right) \right) \left(- \left(3g_3^2 + g_1^2 \right) \delta_{\alpha\gamma} \delta_{\beta\delta} \delta_{ik} \delta_{jl} + 9 \delta_{\alpha\delta} \delta_{\beta\gamma} \left(-2 Y_{d,il}^* \delta_{il} \delta_{jk} Y_{d,kj} + \right. \right. \right. \\ & \left. \left. + \text{conj} \left(\text{ZU}(\text{gt2}) \left(\text{ft2}, 2 \right) \right) \left(\left(3g_3^2 + 4g_1^2 \right) \delta_{\alpha\gamma} \delta_{\beta\delta} - 9g_3^2 \delta_{\alpha\delta} \delta_{\beta\gamma} \right) \delta_{ik} \delta_{jl} \text{ZU}(\text{gt4}) \left(\text{ft4}, 2 \right) \right) \right. \\ & \left. - \text{conj} \left(\text{ZD}(\text{gt1}) \left(\text{ft1}, 1 \right) \right) \text{ZD}(\text{gt3}) \left(\text{ft3}, 1 \right) \left(\text{conj} \left(\text{ZU}(\text{gt2}) \left(\text{ft2}, 1 \right) \right) \left(18 \delta_{\alpha\delta} \delta_{\beta\gamma} \left(g_2^2 \delta_{il} \delta_{jk} + g_3^2 \delta_{ik} \delta_{jl} \right) + \left(-6g_3^2 - 9g_2^2 + g_1^2 \right) \delta_{\alpha\gamma} \delta_{\beta\delta} \delta_{ik} \right. \right. \right. \\ & \left. \left. + 2 \text{conj} \left(\text{ZU}(\text{gt2}) \left(\text{ft2}, 2 \right) \right) \left(\left(-2g_1^2 + 3g_3^2 \right) \delta_{\alpha\gamma} \delta_{\beta\delta} \delta_{ik} \delta_{jl} - 9 \delta_{\alpha\delta} \delta_{\beta\gamma} \left(-2 Y_{u,jk}^* \delta_{il} \delta_{jk} Y_{u,li} + g_3^2 \delta_{ik} \delta_{jl} \right) \right) \text{ZU}(\text{gt4}) \left(\text{ft4}, 2 \right) \right) \right) \end{aligned} \quad (295)$$



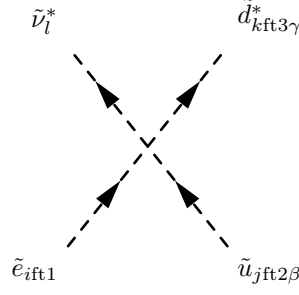
$$-\frac{i}{12}\delta_{\alpha\gamma}\delta_{ik}\delta_{jl}\left(2g_1^2\text{conj}\left(\text{ZD}\left(\text{gt1}\right)\left(\text{ft1},2\right)\right)\text{ZD}\left(\text{gt3}\right)\left(\text{ft3},2\right)+\left(3g_2^2+g_1^2\right)\text{conj}\left(\text{ZD}\left(\text{gt1}\right)\left(\text{ft1},1\right)\right)\text{ZD}\left(\text{gt3}\right)\left(\text{ft3},1\right)\right) \quad (296)$$



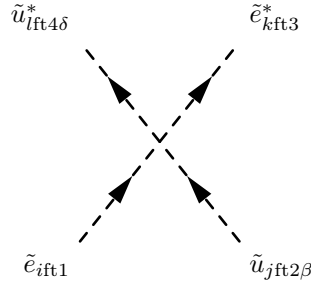
$$-\frac{i}{2}\delta_{\alpha\delta}\delta_{il}\delta_{jk}\left(2Y_{d,il}^*\text{conj}\left(\text{ZD}\left(\text{gt1}\right)\left(\text{ft1},2\right)\right)Y_{e,kj}\text{ZE}\left(\text{gt3}\right)\left(\text{ft3},2\right)+g_2^2\text{conj}\left(\text{ZD}\left(\text{gt1}\right)\left(\text{ft1},1\right)\right)\text{ZE}\left(\text{gt3}\right)\left(\text{ft3},1\right)\right)\text{ZU}\left(\text{gt4}\right)\left(\text{ft4},1\right) \quad (297)$$



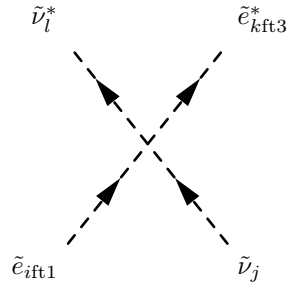
$$\begin{aligned} & \frac{i}{4}\left(-\text{conj}\left(\text{ZE}\left(\text{gt1}\right)\left(\text{ft1},1\right)\right)\left(\left(g_1^2+g_2^2\right)\text{conj}\left(\text{ZE}\left(\text{gt2}\right)\left(\text{ft2},1\right)\right)\left(\delta_{ik}\delta_{jl}+\delta_{il}\delta_{jk}\right)\text{ZE}\left(\text{gt3}\right)\left(\text{ft3},1\right)\text{ZE}\left(\text{gt4}\right)\left(\text{ft4},1\right)\right. \right. \\ & -2\text{conj}\left(\text{ZE}\left(\text{gt2}\right)\left(\text{ft2},2\right)\right)\left(\delta_{ik}\delta_{jl}\left(-2Y_{e,jl}^*Y_{e,ki}\text{ZE}\left(\text{gt3}\right)\left(\text{ft3},2\right)\text{ZE}\left(\text{gt4}\right)\left(\text{ft4},1\right)+g_1^2\text{ZE}\left(\text{gt3}\right)\left(\text{ft3},1\right)\text{ZE}\left(\text{gt4}\right)\left(\text{ft4},2\right)\right)+\delta_{il}\delta_{jk}\left(\right. \right. \\ & +2\text{conj}\left(\text{ZE}\left(\text{gt1}\right)\left(\text{ft1},2\right)\right)\left(-2g_1^2\text{conj}\left(\text{ZE}\left(\text{gt2}\right)\left(\text{ft2},2\right)\right)\left(\delta_{ik}\delta_{jl}+\delta_{il}\delta_{jk}\right)\text{ZE}\left(\text{gt3}\right)\left(\text{ft3},2\right)\text{ZE}\left(\text{gt4}\right)\left(\text{ft4},2\right)\right. \right. \\ & \left. \left. +\text{conj}\left(\text{ZE}\left(\text{gt2}\right)\left(\text{ft2},1\right)\right)\left(\delta_{ik}\delta_{jl}\left(-2Y_{e,ik}^*Y_{e,lj}\text{ZE}\left(\text{gt3}\right)\left(\text{ft3},1\right)\text{ZE}\left(\text{gt4}\right)\left(\text{ft4},2\right)+g_1^2\text{ZE}\left(\text{gt3}\right)\left(\text{ft3},2\right)\text{ZE}\left(\text{gt4}\right)\left(\text{ft4},1\right)\right)+\delta_{il}\delta_{jk}\left(-\right.\right) \right. \end{aligned} \quad (298)$$



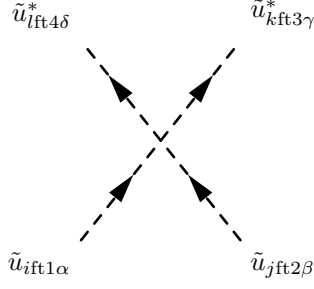
$$-\frac{i}{2} \text{conj}\left(\text{ZU}(\text{gt2})(\text{ft2}, 1)\right) \delta_{\beta\gamma} \delta_{il} \delta_{jk} \left(2Y_{e,il}^* \text{conj}\left(\text{ZE}(\text{gt1})(\text{ft1}, 2)\right) Y_{d,kj} \text{ZD}(\text{gt3})(\text{ft3}, 2) + g_2^2 \text{conj}\left(\text{ZE}(\text{gt1})(\text{ft1}, 1)\right) \text{ZD}(\text{gt3})(\text{ft3}, 2)\right) \quad (299)$$



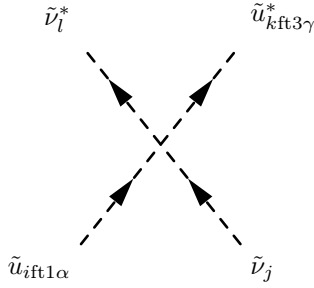
$$\frac{i}{12} \delta_{\beta\delta} \delta_{ik} \delta_{jl} \left(-2g_1^2 \text{conj}\left(\text{ZE}(\text{gt1})(\text{ft1}, 2)\right) \text{ZE}(\text{gt3})(\text{ft3}, 2) \left(-4 \text{conj}\left(\text{ZU}(\text{gt2})(\text{ft2}, 2)\right) \text{ZU}(\text{gt4})(\text{ft4}, 2) + \text{conj}\left(\text{ZU}(\text{gt2})(\text{ft2}, 1)\right) \text{ZU}(\text{gt4})(\text{ft4}, 1)\right) + \text{conj}\left(\text{ZE}(\text{gt1})(\text{ft1}, 1)\right) \text{ZD}(\text{gt3})(\text{ft3}, 2)\right) \quad (300)$$



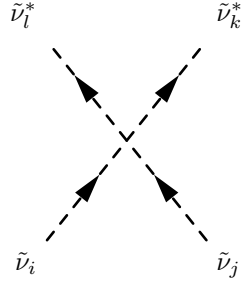
$$\frac{i}{4} \left(2 \text{conj}\left(\text{ZE}(\text{gt1})(\text{ft1}, 2)\right) \left(-2Y_{e,il}^* \delta_{il} \delta_{jk} Y_{e,kj} + g_1^2 \delta_{ik} \delta_{jl}\right) \text{ZE}(\text{gt3})(\text{ft3}, 2) + \text{conj}\left(\text{ZE}(\text{gt1})(\text{ft1}, 1)\right) \left(-2g_2^2 \delta_{il} \delta_{jk} + (-g_1^2 + g_2^2) \delta_{ik} \delta_{jl}\right) \text{ZD}(\text{gt3})(\text{ft3}, 2)\right) \quad (301)$$



$$\begin{aligned}
& \frac{i}{36} \left(-\text{conj}\left(\text{ZU}\left(\text{gt}1\right)\left(\text{ft}1,1\right)\right)\right) \left(\text{conj}\left(\text{ZU}\left(\text{gt}2\right)\left(\text{ft}2,1\right)\right)\right) \left(\delta_{\alpha\delta}\delta_{\beta\gamma}\left(18g_3^2\delta_{ik}\delta_{jl} + \left(-6g_3^2 + 9g_2^2 + g_1^2\right)\delta_{il}\delta_{jk}\right)\right. \\
& + \delta_{\alpha\gamma}\delta_{\beta\delta}\left(18g_3^2\delta_{il}\delta_{jk} + \left(-6g_3^2 + 9g_2^2 + g_1^2\right)\delta_{ik}\delta_{jl}\right)\text{ZU}\left(\text{gt}3\right)\left(\text{ft}3,1\right)\text{ZU}\left(\text{gt}4\right)\left(\text{ft}4,1\right) \\
& + 2\text{conj}\left(\text{ZU}\left(\text{gt}2\right)\left(\text{ft}2,2\right)\right)\left(\delta_{\alpha\gamma}\delta_{\beta\delta}\left(-9g_3^2\delta_{il}\delta_{jk}\text{ZU}\left(\text{gt}3\right)\left(\text{ft}3,2\right)\text{ZU}\left(\text{gt}4\right)\left(\text{ft}4,1\right) + \delta_{ik}\delta_{jl}\left(18Y_{u,jl}^*Y_{u,ki}\text{ZU}\left(\text{gt}3\right)\left(\text{ft}3,2\right)\text{ZU}\left(\text{gt}4\right)\left(\text{ft}4,1\right)\right.\right.\right. \\
& + \delta_{\alpha\delta}\delta_{\beta\gamma}\left(-9g_3^2\delta_{ik}\delta_{jl}\text{ZU}\left(\text{gt}3\right)\left(\text{ft}3,1\right)\text{ZU}\left(\text{gt}4\right)\left(\text{ft}4,2\right) + \delta_{il}\delta_{jk}\left(18Y_{u,jk}^*Y_{u,li}\text{ZU}\left(\text{gt}3\right)\left(\text{ft}3,1\right)\text{ZU}\left(\text{gt}4\right)\left(\text{ft}4,2\right) + \left(-2g_1^2 + 3g_3^2\right)\text{ZU}\left(\text{gt}3\right)\left(\text{ft}3,2\right)\text{ZU}\left(\text{gt}4\right)\left(\text{ft}4,2\right)\right) \\
& + 2\text{conj}\left(\text{ZU}\left(\text{gt}1\right)\left(\text{ft}1,2\right)\right)\left(-\text{conj}\left(\text{ZU}\left(\text{gt}2\right)\left(\text{ft}2,2\right)\right)\right)\left(\delta_{\alpha\delta}\delta_{\beta\gamma}\left(\left(-3g_3^2 + 8g_1^2\right)\delta_{il}\delta_{jk} + 9g_3^2\delta_{ik}\delta_{jl}\right)\right) \\
& + \delta_{\alpha\gamma}\delta_{\beta\delta}\left(\left(-3g_3^2 + 8g_1^2\right)\delta_{ik}\delta_{jl} + 9g_3^2\delta_{il}\delta_{jk}\right)\text{ZU}\left(\text{gt}3\right)\left(\text{ft}3,2\right)\text{ZU}\left(\text{gt}4\right)\left(\text{ft}4,2\right) \\
& + \text{conj}\left(\text{ZU}\left(\text{gt}2\right)\left(\text{ft}2,1\right)\right)\left(\delta_{\alpha\delta}\delta_{\beta\gamma}\left(9g_3^2\delta_{ik}\delta_{jl}\text{ZU}\left(\text{gt}3\right)\left(\text{ft}3,2\right)\text{ZU}\left(\text{gt}4\right)\left(\text{ft}4,1\right) + \delta_{il}\delta_{jk}\left(-18Y_{u,il}^*Y_{u,kj}\text{ZU}\left(\text{gt}3\right)\left(\text{ft}3,2\right)\text{ZU}\left(\text{gt}4\right)\left(\text{ft}4,1\right)\right.\right.\right. \\
& + \delta_{\alpha\gamma}\delta_{\beta\delta}\left(9g_3^2\delta_{il}\delta_{jk}\text{ZU}\left(\text{gt}3\right)\left(\text{ft}3,1\right)\text{ZU}\left(\text{gt}4\right)\left(\text{ft}4,2\right) + \delta_{ik}\delta_{jl}\left(-18Y_{u,ik}^*Y_{u,lj}\text{ZU}\left(\text{gt}3\right)\left(\text{ft}3,1\right)\text{ZU}\left(\text{gt}4\right)\left(\text{ft}4,2\right) + \left(2g_1^2 - 3g_3^2\right)\text{ZU}\left(\text{gt}3\right)\left(\text{ft}3,2\right)\text{ZU}\left(\text{gt}4\right)\left(\text{ft}4,2\right)\right) \\
& \hspace{15em} (302)
\end{aligned}$$

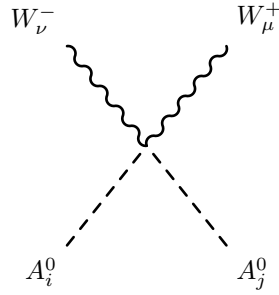


$$\begin{aligned}
& \frac{i}{12} \delta_{\alpha\gamma}\delta_{ik}\delta_{jl} \left(\left(-3g_2^2 + g_1^2 \right) \text{conj}\left(\text{ZU}\left(\text{gt}1\right)\left(\text{ft}1,1\right)\right)\text{ZU}\left(\text{gt}3\right)\left(\text{ft}3,1\right) - 4g_1^2 \text{conj}\left(\text{ZU}\left(\text{gt}1\right)\left(\text{ft}1,2\right)\right)\text{ZU}\left(\text{gt}3\right)\left(\text{ft}3,2\right) \right) \\
& \hspace{15em} (303)
\end{aligned}$$

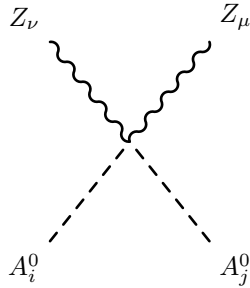


$$-\frac{i}{4}(g_1^2 + g_2^2)(\delta_{ik}\delta_{jl} + \delta_{il}\delta_{jk}) \quad (304)$$

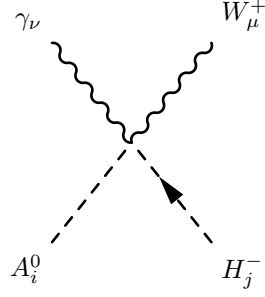
8.8 Two Scalar-Two Vector Boson-Interaction



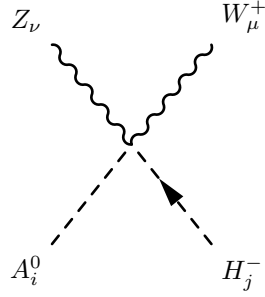
$$\left(\frac{i}{2}g_2^2 Z_{i1}^A Z_{j1}^A + \frac{i}{2}g_2^2 Z_{i2}^A Z_{j2}^A\right)(g_{\mu\nu}) \quad (305)$$



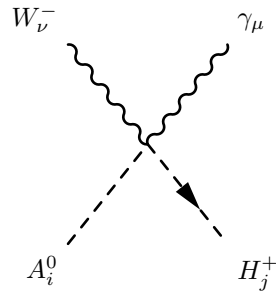
$$\begin{aligned} & \left(+\frac{i}{2}g_2^2 \cos^2 \Theta_W Z_{i1}^A Z_{j1}^A + ig_1 g_2 \cos \Theta_W \sin \Theta_W Z_{i1}^A Z_{j1}^A + \frac{i}{2}g_1^2 \sin^2 \Theta_W Z_{i1}^A Z_{j1}^A \right. \\ & \left. + \frac{i}{2}g_2^2 \cos^2 \Theta_W Z_{i2}^A Z_{j2}^A + ig_1 g_2 \cos \Theta_W \sin \Theta_W Z_{i2}^A Z_{j2}^A + \frac{i}{2}g_1^2 \sin^2 \Theta_W Z_{i2}^A Z_{j2}^A \right)(g_{\mu\nu}) \end{aligned} \quad (306)$$



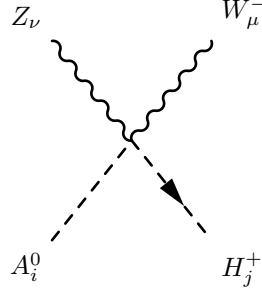
$$\left(-\frac{1}{2}g_1g_2 \cos \Theta_W Z_{i1}^A Z_{j1}^+ - \frac{1}{2}g_1g_2 \cos \Theta_W Z_{i2}^A Z_{j2}^+ \right) (g_{\mu\nu}) \quad (307)$$



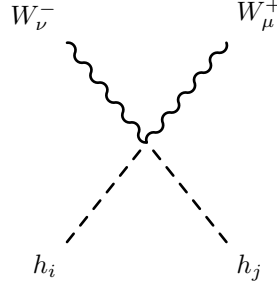
$$\left(\frac{1}{2}g_1g_2 \sin \Theta_W Z_{i1}^A Z_{j1}^+ + \frac{1}{2}g_1g_2 \sin \Theta_W Z_{i2}^A Z_{j2}^+ \right) (g_{\mu\nu}) \quad (308)$$



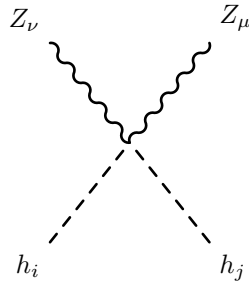
$$\left(\frac{1}{2}g_1g_2 \cos \Theta_W Z_{i1}^A Z_{j1}^+ + \frac{1}{2}g_1g_2 \cos \Theta_W Z_{i2}^A Z_{j2}^+ \right) (g_{\mu\nu}) \quad (309)$$



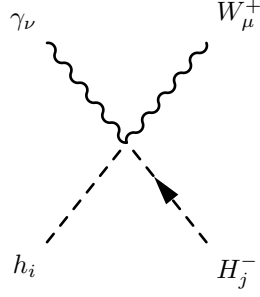
$$\left(-\frac{1}{2}g_1g_2 \sin \Theta_W Z_{i1}^A Z_{j1}^+ - \frac{1}{2}g_1g_2 \sin \Theta_W Z_{i2}^A Z_{j2}^+ \right) (g_{\mu\nu}) \quad (310)$$



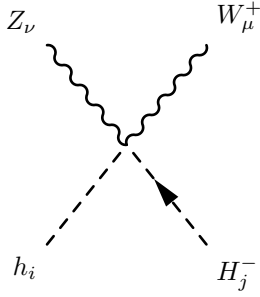
$$\left(\frac{i}{2}g_2^2 Z_{i1}^H Z_{j1}^H + \frac{i}{2}g_2^2 Z_{i2}^H Z_{j2}^H \right) (g_{\mu\nu}) \quad (311)$$



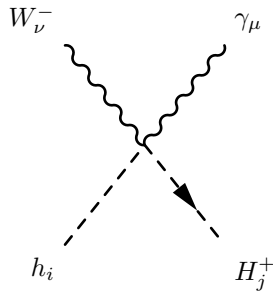
$$\begin{aligned} & \left(+\frac{i}{2}g_2^2 \cos^2 \Theta_W^2 Z_{i1}^H Z_{j1}^H + ig_1g_2 \cos \Theta_W \sin \Theta_W Z_{i1}^H Z_{j1}^H + \frac{i}{2}g_1^2 \sin^2 \Theta_W Z_{i1}^H Z_{j1}^H \right. \\ & \left. + \frac{i}{2}g_2^2 \cos^2 \Theta_W^2 Z_{i2}^H Z_{j2}^H + ig_1g_2 \cos \Theta_W \sin \Theta_W Z_{i2}^H Z_{j2}^H + \frac{i}{2}g_1^2 \sin^2 \Theta_W Z_{i2}^H Z_{j2}^H \right) (g_{\mu\nu}) \quad (312) \end{aligned}$$



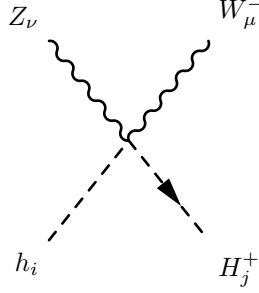
$$\left(-\frac{i}{2}g_1g_2 \cos \Theta_W Z_{i1}^H Z_{j1}^+ + \frac{i}{2}g_1g_2 \cos \Theta_W Z_{i2}^H Z_{j2}^+ \right) (g_{\mu\nu}) \quad (313)$$



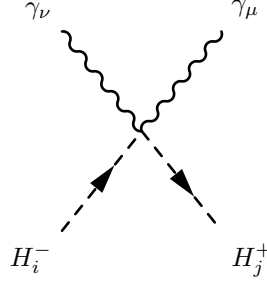
$$\left(\frac{i}{2}g_1g_2 \sin \Theta_W Z_{i1}^H Z_{j1}^+ - \frac{i}{2}g_1g_2 \sin \Theta_W Z_{i2}^H Z_{j2}^+ \right) (g_{\mu\nu}) \quad (314)$$



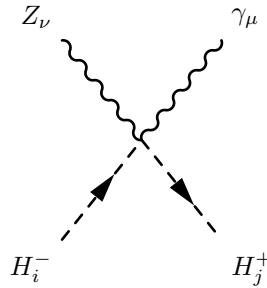
$$\left(-\frac{i}{2}g_1g_2 \cos \Theta_W Z_{i1}^H Z_{j1}^+ + \frac{i}{2}g_1g_2 \cos \Theta_W Z_{i2}^H Z_{j2}^+ \right) (g_{\mu\nu}) \quad (315)$$



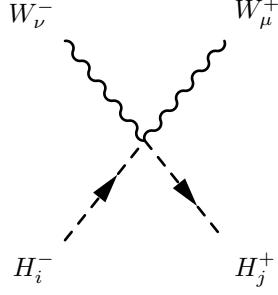
$$\left(\frac{i}{2} g_1 g_2 \sin \Theta_W Z_{i1}^H Z_{j1}^+ - \frac{i}{2} g_1 g_2 \sin \Theta_W Z_{i2}^H Z_{j2}^+ \right) (g_{\mu\nu}) \quad (316)$$



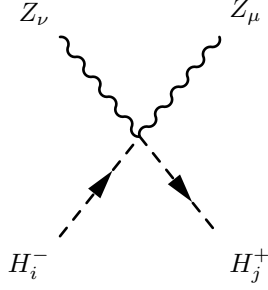
$$\left(+ \frac{i}{2} g_1^2 \cos^2 \Theta_W Z_{i1}^+ Z_{j1}^+ + i g_1 g_2 \cos \Theta_W \sin \Theta_W Z_{i1}^+ Z_{j1}^+ + \frac{i}{2} g_2^2 \sin^2 \Theta_W Z_{i1}^+ Z_{j1}^+ \right. \\ \left. + \frac{i}{2} g_1^2 \cos^2 \Theta_W Z_{i2}^+ Z_{j2}^+ + i g_1 g_2 \cos \Theta_W \sin \Theta_W Z_{i2}^+ Z_{j2}^+ + \frac{i}{2} g_2^2 \sin^2 \Theta_W Z_{i2}^+ Z_{j2}^+ \right) (g_{\mu\nu}) \quad (317)$$



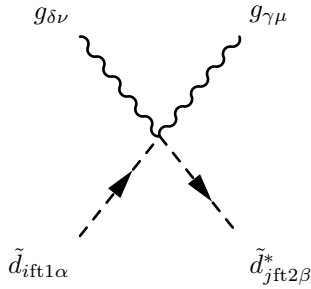
$$\left(+ \frac{i}{2} g_1 g_2 \cos 2\Theta_W Z_{i1}^+ Z_{j1}^+ - \frac{i}{4} g_1^2 \sin 2\Theta_W Z_{i1}^+ Z_{j1}^+ + \frac{i}{4} g_2^2 \sin 2\Theta_W Z_{i1}^+ Z_{j1}^+ \right. \\ \left. + \frac{i}{2} g_1 g_2 \cos 2\Theta_W Z_{i2}^+ Z_{j2}^+ - \frac{i}{4} g_1^2 \sin 2\Theta_W Z_{i2}^+ Z_{j2}^+ + \frac{i}{4} g_2^2 \sin 2\Theta_W Z_{i2}^+ Z_{j2}^+ \right) (g_{\mu\nu}) \quad (318)$$



$$\left(\frac{i}{2}g_2^2 Z_{i1}^+ Z_{j1}^+ + \frac{i}{2}g_2^2 Z_{i2}^+ Z_{j2}^+\right) (g_{\mu\nu}) \quad (319)$$

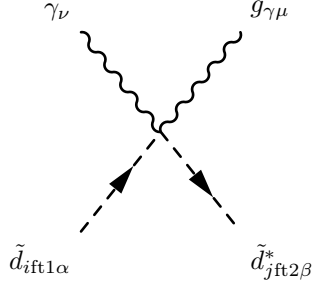


$$\begin{aligned} & \left(+ \frac{i}{2}g_2^2 \cos^2 \Theta_W Z_{i1}^+ Z_{j1}^+ - i g_1 g_2 \cos \Theta_W \sin \Theta_W Z_{i1}^+ Z_{j1}^+ \right. \\ & + \frac{i}{2}g_1^2 \sin^2 \Theta_W Z_{i1}^+ Z_{j1}^+ + \frac{i}{2}g_2^2 \cos^2 \Theta_W Z_{i2}^+ Z_{j2}^+ \\ & \left. - i g_1 g_2 \cos \Theta_W \sin \Theta_W Z_{i2}^+ Z_{j2}^+ + \frac{i}{2}g_1^2 \sin^2 \Theta_W Z_{i2}^+ Z_{j2}^+ \right) (g_{\mu\nu}) \quad (320) \end{aligned}$$

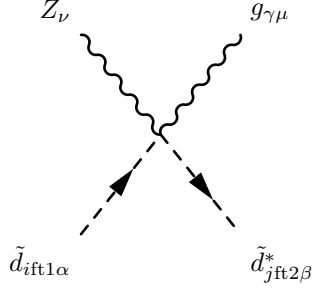


$$\left(+ \frac{i}{4}g_3^2 \text{conj}(\text{ZD}(\text{gt1})(\text{ft1}, 1)) \delta_{ij} \sum_{a=1}^3 \lambda_{a,\alpha}^\gamma \lambda_{\beta,a}^\delta \text{ZD}(\text{gt2})(\text{ft2}, 1) + \frac{i}{4}g_3^2 \text{conj}(\text{ZD}(\text{gt1})(\text{ft1}, 1)) \delta_{ij} \sum_{a=1}^3 \lambda_{\beta,a}^\gamma \lambda_{a,\alpha}^\delta \text{ZD}(\text{gt2})(\text{ft2}, 1) + \frac{i}{4}g_3^2 \text{conj}(\text{ZD}(\text{gt1})(\text{ft1}, 1)) \delta_{ij} \sum_{a=1}^3 \lambda_{a,\alpha}^\gamma \lambda_{\beta,a}^\delta \text{ZD}(\text{gt2})(\text{ft2}, 1) + \frac{i}{4}g_3^2 \text{conj}(\text{ZD}(\text{gt1})(\text{ft1}, 1)) \delta_{ij} \sum_{a=1}^3 \lambda_{\beta,a}^\gamma \lambda_{a,\alpha}^\delta \text{ZD}(\text{gt2})(\text{ft2}, 1) \right)$$

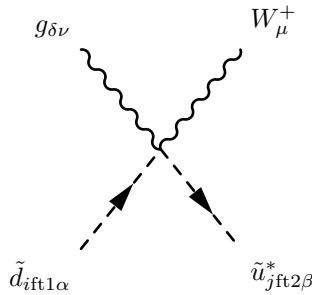
$$+ \frac{i}{4} g_3^2 \text{conj} \left(\text{ZD}(\text{gt1})(\text{ft1}, 2) \right) \delta_{ij} \sum_{a=1}^3 \lambda_{\beta,a}^\gamma \lambda_{a,\alpha}^\delta \text{ZD}(\text{gt2})(\text{ft2}, 2) \left(g_{\mu\nu} \right) \quad (321)$$



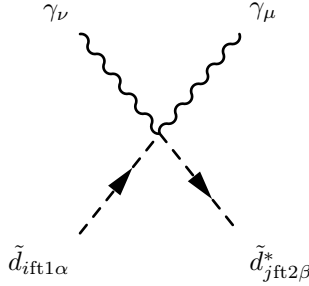
$$\left(+ \frac{i}{6} g_1 g_3 \text{conj} \left(\text{ZD}(\text{gt1})(\text{ft1}, 1) \right) \cos \Theta_W \delta_{ij} \lambda_{\beta,\alpha}^\gamma \text{ZD}(\text{gt2})(\text{ft2}, 1) - \frac{i}{2} g_2 g_3 \text{conj} \left(\text{ZD}(\text{gt1})(\text{ft1}, 1) \right) \delta_{ij} \lambda_{\beta,\alpha}^\gamma \sin \Theta_W \text{ZD}(\text{gt2})(\text{ft2}, 1) \right. \\ \left. - \frac{i}{3} g_1 g_3 \text{conj} \left(\text{ZD}(\text{gt1})(\text{ft1}, 2) \right) \cos \Theta_W \delta_{ij} \lambda_{\beta,\alpha}^\gamma \text{ZD}(\text{gt2})(\text{ft2}, 2) \right) \left(g_{\mu\nu} \right) \quad (322)$$



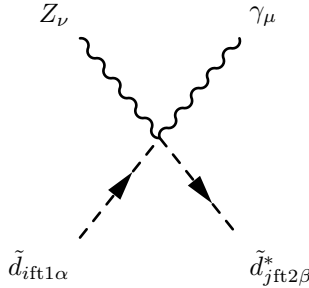
$$\left(- \frac{i}{2} g_2 g_3 \text{conj} \left(\text{ZD}(\text{gt1})(\text{ft1}, 1) \right) \cos \Theta_W \delta_{ij} \lambda_{\beta,\alpha}^\gamma \text{ZD}(\text{gt2})(\text{ft2}, 1) - \frac{i}{6} g_1 g_3 \text{conj} \left(\text{ZD}(\text{gt1})(\text{ft1}, 1) \right) \delta_{ij} \lambda_{\beta,\alpha}^\gamma \sin \Theta_W \text{ZD}(\text{gt2})(\text{ft2}, 1) \right. \\ \left. + \frac{i}{3} g_1 g_3 \text{conj} \left(\text{ZD}(\text{gt1})(\text{ft1}, 2) \right) \delta_{ij} \lambda_{\beta,\alpha}^\gamma \sin \Theta_W \text{ZD}(\text{gt2})(\text{ft2}, 2) \right) \left(g_{\mu\nu} \right) \quad (323)$$



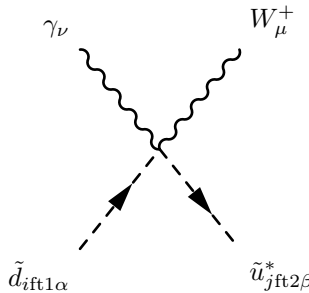
$$i \frac{1}{\sqrt{2}} g_2 g_3 \text{conj} \left(\text{ZD}(\text{gt1}) (\text{ft1}, 1) \right) \delta_{ij} \lambda_{\beta, \alpha}^{\delta} \text{ZU}(\text{gt2}) (\text{ft2}, 1) (g_{\mu\nu}) \quad (324)$$



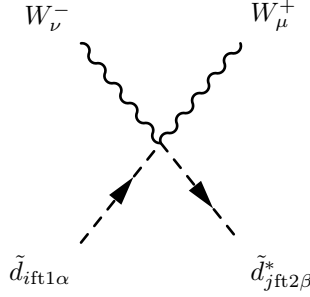
$$\begin{aligned} & \left(+ \frac{i}{18} g_1^2 \text{conj} \left(\text{ZD}(\text{gt1}) (\text{ft1}, 1) \right) \cos^2 \Theta_W \delta_{\alpha\beta} \delta_{ij} \text{ZD}(\text{gt2}) (\text{ft2}, 1) - \frac{i}{3} g_1 g_2 \text{conj} \left(\text{ZD}(\text{gt1}) (\text{ft1}, 1) \right) \cos \Theta_W \delta_{\alpha\beta} \delta_{ij} \sin \Theta_W \text{ZD}(\text{gt2}) (\text{ft2}, 1) \right. \\ & \left. + \frac{i}{2} g_2^2 \text{conj} \left(\text{ZD}(\text{gt1}) (\text{ft1}, 1) \right) \delta_{\alpha\beta} \delta_{ij} \sin^2 \Theta_W \text{ZD}(\text{gt2}) (\text{ft2}, 1) + \frac{2i}{9} g_1^2 \text{conj} \left(\text{ZD}(\text{gt1}) (\text{ft1}, 2) \right) \cos^2 \Theta_W \delta_{\alpha\beta} \delta_{ij} \text{ZD}(\text{gt2}) (\text{ft2}, 2) \right) (g_{\mu\nu}) \end{aligned} \quad (325)$$



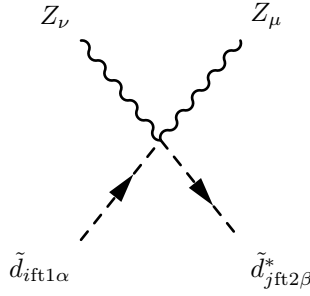
$$\begin{aligned} & \left(- \frac{i}{6} g_1 g_2 \text{conj} \left(\text{ZD}(\text{gt1}) (\text{ft1}, 1) \right) \cos 2\Theta_W \delta_{\alpha\beta} \delta_{ij} \text{ZD}(\text{gt2}) (\text{ft2}, 1) - \frac{i}{36} g_1^2 \text{conj} \left(\text{ZD}(\text{gt1}) (\text{ft1}, 1) \right) \delta_{\alpha\beta} \delta_{ij} \sin 2\Theta_W \text{ZD}(\text{gt2}) (\text{ft2}, 1) \right. \\ & \left. + \frac{i}{4} g_2^2 \text{conj} \left(\text{ZD}(\text{gt1}) (\text{ft1}, 1) \right) \delta_{\alpha\beta} \delta_{ij} \sin 2\Theta_W \text{ZD}(\text{gt2}) (\text{ft2}, 1) - \frac{i}{9} g_1^2 \text{conj} \left(\text{ZD}(\text{gt1}) (\text{ft1}, 2) \right) \delta_{\alpha\beta} \delta_{ij} \sin 2\Theta_W \text{ZD}(\text{gt2}) (\text{ft2}, 2) \right) (g_{\mu\nu}) \end{aligned} \quad (326)$$



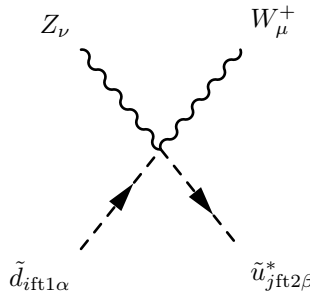
$$\frac{i}{3} \frac{1}{\sqrt{2}} g_1 g_2 \text{conj} \left(\text{ZD}(\text{gt1}) \left(\text{ft1}, 1 \right) \right) \cos \Theta_W \delta_{\alpha\beta} \delta_{ij} \text{ZU}(\text{gt2}) \left(\text{ft2}, 1 \right) \left(g_{\mu\nu} \right) \quad (327)$$



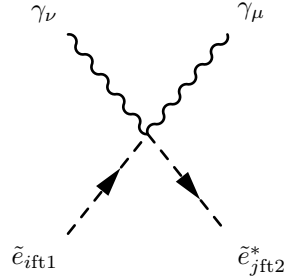
$$\frac{i}{2} g_2^2 \text{conj} \left(\text{ZD}(\text{gt1}) \left(\text{ft1}, 1 \right) \right) \delta_{\alpha\beta} \delta_{ij} \text{ZD}(\text{gt2}) \left(\text{ft2}, 1 \right) \left(g_{\mu\nu} \right) \quad (328)$$



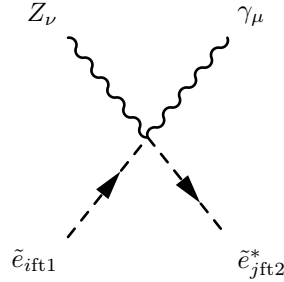
$$\begin{aligned} & \left(+ \frac{i}{2} g_2^2 \text{conj} \left(\text{ZD}(\text{gt1}) \left(\text{ft1}, 1 \right) \right) \cos \Theta_W^2 \delta_{\alpha\beta} \delta_{ij} \text{ZD}(\text{gt2}) \left(\text{ft2}, 1 \right) + \frac{i}{3} g_1 g_2 \text{conj} \left(\text{ZD}(\text{gt1}) \left(\text{ft1}, 1 \right) \right) \cos \Theta_W \delta_{\alpha\beta} \delta_{ij} \sin \Theta_W \text{ZD}(\text{gt2}) \left(\text{ft2}, 1 \right) \right. \\ & \left. + \frac{i}{18} g_1^2 \text{conj} \left(\text{ZD}(\text{gt1}) \left(\text{ft1}, 1 \right) \right) \delta_{\alpha\beta} \delta_{ij} \sin \Theta_W^2 \text{ZD}(\text{gt2}) \left(\text{ft2}, 1 \right) + \frac{2i}{9} g_1^2 \text{conj} \left(\text{ZD}(\text{gt1}) \left(\text{ft1}, 2 \right) \right) \delta_{\alpha\beta} \delta_{ij} \sin \Theta_W^2 \text{ZD}(\text{gt2}) \left(\text{ft2}, 2 \right) \right) \left(g_{\mu\nu} \right) \end{aligned} \quad (329)$$



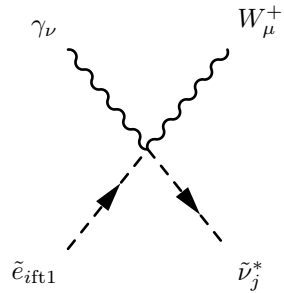
$$- \frac{i}{3} \frac{1}{\sqrt{2}} g_1 g_2 \text{conj} \left(\text{ZD}(\text{gt1}) (\text{ft1}, 1) \right) \delta_{\alpha\beta} \delta_{ij} \sin \Theta_W \text{ZU}(\text{gt2}) (\text{ft2}, 1) (g_{\mu\nu}) \quad (330)$$



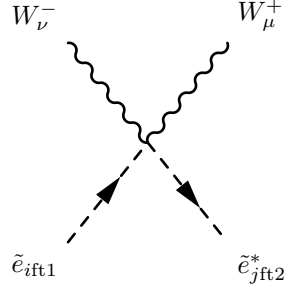
$$\begin{aligned} & \left(+ \frac{i}{2} g_1^2 \text{conj} \left(\text{ZE}(\text{gt1}) (\text{ft1}, 1) \right) \cos \Theta_W^2 \delta_{ij} \text{ZE}(\text{gt2}) (\text{ft2}, 1) + i g_1 g_2 \text{conj} \left(\text{ZE}(\text{gt1}) (\text{ft1}, 1) \right) \cos \Theta_W \delta_{ij} \sin \Theta_W \text{ZE}(\text{gt2}) (\text{ft2}, 1) \right. \\ & \left. + \frac{i}{2} g_2^2 \text{conj} \left(\text{ZE}(\text{gt1}) (\text{ft1}, 1) \right) \delta_{ij} \sin \Theta_W^2 \text{ZE}(\text{gt2}) (\text{ft2}, 1) + 2i g_1^2 \text{conj} \left(\text{ZE}(\text{gt1}) (\text{ft1}, 2) \right) \cos \Theta_W^2 \delta_{ij} \text{ZE}(\text{gt2}) (\text{ft2}, 2) \right) (g_{\mu\nu}) \end{aligned} \quad (331)$$



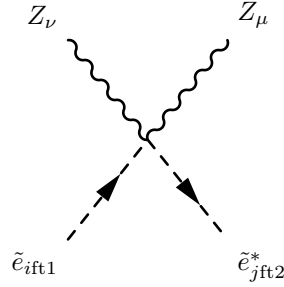
$$\begin{aligned} & \left(+ \frac{i}{2} g_1 g_2 \text{conj} \left(\text{ZE}(\text{gt1}) (\text{ft1}, 1) \right) \cos 2\Theta_W \delta_{ij} \text{ZE}(\text{gt2}) (\text{ft2}, 1) - \frac{i}{4} g_1^2 \text{conj} \left(\text{ZE}(\text{gt1}) (\text{ft1}, 1) \right) \delta_{ij} \sin 2\Theta_W \text{ZE}(\text{gt2}) (\text{ft2}, 1) + \frac{i}{4} g_2^2 \text{conj} \right. \\ & \left. - i g_1^2 \text{conj} \left(\text{ZE}(\text{gt1}) (\text{ft1}, 2) \right) \delta_{ij} \sin 2\Theta_W \text{ZE}(\text{gt2}) (\text{ft2}, 2) \right) (g_{\mu\nu}) \end{aligned} \quad (332)$$



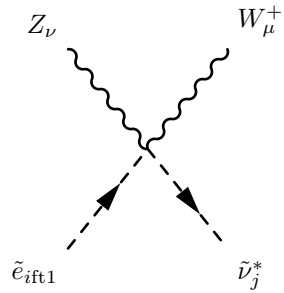
$$-i\frac{1}{\sqrt{2}}g_1g_2\text{conj}\left(\text{ZE}\left(\text{gt1}\right)\left(\text{ft1},1\right)\right)\cos\Theta_W\delta_{ij}\left(g_{\mu\nu}\right) \quad (333)$$



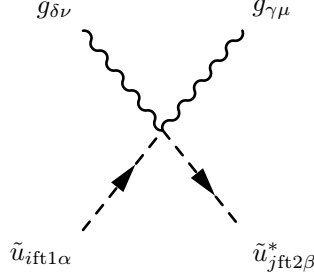
$$\frac{i}{2}g_2^2\text{conj}\left(\text{ZE}\left(\text{gt1}\right)\left(\text{ft1},1\right)\right)\delta_{ij}\text{ZE}\left(\text{gt2}\right)\left(\text{ft2},1\right)\left(g_{\mu\nu}\right) \quad (334)$$



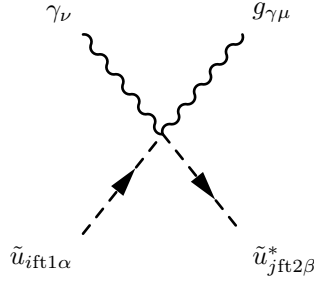
$$\begin{aligned} &\left(+\frac{i}{2}g_2^2\text{conj}\left(\text{ZE}\left(\text{gt1}\right)\left(\text{ft1},1\right)\right)\cos\Theta_W^2\delta_{ij}\text{ZE}\left(\text{gt2}\right)\left(\text{ft2},1\right)-ig_1g_2\text{conj}\left(\text{ZE}\left(\text{gt1}\right)\left(\text{ft1},1\right)\right)\cos\Theta_W\delta_{ij}\sin\Theta_W\text{ZE}\left(\text{gt2}\right)\left(\text{ft2},1\right)\right. \\ &\left.+\frac{i}{2}g_1^2\text{conj}\left(\text{ZE}\left(\text{gt1}\right)\left(\text{ft1},1\right)\right)\delta_{ij}\sin\Theta_W^2\text{ZE}\left(\text{gt2}\right)\left(\text{ft2},1\right)+2ig_1^2\text{conj}\left(\text{ZE}\left(\text{gt1}\right)\left(\text{ft1},2\right)\right)\delta_{ij}\sin\Theta_W^2\text{ZE}\left(\text{gt2}\right)\left(\text{ft2},2\right)\right)\left(g_{\mu\nu}\right) \end{aligned} \quad (335)$$



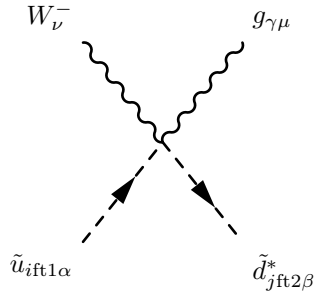
$$i \frac{1}{\sqrt{2}} g_1 g_2 \text{conj} \left(\text{ZE}(\text{gt1}) (\text{ft1}, 1) \right) \delta_{ij} \sin \Theta_W (g_{\mu\nu}) \quad (336)$$



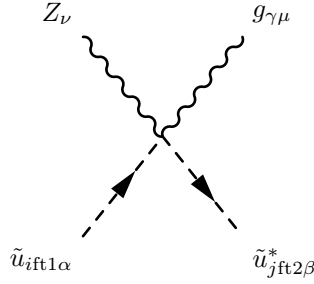
$$\begin{aligned} & \left(+ \frac{i}{4} g_3^2 \text{conj} \left(\text{ZU}(\text{gt1}) (\text{ft1}, 1) \right) \right) \delta_{ij} \sum_{a=1}^3 \lambda_{a,\alpha}^\gamma \lambda_{\beta,a}^\delta \text{ZU}(\text{gt2}) (\text{ft2}, 1) + \frac{i}{4} g_3^2 \text{conj} \left(\text{ZU}(\text{gt1}) (\text{ft1}, 1) \right) \delta_{ij} \sum_{a=1}^3 \lambda_{\beta,a}^\gamma \lambda_{a,\alpha}^\delta \text{ZU}(\text{gt2}) (\text{ft2}, 1) + \frac{i}{4} g_3^2 \text{conj} \left(\text{ZU}(\text{gt1}) (\text{ft1}, 2) \right) \delta_{ij} \sum_{a=1}^3 \lambda_{\beta,a}^\gamma \lambda_{a,\alpha}^\delta \text{ZU}(\text{gt2}) (\text{ft2}, 2) \left(g_{\mu\nu} \right) \end{aligned} \quad (337)$$



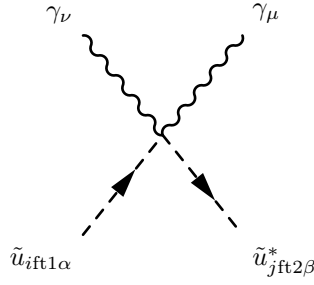
$$\begin{aligned} & \left(+ \frac{i}{6} g_1 g_3 \text{conj} \left(\text{ZU}(\text{gt1}) (\text{ft1}, 1) \right) \right) \cos \Theta_W \delta_{ij} \lambda_{\beta,\alpha}^\gamma \text{ZU}(\text{gt2}) (\text{ft2}, 1) + \frac{i}{2} g_2 g_3 \text{conj} \left(\text{ZU}(\text{gt1}) (\text{ft1}, 1) \right) \delta_{ij} \lambda_{\beta,\alpha}^\gamma \sin \Theta_W \text{ZU}(\text{gt2}) (\text{ft2}, 1) \\ & + \frac{2i}{3} g_1 g_3 \text{conj} \left(\text{ZU}(\text{gt1}) (\text{ft1}, 2) \right) \cos \Theta_W \delta_{ij} \lambda_{\beta,\alpha}^\gamma \text{ZU}(\text{gt2}) (\text{ft2}, 2) \left(g_{\mu\nu} \right) \end{aligned} \quad (338)$$



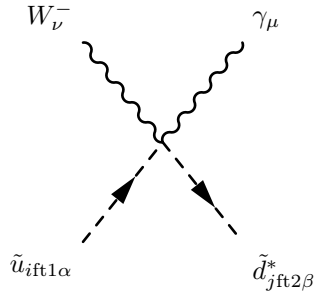
$$i\frac{1}{\sqrt{2}}g_2g_3\text{conj}\left(\text{ZU}\left(\text{gt1}\right)\left(\text{ft1},1\right)\right)\delta_{ij}\lambda_{\beta,\alpha}^\gamma\text{ZD}\left(\text{gt2}\right)\left(\text{ft2},1\right)\left(g_{\mu\nu}\right) \quad (339)$$



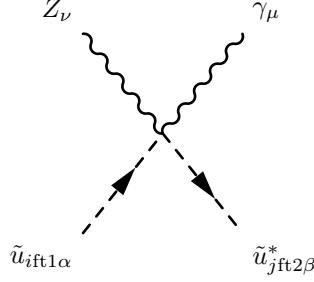
$$\begin{aligned} & \left(+\frac{i}{2}g_2g_3\text{conj}\left(\text{ZU}\left(\text{gt1}\right)\left(\text{ft1},1\right)\right)\cos\Theta_W\delta_{ij}\lambda_{\beta,\alpha}^\gamma\text{ZU}\left(\text{gt2}\right)\left(\text{ft2},1\right) -\frac{i}{6}g_1g_3\text{conj}\left(\text{ZU}\left(\text{gt1}\right)\left(\text{ft1},1\right)\right)\delta_{ij}\lambda_{\beta,\alpha}^\gamma\sin\Theta_W\text{ZU}\left(\text{gt2}\right)\left(\text{ft2},1\right) \right. \\ & \left. -\frac{2i}{3}g_1g_3\text{conj}\left(\text{ZU}\left(\text{gt1}\right)\left(\text{ft1},2\right)\right)\delta_{ij}\lambda_{\beta,\alpha}^\gamma\sin\Theta_W\text{ZU}\left(\text{gt2}\right)\left(\text{ft2},2\right)\right)\left(g_{\mu\nu}\right) \end{aligned} \quad (340)$$



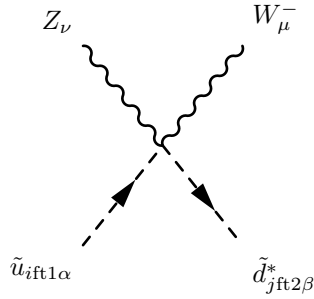
$$\begin{aligned} & \left(+\frac{i}{18}g_1^2\text{conj}\left(\text{ZU}\left(\text{gt1}\right)\left(\text{ft1},1\right)\right)\cos\Theta_W^2\delta_{\alpha\beta}\delta_{ij}\text{ZU}\left(\text{gt2}\right)\left(\text{ft2},1\right) +\frac{i}{3}g_1g_2\text{conj}\left(\text{ZU}\left(\text{gt1}\right)\left(\text{ft1},1\right)\right)\cos\Theta_W\delta_{\alpha\beta}\delta_{ij}\sin\Theta_W\text{ZU}\left(\text{gt2}\right)\left(\text{ft2},1\right) \right. \\ & \left. +\frac{i}{2}g_2^2\text{conj}\left(\text{ZU}\left(\text{gt1}\right)\left(\text{ft1},1\right)\right)\delta_{\alpha\beta}\delta_{ij}\sin\Theta_W^2\text{ZU}\left(\text{gt2}\right)\left(\text{ft2},1\right) +\frac{8i}{9}g_1^2\text{conj}\left(\text{ZU}\left(\text{gt1}\right)\left(\text{ft1},2\right)\right)\cos\Theta_W^2\delta_{\alpha\beta}\delta_{ij}\text{ZU}\left(\text{gt2}\right)\left(\text{ft2},2\right)\right)\left(g_{\mu\nu}\right) \end{aligned} \quad (341)$$



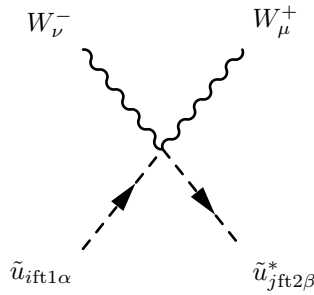
$$\frac{i}{3} \frac{1}{\sqrt{2}} g_1 g_2 \text{conj} \left(\text{ZU}(\text{gt1}) (\text{ft1}, 1) \right) \cos \Theta_W \delta_{\alpha\beta} \delta_{ij} \text{ZD}(\text{gt2}) (\text{ft2}, 1) (g_{\mu\nu}) \quad (342)$$



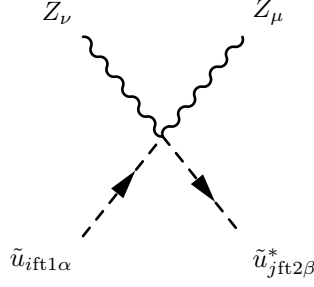
$$\begin{aligned} & \left(+ \frac{i}{6} g_1 g_2 \text{conj} \left(\text{ZU}(\text{gt1}) (\text{ft1}, 1) \right) \cos 2\Theta_W \delta_{\alpha\beta} \delta_{ij} \text{ZU}(\text{gt2}) (\text{ft2}, 1) - \frac{i}{36} g_1^2 \text{conj} \left(\text{ZU}(\text{gt1}) (\text{ft1}, 1) \right) \delta_{\alpha\beta} \delta_{ij} \sin 2\Theta_W \text{ZU}(\text{gt2}) (\text{ft2}, 1) \right. \\ & \left. + \frac{i}{4} g_2^2 \text{conj} \left(\text{ZU}(\text{gt1}) (\text{ft1}, 1) \right) \delta_{\alpha\beta} \delta_{ij} \sin 2\Theta_W \text{ZU}(\text{gt2}) (\text{ft2}, 1) - \frac{4i}{9} g_1^2 \text{conj} \left(\text{ZU}(\text{gt1}) (\text{ft1}, 2) \right) \delta_{\alpha\beta} \delta_{ij} \sin 2\Theta_W \text{ZU}(\text{gt2}) (\text{ft2}, 2) \right) (g_{\mu\nu}) \end{aligned} \quad (343)$$



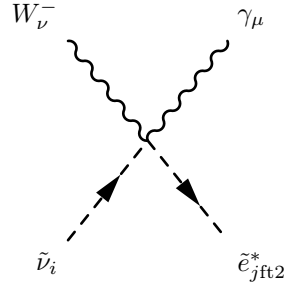
$$- \frac{i}{3} \frac{1}{\sqrt{2}} g_1 g_2 \text{conj} \left(\text{ZU}(\text{gt1}) (\text{ft1}, 1) \right) \delta_{\alpha\beta} \delta_{ij} \sin \Theta_W \text{ZD}(\text{gt2}) (\text{ft2}, 1) (g_{\mu\nu}) \quad (344)$$



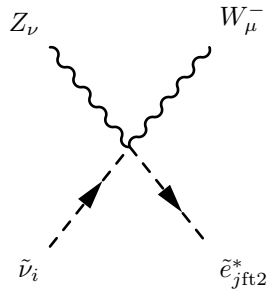
$$\frac{i}{2}g_2^2\text{conj}\left(\text{ZU}\left(\text{gt1}\right)\left(\text{ft1},1\right)\right)\delta_{\alpha\beta}\delta_{ij}\text{ZU}\left(\text{gt2}\right)\left(\text{ft2},1\right)\left(g_{\mu\nu}\right) \quad (345)$$



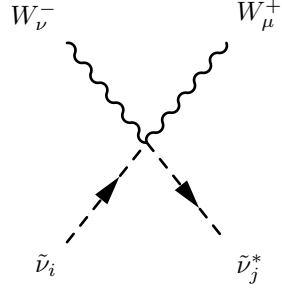
$$\begin{aligned} & \left(+ \frac{i}{2}g_2^2\text{conj}\left(\text{ZU}\left(\text{gt1}\right)\left(\text{ft1},1\right)\right)\cos\Theta_W^2\delta_{\alpha\beta}\delta_{ij}\text{ZU}\left(\text{gt2}\right)\left(\text{ft2},1\right) - \frac{i}{3}g_1g_2\text{conj}\left(\text{ZU}\left(\text{gt1}\right)\left(\text{ft1},1\right)\right)\cos\Theta_W\delta_{\alpha\beta}\delta_{ij}\sin\Theta_W\text{ZU}\left(\text{gt2}\right)\left(\text{ft2},1\right) \right. \\ & \left. + \frac{i}{18}g_1^2\text{conj}\left(\text{ZU}\left(\text{gt1}\right)\left(\text{ft1},1\right)\right)\delta_{\alpha\beta}\delta_{ij}\sin\Theta_W^2\text{ZU}\left(\text{gt2}\right)\left(\text{ft2},1\right) + \frac{8i}{9}g_1^2\text{conj}\left(\text{ZU}\left(\text{gt1}\right)\left(\text{ft1},2\right)\right)\delta_{\alpha\beta}\delta_{ij}\sin\Theta_W^2\text{ZU}\left(\text{gt2}\right)\left(\text{ft2},2\right)\right)\left(g_{\mu\nu}\right) \end{aligned} \quad (346)$$



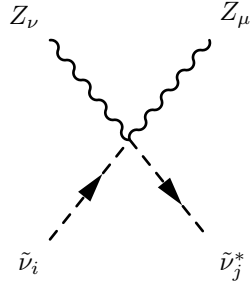
$$-i\frac{1}{\sqrt{2}}g_1g_2\cos\Theta_W\delta_{ij}\text{ZE}\left(\text{gt2}\right)\left(\text{ft2},1\right)\left(g_{\mu\nu}\right) \quad (347)$$



$$i \frac{1}{\sqrt{2}} g_1 g_2 \delta_{ij} \sin \Theta_W \text{ZE}(\text{gt}2) (\text{ft}2, 1) (g_{\mu\nu}) \quad (348)$$

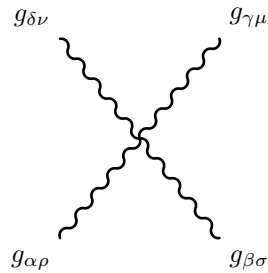


$$\frac{i}{2} g_2^2 \delta_{ij} (g_{\mu\nu}) \quad (349)$$



$$\left(\frac{i}{2} g_1^2 \delta_{ij} \sin^2 \Theta_W + \frac{i}{2} g_2^2 \cos^2 \Theta_W \delta_{ij} + i g_1 g_2 \cos \Theta_W \delta_{ij} \sin \Theta_W \right) (g_{\mu\nu}) \quad (350)$$

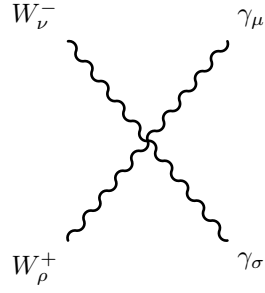
8.9 Four Vector Boson-Interaction



$$ig_3^2 \left(- \sum_{a=1}^8 f_{\alpha,\delta,a} f_{\beta,\gamma,a} - \sum_{a=1}^8 f_{\alpha,\gamma,a} f_{\beta,\delta,a} \right) (g_{\rho\sigma} g_{\mu\nu}) \quad (351)$$

$$+ ig_3^2 \left(- \sum_{a=1}^8 f_{\alpha,\beta,a} f_{\gamma,\delta,a} + \sum_{a=1}^8 f_{\alpha,\delta,a} f_{\beta,\gamma,a} \right) (g_{\rho\mu} g_{\sigma\nu}) \quad (352)$$

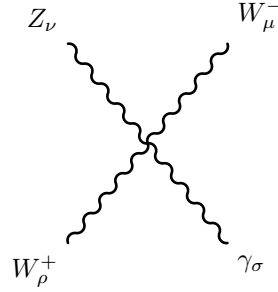
$$+ ig_3^2 \left(\sum_{a=1}^8 f_{\alpha,\gamma,a} f_{\beta,\delta,a} + \sum_{a=1}^8 f_{\alpha,\beta,a} f_{\gamma,\delta,a} \right) (g_{\rho\nu} g_{\sigma\mu}) \quad (353)$$



$$ig_2^2 \sin^2 \Theta_W (g_{\rho\sigma} g_{\mu\nu}) \quad (354)$$

$$+ ig_2^2 \sin^2 \Theta_W (g_{\rho\mu} g_{\sigma\nu}) \quad (355)$$

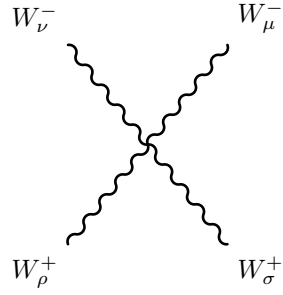
$$+ -2ig_2^2 \sin^2 \Theta_W (g_{\rho\nu} g_{\sigma\mu}) \quad (356)$$



$$\frac{i}{2} g_2^2 \sin 2\Theta_W (g_{\rho\sigma} g_{\mu\nu}) \quad (357)$$

$$+ -ig_2^2 \sin 2\Theta_W (g_{\rho\mu} g_{\sigma\nu}) \quad (358)$$

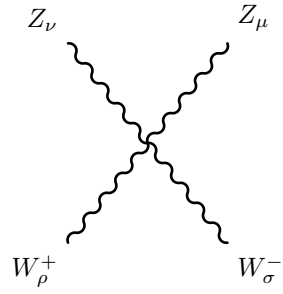
$$+ \frac{i}{2} g_2^2 \sin 2\Theta_W (g_{\rho\nu} g_{\sigma\mu}) \quad (359)$$



$$2ig_2^2(g_{\rho\sigma}g_{\mu\nu}) \quad (360)$$

$$+ -ig_2^2(g_{\rho\mu}g_{\sigma\nu}) \quad (361)$$

$$+ -ig_2^2(g_{\rho\nu}g_{\sigma\mu}) \quad (362)$$

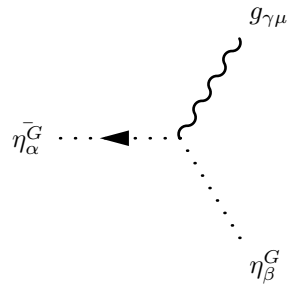


$$- 2ig_2^2 \cos^2 \Theta_W^2 (g_{\rho\sigma}g_{\mu\nu}) \quad (363)$$

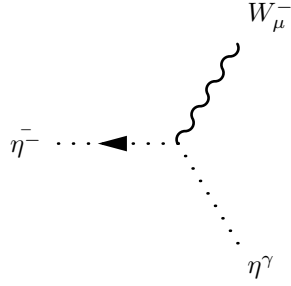
$$+ ig_2^2 \cos^2 \Theta_W^2 (g_{\rho\mu}g_{\sigma\nu}) \quad (364)$$

$$+ ig_2^2 \cos^2 \Theta_W^2 (g_{\rho\nu}g_{\sigma\mu}) \quad (365)$$

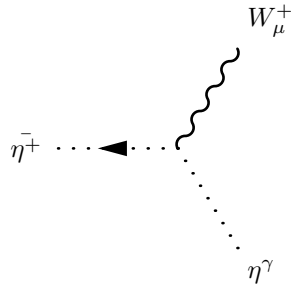
8.10 Two Ghosts-One Vector Boson-Interaction



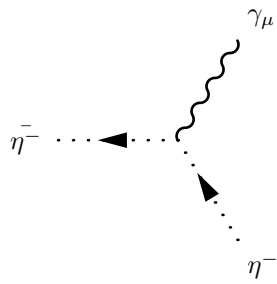
$$g_3 f_{\alpha,\beta,\gamma} \left(p_\mu^{\eta_\beta^G} \right) \quad (366)$$



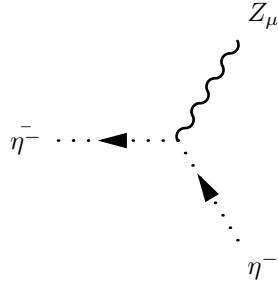
$$i g_2 \sin \Theta_W \left(p_\mu^{\eta^\gamma} \right) \quad (367)$$



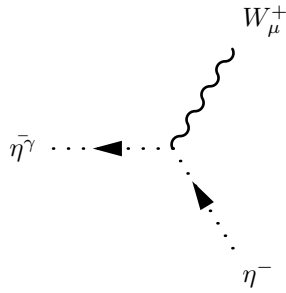
$$- i g_2 \sin \Theta_W \left(p_\mu^{\eta^\gamma} \right) \quad (368)$$



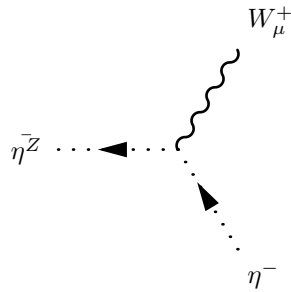
$$- i g_2 \sin \Theta_W \left(p_\mu^{\eta^-} \right) \quad (369)$$



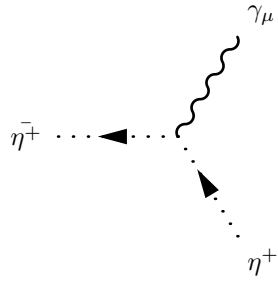
$$-ig_2 \cos \Theta_W (p_\mu^{\eta^-}) \quad (370)$$



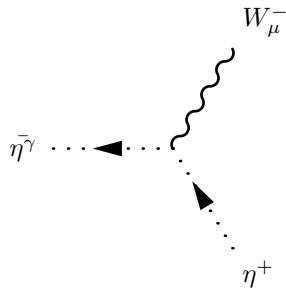
$$ig_2 \sin \Theta_W (p_\mu^{\eta^-}) \quad (371)$$



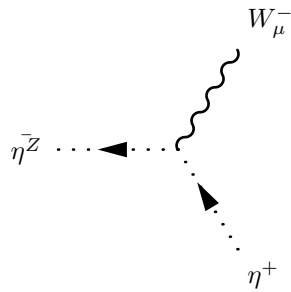
$$ig_2 \cos \Theta_W (p_\mu^{\eta^-}) \quad (372)$$



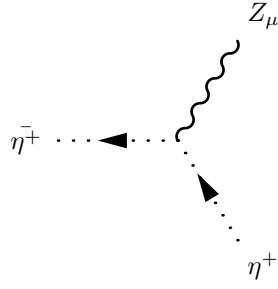
$$ig_2 \sin \Theta_W (p_\mu^{\eta^+}) \quad (373)$$



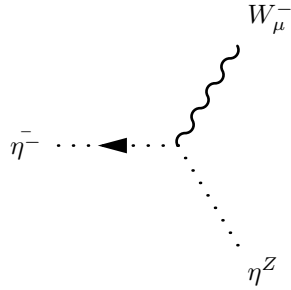
$$-ig_2 \sin \Theta_W (p_\mu^{\eta^+}) \quad (374)$$



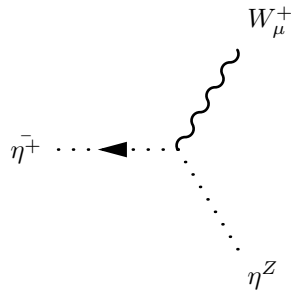
$$-ig_2 \cos \Theta_W (p_\mu^{\eta^+}) \quad (375)$$



$$ig_2 \cos \Theta_W (p_\mu^{\eta^+}) \quad (376)$$

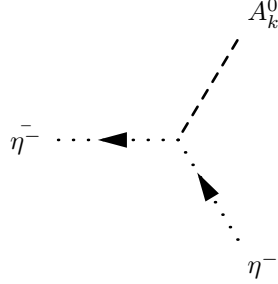


$$ig_2 \cos \Theta_W (p_\mu^{\eta^Z}) \quad (377)$$

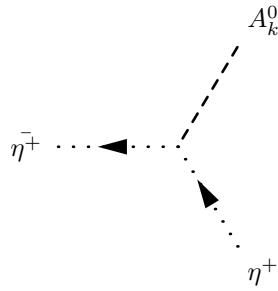


$$-ig_2 \cos \Theta_W (p_\mu^{\eta^Z}) \quad (378)$$

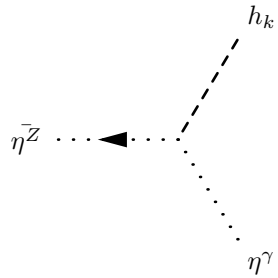
8.11 Two Ghosts-One Scalar-Interaction



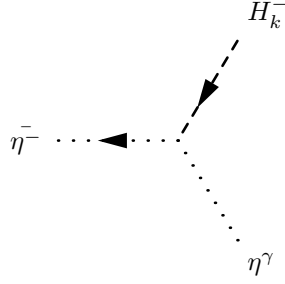
$$\frac{1}{4}g_2^2\xi_{W^-}\left(v_d Z_{k1}^A - v_u Z_{k2}^A\right) \quad (379)$$



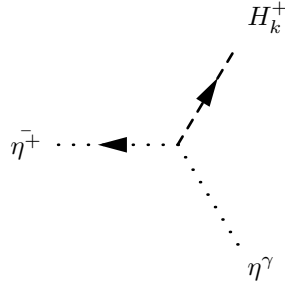
$$-\frac{1}{4}g_2^2\xi_{W^-}\left(v_d Z_{k1}^A - v_u Z_{k2}^A\right) \quad (380)$$



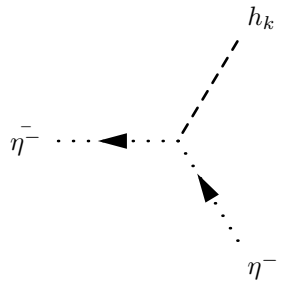
$$\frac{i}{8}\xi_Z\left(2g_1g_2\cos 2\Theta_W + \left(-g_2^2 + g_1^2\right)\sin 2\Theta_W\right)\left(v_d Z_{k1}^H + v_u Z_{k2}^H\right) \quad (381)$$



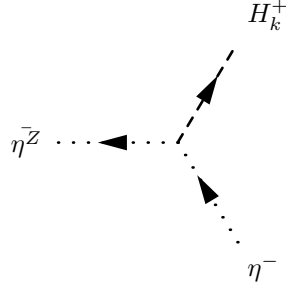
$$\frac{i}{4} g_2 \xi_{W^-} \left(g_1 \cos \Theta_W + g_2 \sin \Theta_W \right) \left(v_d Z_{k1}^+ - v_u Z_{k2}^+ \right) \quad (382)$$



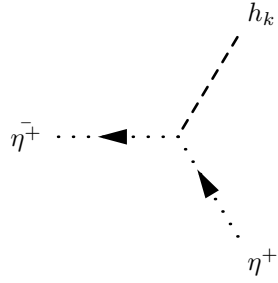
$$\frac{i}{4} g_2 \xi_{W^-} \left(g_1 \cos \Theta_W + g_2 \sin \Theta_W \right) \left(v_d Z_{k1}^+ - v_u Z_{k2}^+ \right) \quad (383)$$



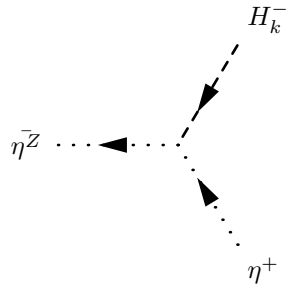
$$-\frac{i}{4} g_2^2 \xi_{W^-} \left(v_d Z_{k1}^H + v_u Z_{k2}^H \right) \quad (384)$$



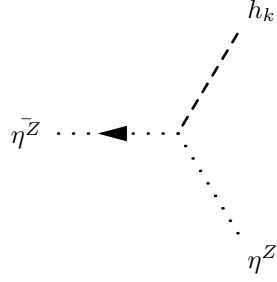
$$-\frac{i}{4}g_2\xi_Z(g_1\sin\Theta_W+g_2\cos\Theta_W)(v_dZ_{k1}^+-v_uZ_{k2}^+) \quad (385)$$



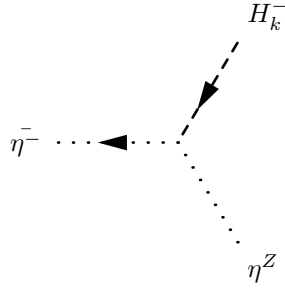
$$-\frac{i}{4}g_2^2\xi_{W^-}(v_dZ_{k1}^H+v_uZ_{k2}^H) \quad (386)$$



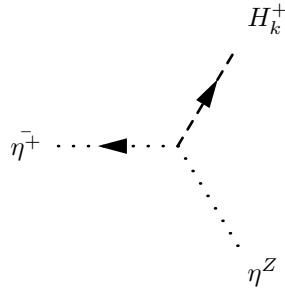
$$-\frac{i}{4}g_2\xi_Z(g_1\sin\Theta_W+g_2\cos\Theta_W)(v_dZ_{k1}^+-v_uZ_{k2}^+) \quad (387)$$



$$-\frac{i}{4}\xi_Z(g_1 \sin \Theta_W + g_2 \cos \Theta_W)^2(v_d Z_{k1}^H + v_u Z_{k2}^H) \quad (388)$$



$$\frac{i}{4}g_2\xi_{W^-}(-g_1 \sin \Theta_W + g_2 \cos \Theta_W)(v_d Z_{k1}^+ - v_u Z_{k2}^+) \quad (389)$$



$$\frac{i}{4}g_2\xi_{W^-}(-g_1 \sin \Theta_W + g_2 \cos \Theta_W)(v_d Z_{k1}^+ - v_u Z_{k2}^+) \quad (390)$$

9 Clebsch-Gordan Coefficients